

Lesson 1

Introduction

Operating systems design
Degree in Computer Science and Engineering

Recommended materials

Base



1. Carretero 2007:
 1. Cap. 2

Recommended



1. Tanenbaum 2006:
 1. Cap.1
1. Stallings 2005:
 1. Parte uno. Transfondo.
1. Silberschatz 2006:
 1. Cap.1

Contents

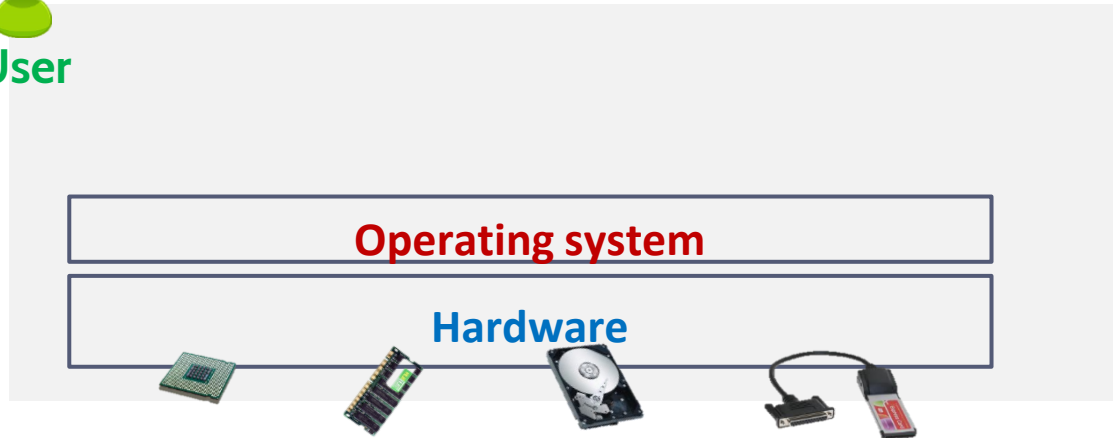
1. What an Operating System is.
 1. Definition, main functionalities and features
1. Operating system structure.
 1. Main goals, structure and asynchronous execution.
 2. Kernel and modules

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1. What an Operating System is.
 1. **Definition**, main functionalities and features
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What is an Operating System?

- ▶ **Operating system:** software designed to communicate **users** and **hardware** and to manage the available resources efficiently.



What is an Operating System?

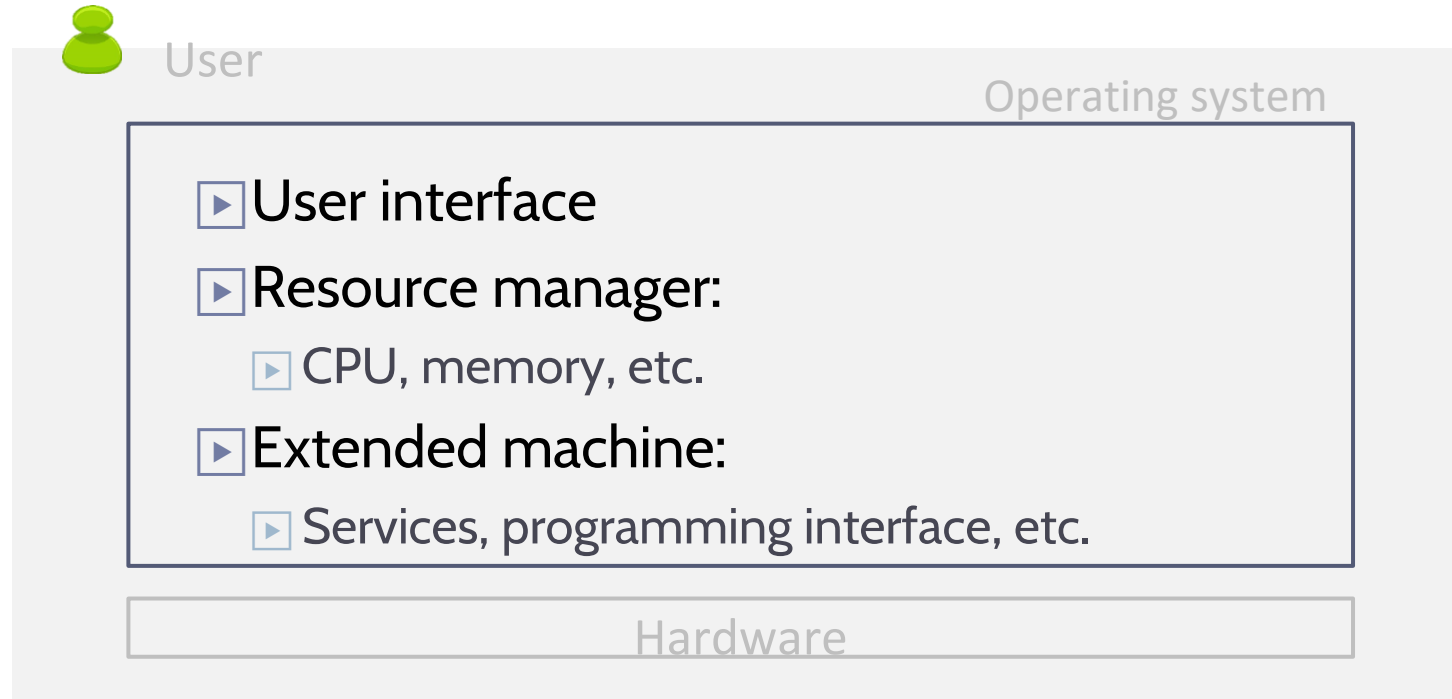
- ▶ **Operating system:** software designed to communicate **users** and **hardware** and to manage the available resources efficiently.



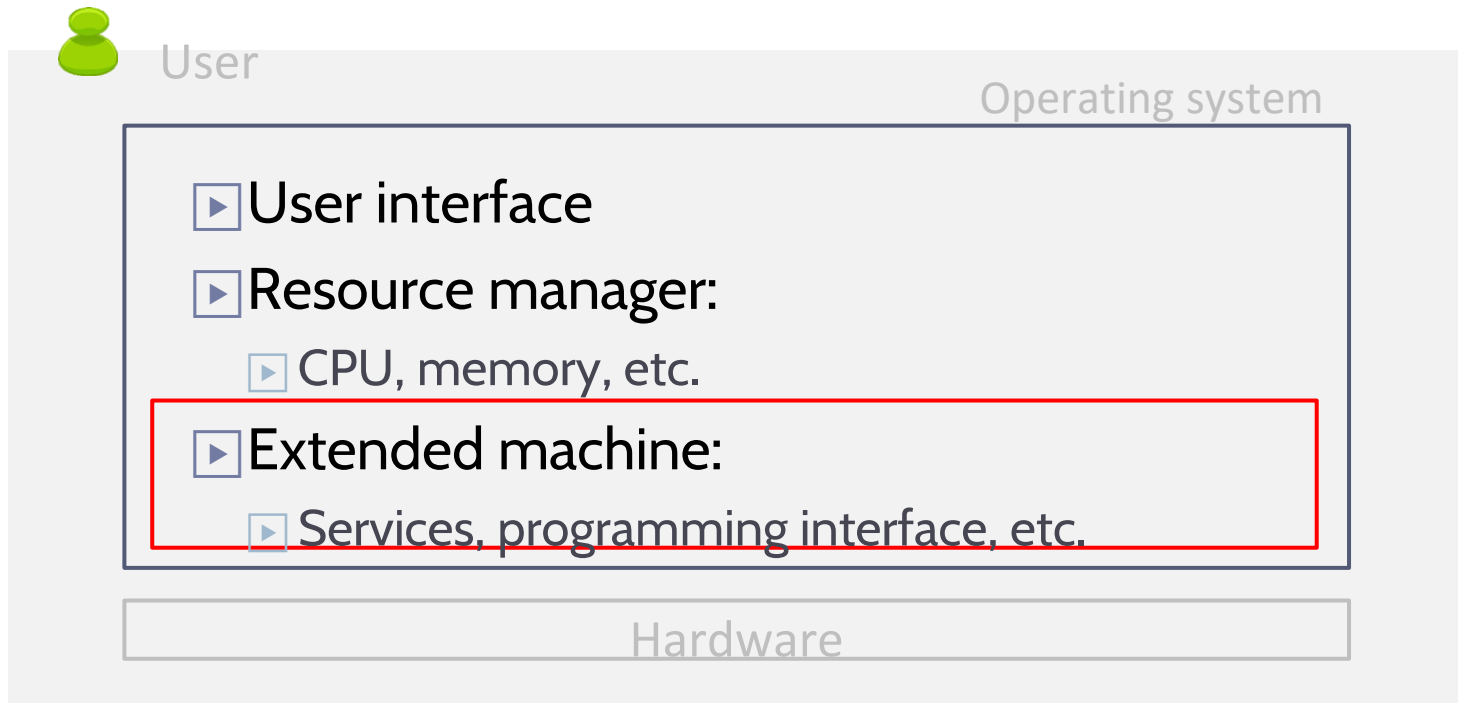
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Operating system functionalities



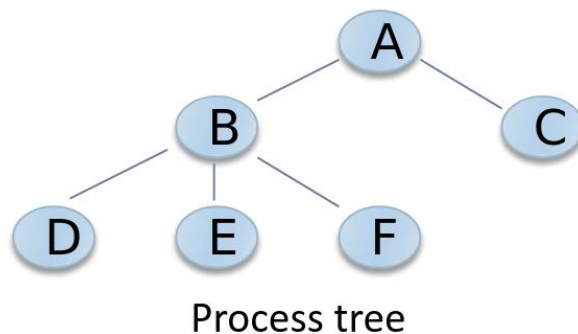
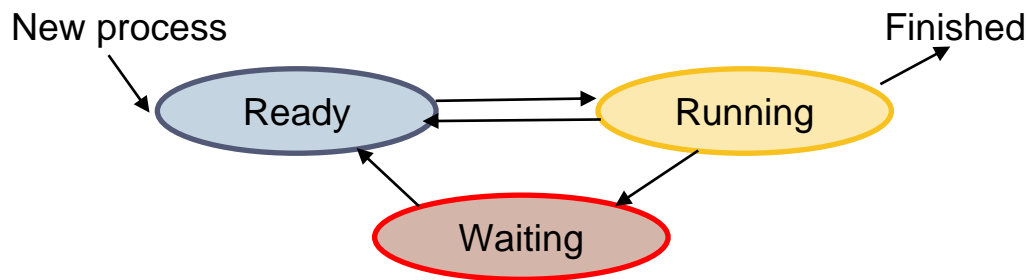
Operating system functionalities



Fundamental abstractions

Processes

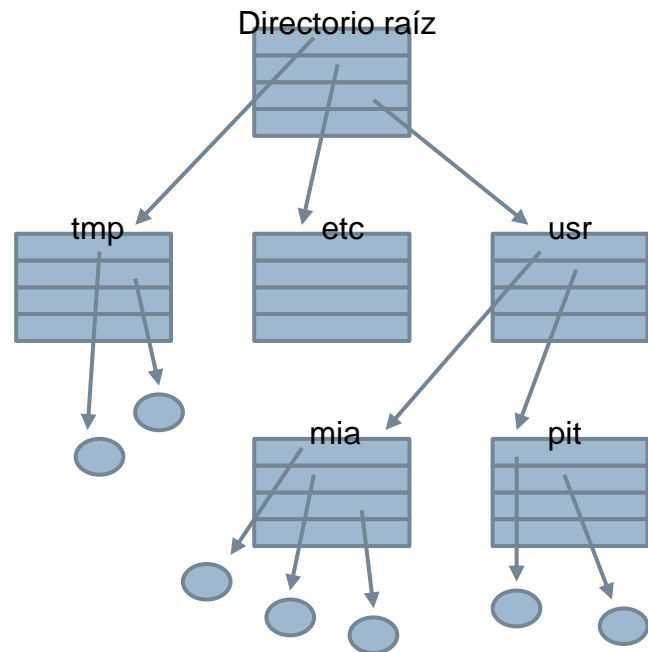
- ▶ Processes, process table, process tree
- ▶ Basic image, scheduling, signals
- ▶ Users and group identifications
- ▶ User interface (*shell*)



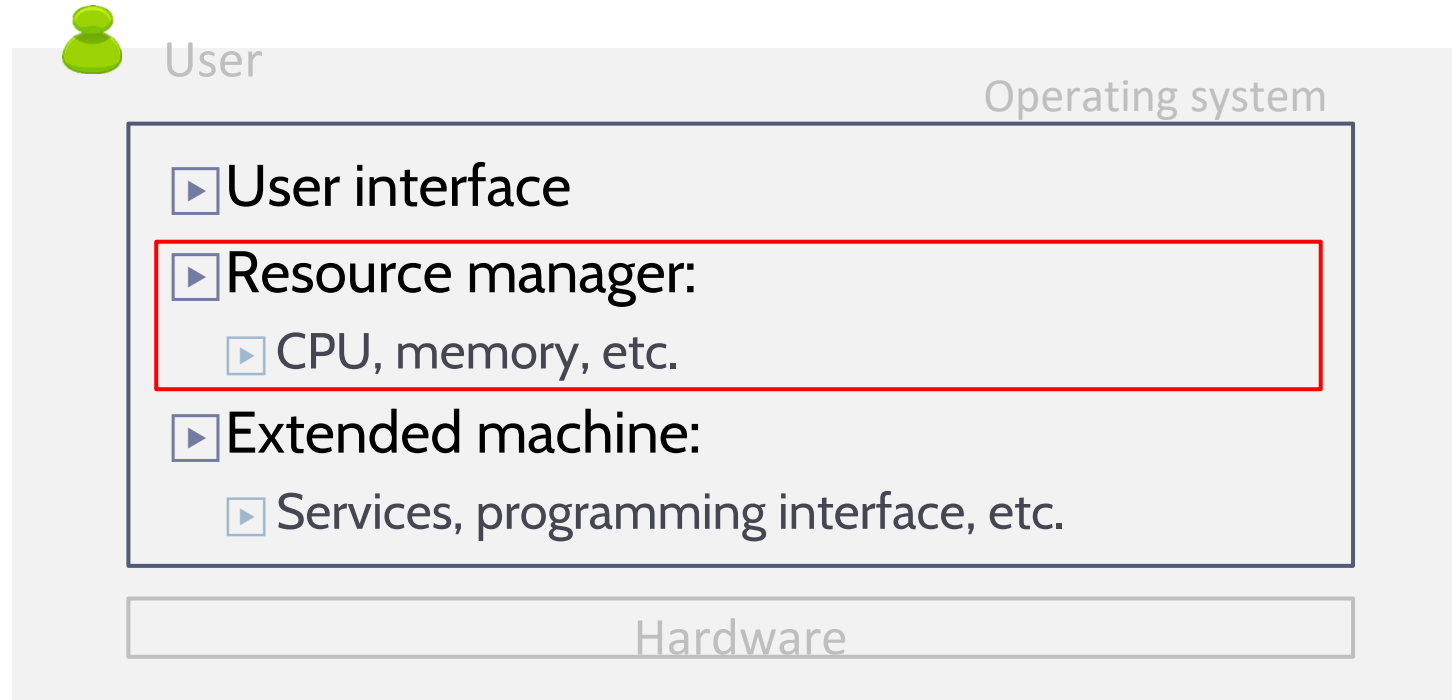
Fundamental abstractions

Files

- ▶ Files and directories
- ▶ Path, working directory and root.
- ▶ Protection
- ▶ File descriptors
- ▶ Special files:
 - ▶ I/O Devices
 - ▶ Pipes
- ▶ Standard input/output/error.



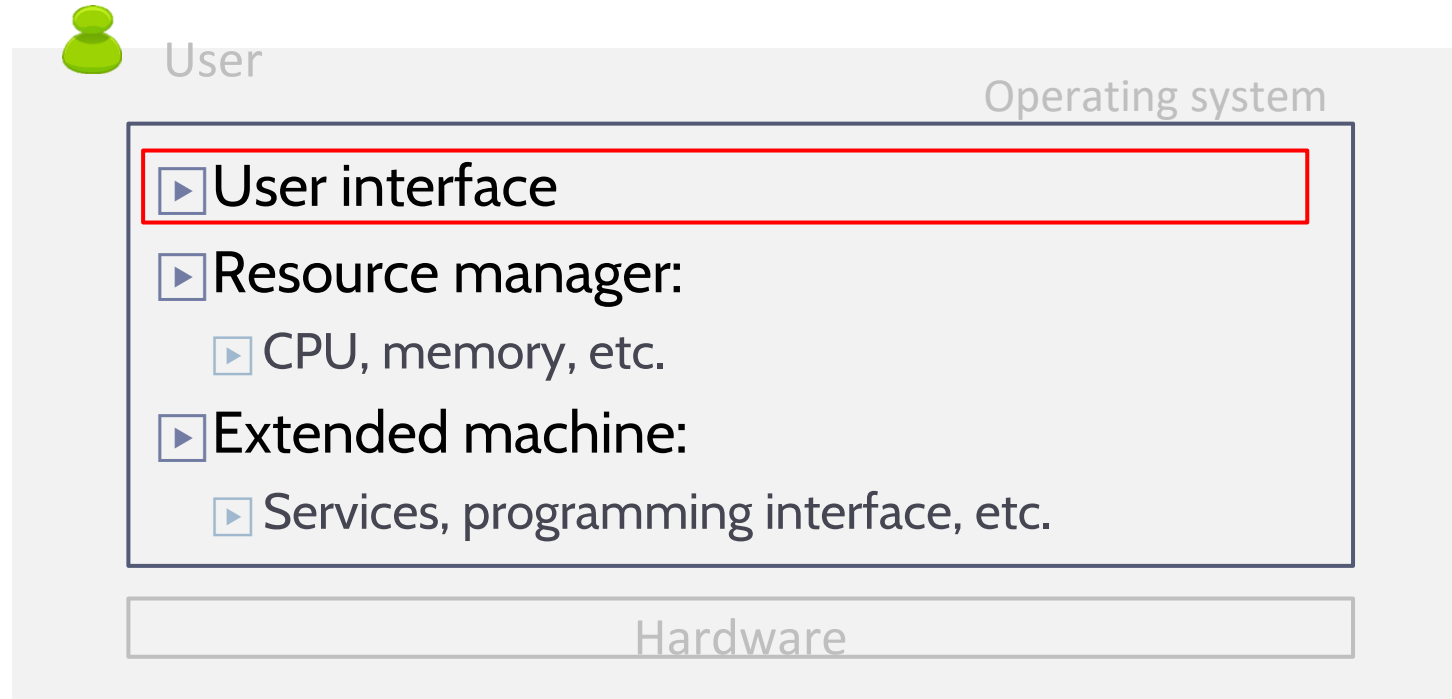
Operating system functionalities



Resource management

- ▶ **Processing** management
 - ▶ Scheduling
 - ▶ Priorities, multi-user
- ▶ **Memory** management
 - ▶ Memory assignment among processes with protection and sharing.
- ▶ **Storage** management – File systems
 - ▶ Offers an unified logical vision for users and programs that is independent of the physical storage.
- ▶ **Device** management
 - ▶ Hide away the hardware dependencies
 - ▶ Provide support for concurrent accesses

Operating system functionalities



User interface

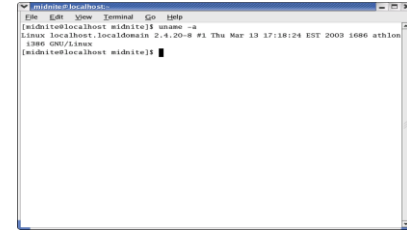
▶ Programming interface:

System calls.

```
ret = close (filedesc) ;
```

▶ User interface:

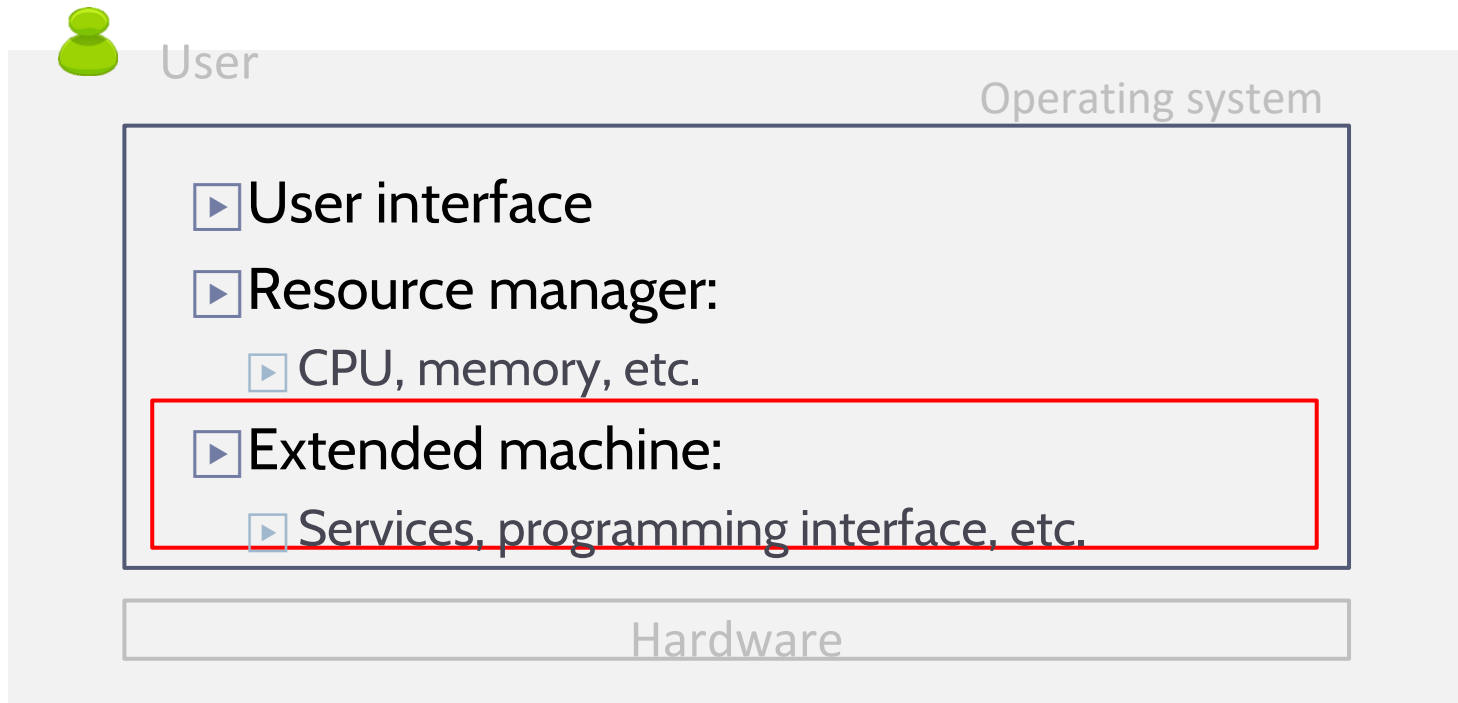
▶ command-line interface or CLI



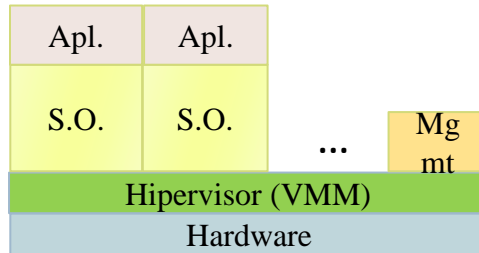
▶ Graphic Interface o GUI



Operating system functionalities

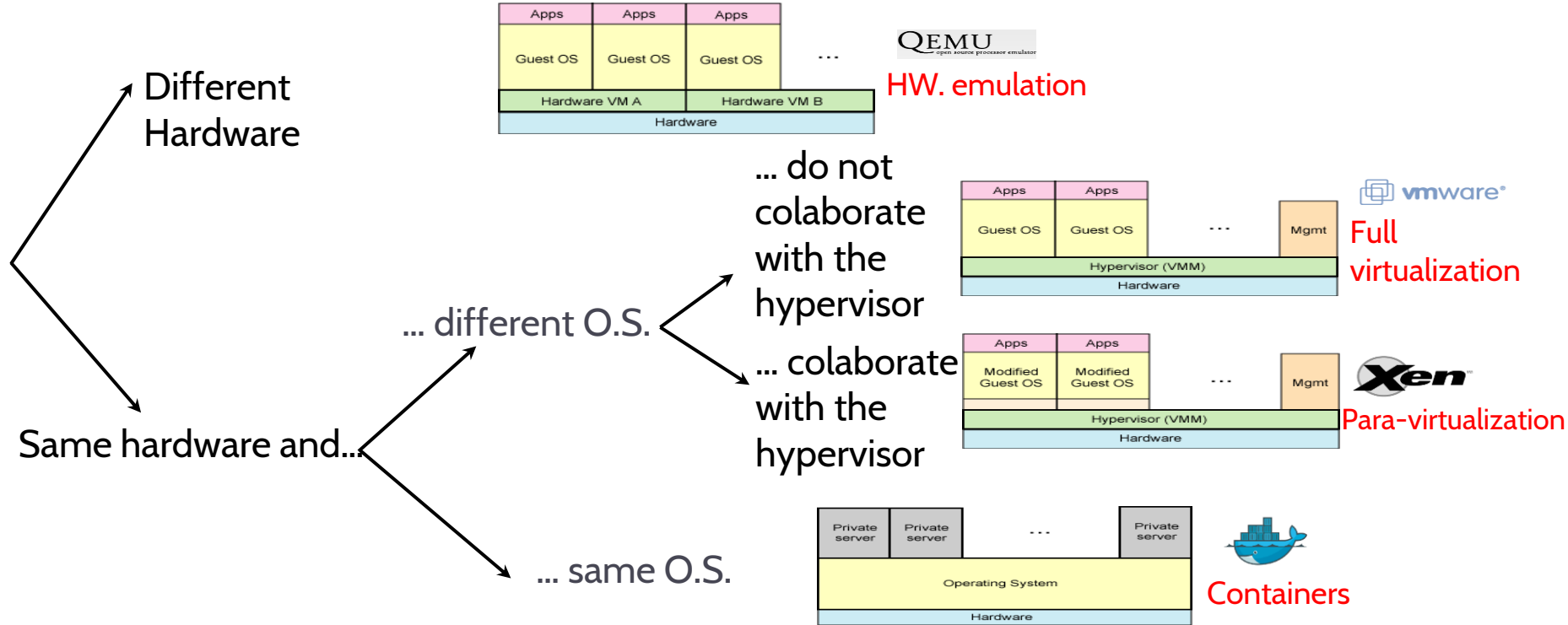


Virtual machines



- ▶ An operating system virtualize part of the hardware elements; Why not **virtualize all of them**?
- ▶ **IBM** used this idea on their mainframes since **70s**.
- ▶ An hypervisor virtualize the whole computer, allowing the execution of multiple operating systems at the same time.
- ▶ Virtualization:
 - ▶ **[+]** offers an excelent system **isolating** among systems and **reduces costs** thanks to the flexible resource allocation.
 - ▶ **[-]** **overheads**

Virtual machines



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Main features

- ▶ Portable
- ▶ Adaptative
- ▶ Multidisciplinary
- ▶ Complex
- ▶ Sensitive

Portability



Mainframe
OS/360, z/OS, ...



Minicomputers y PC
Unix, MacOs, Windows, ...



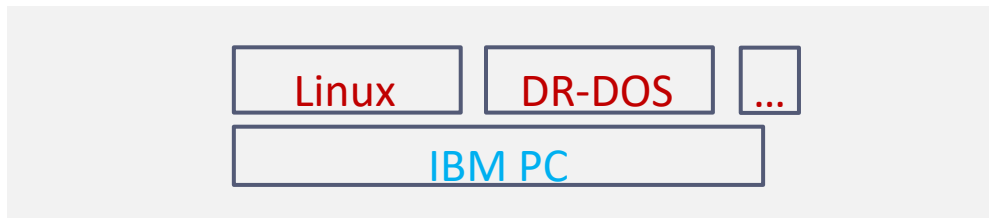
Supercomputer
Unix, Linux, ...



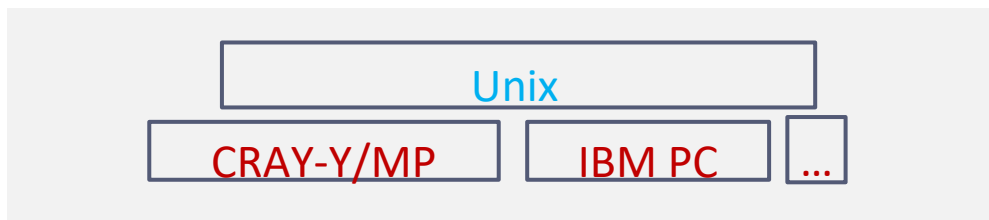
Embedded
VxWorks, QNX, LynxOS,
Android, iOS,
Windows Embedded, ...

1) Portability

- ▶ Same hardware, different O.S.: **IBM PC**



- ▶ Same O.S., different hardware: **Unix**



Portability



2) Adaptive to changes

- ▶ New user requirements:
 - ▶ Voice recognition, multitouch, etc.
- ▶ Hardware evolution:
 - ▶ Controllers for new devices
 - ▶ Multicore systems, virtualization, etc.
- ▶ Integrate solutions for different environments:
 - ▶ Batch processing, multiprogramming, shared CPU time, etc.
 - ▶ Multiuser, cooperative work, etc.
 - ▶ Distributed systems, network services, etc.

3) Multidisciplinary software

- ▶ Integrates works from different areas:

User interface, system software, artificial intelligence, security, software engineering, etc.

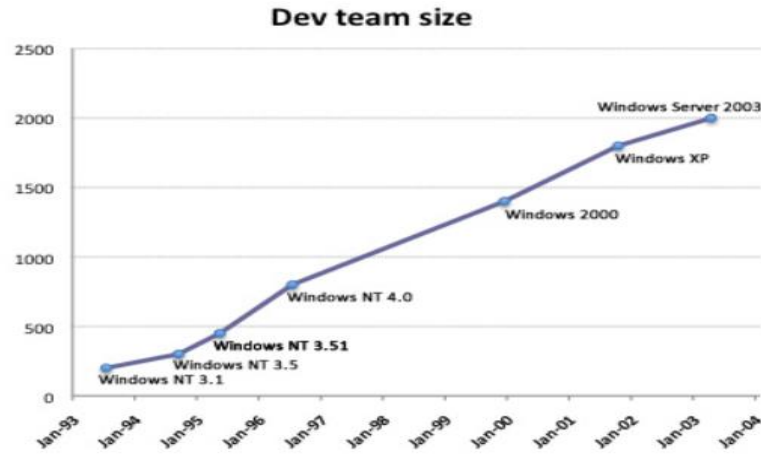


4) Complex software

- ▶ Many lines of code.
- ▶ Many working groups.

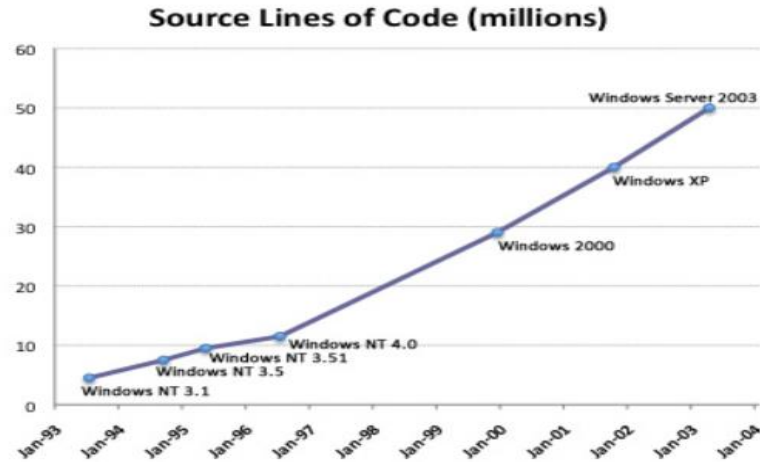
4) Complex software

- ▶ Many lines of code.
- ▶ Many working groups.



4) Complex software

- ▶ Many lines of code.
- ▶ Many working groups.



5) Sensitive software

- ▶ An error in a driver (software in charge of managing a device) may block the entire system.
- ▶ It may work with data that should be carefully treated to not expose the information to not legitimate users nor lose them.

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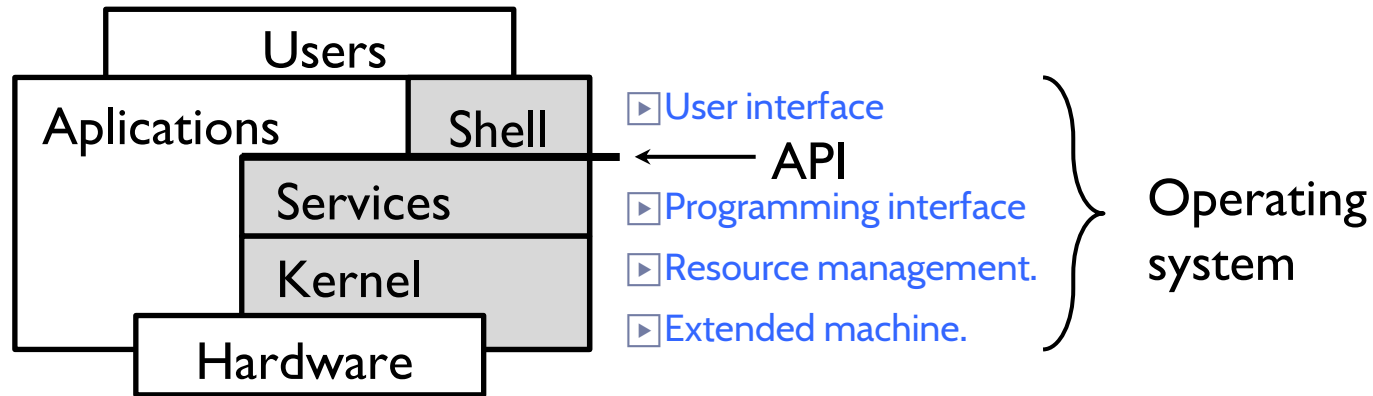
Goals of an operating system design

- ▶ Performance and efficiency.
 - ▶ Low overheads, efficient resource usage
- ▶ Stability: robustness and resilience
 - ▶ Uptime, acceptable degradation, reliability and integrity
- ▶ Capacity: flexibility and compatibility
- ▶ Security and protection
 - ▶ Protection among users
 - ▶ Security
- ▶ Portability
- ▶ Clarity
- ▶ Extensibility

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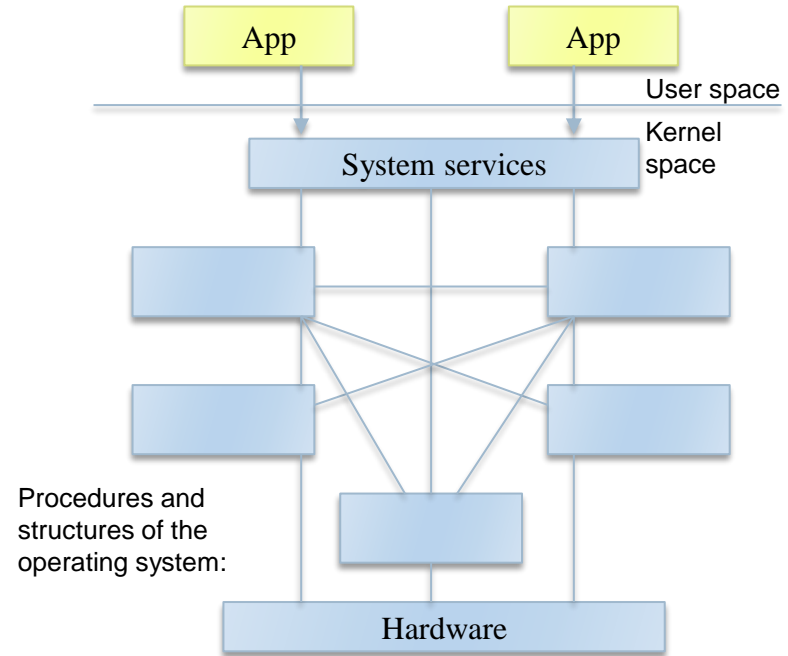
Operating system structure



Operating system structure

Monolithic (macrokernel)

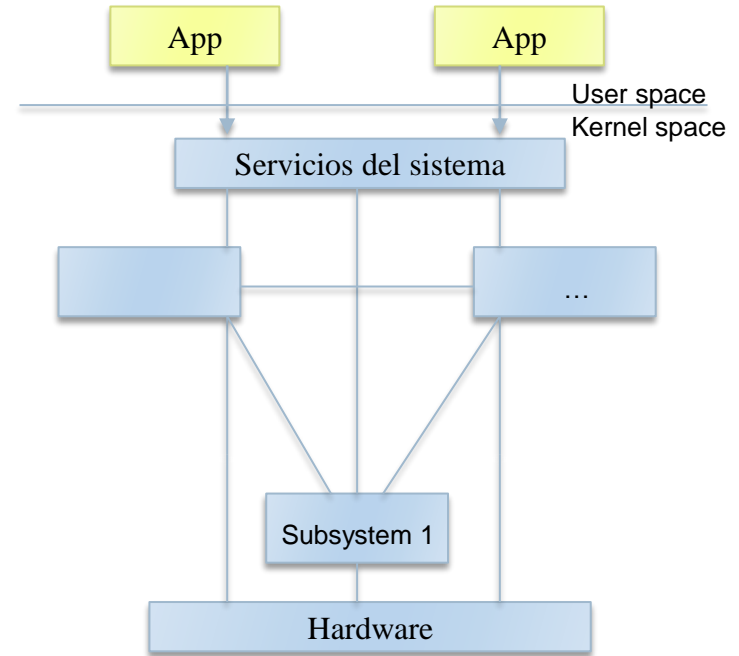
- ▶ monolithic system.
- ▶ Unstructured.
- ▶ Every point can access to any variable or function of other kernel part.
- ▶ **[I]** Poor maintainability, error sensitive.



Operating system structure

subsystems

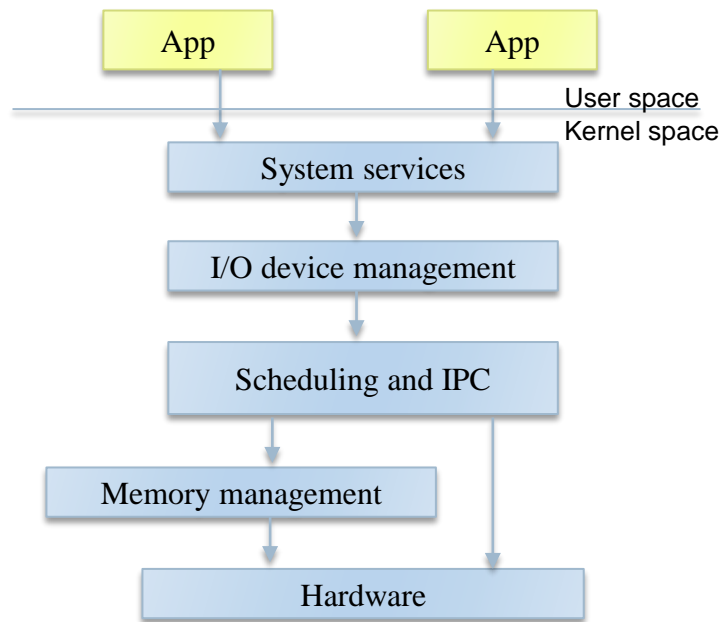
- ▶ Monolithic system comprised by logic subsystems that provides well defined interfaces as entry points.
- ▶ The subsystems groups related procedures and structures.
- ▶ e.g: Linux



Operating system structure

Layered

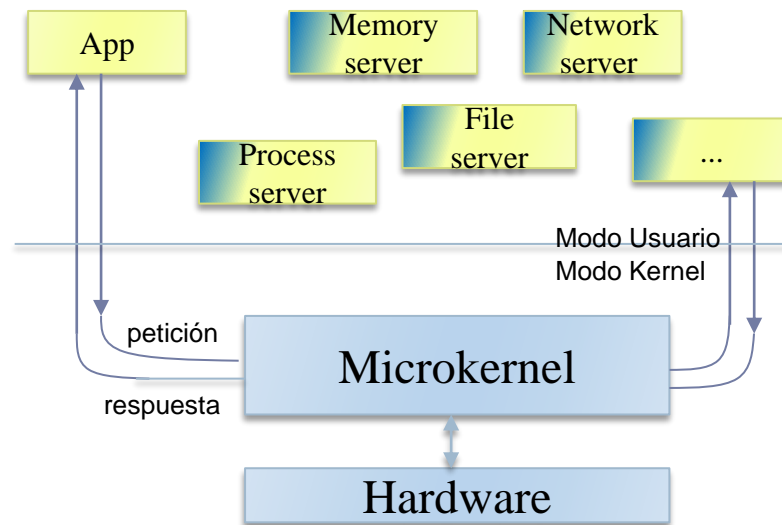
- ▶ Structured in logic layers.
- ▶ Each layer only provide access to lower layers.
- ▶ e.g:
 - ▶ THE (Dijkstra)
 - ▶ Multics, this operating system added the privilege rings.



Operating system structure

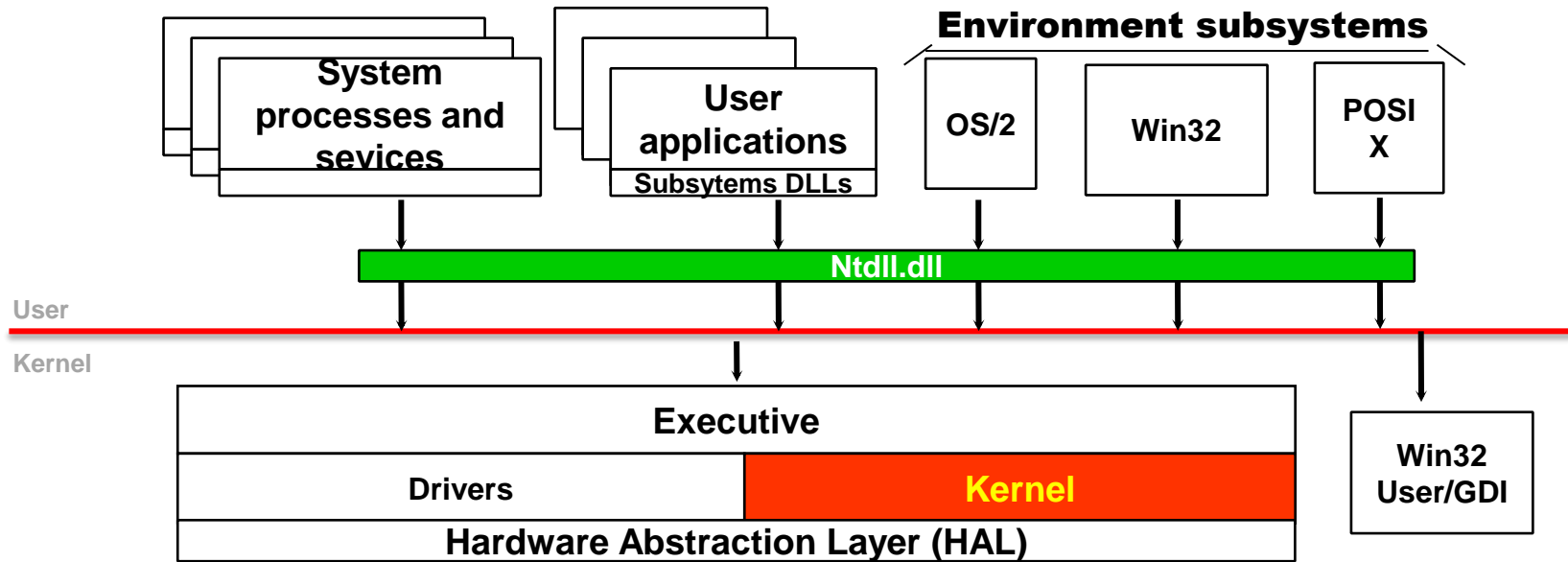
Microkernel

- ▶ The main components are executed outside the kernel space.
- ▶ microkernel:
 - ▶ Scheduling and process management.
 - ▶ Basic virtual memory management.
 - ▶ Basic communication among processes.
- ▶ e.g:
 - ▶ Match, QNX, Minix, L4, etc.



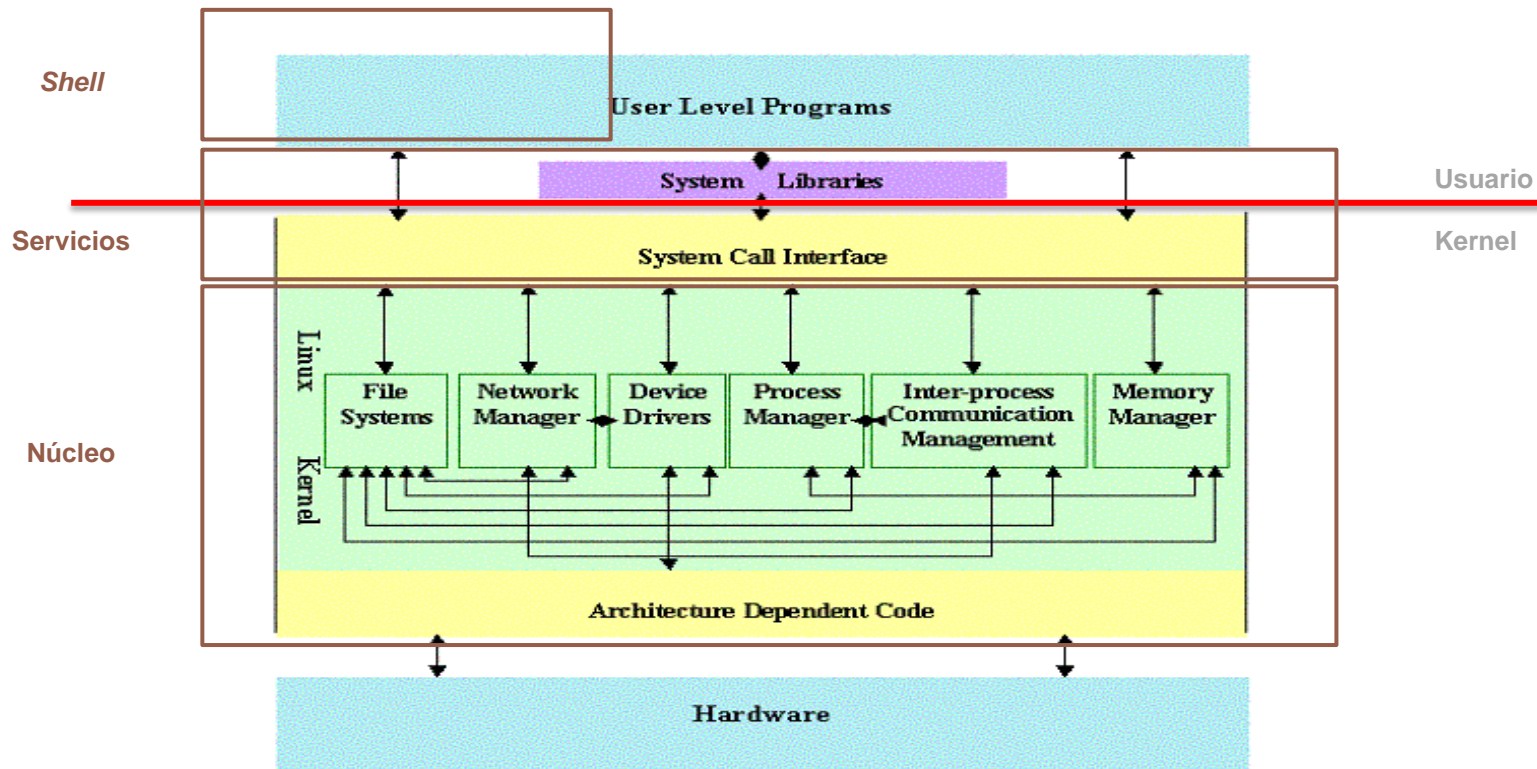
Operating system structure

Windows 2000 (simplified)

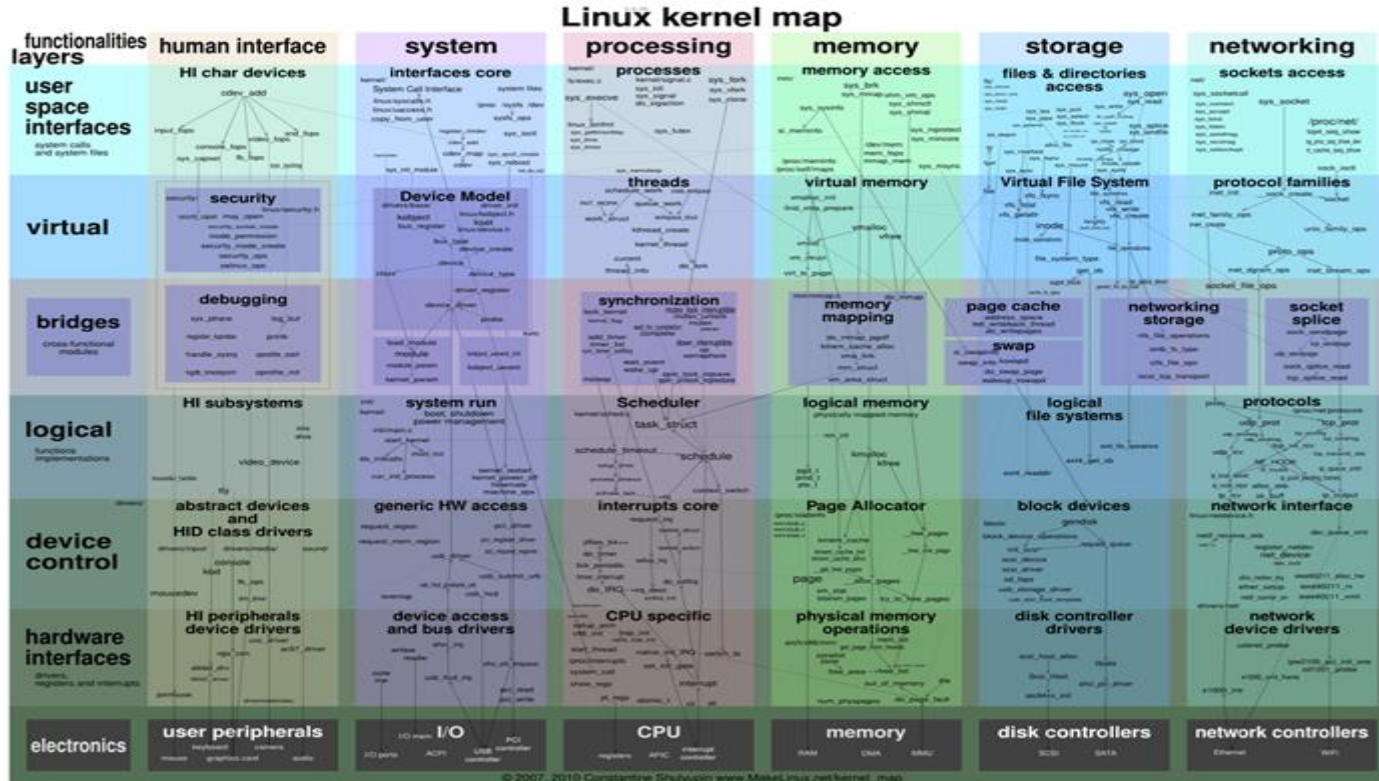


Example of a subsystem operating system

Linux (simplified)



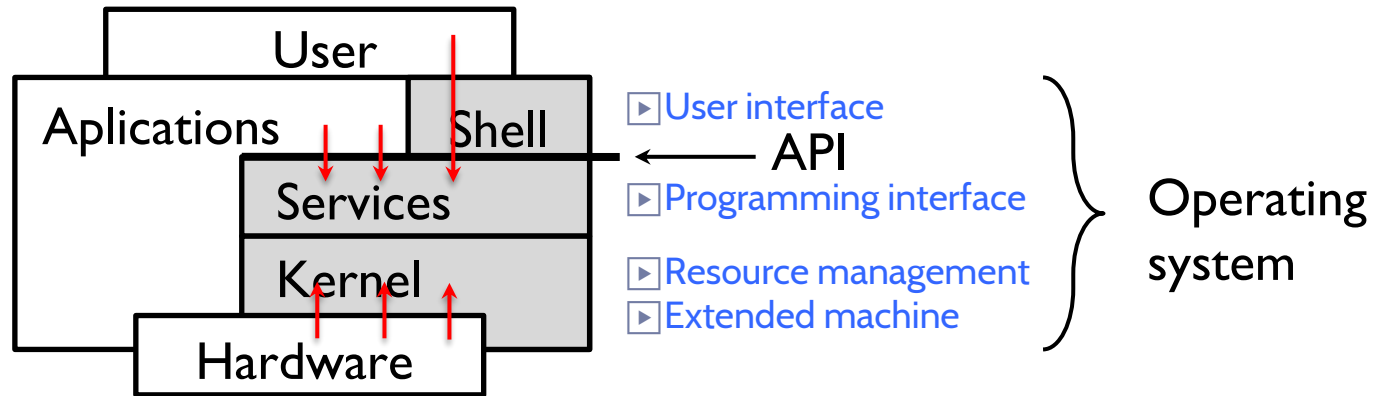
Linux ('less' simplified)



Contents

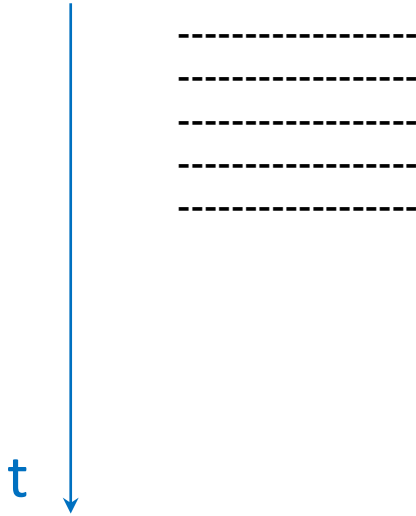
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Operating system structure



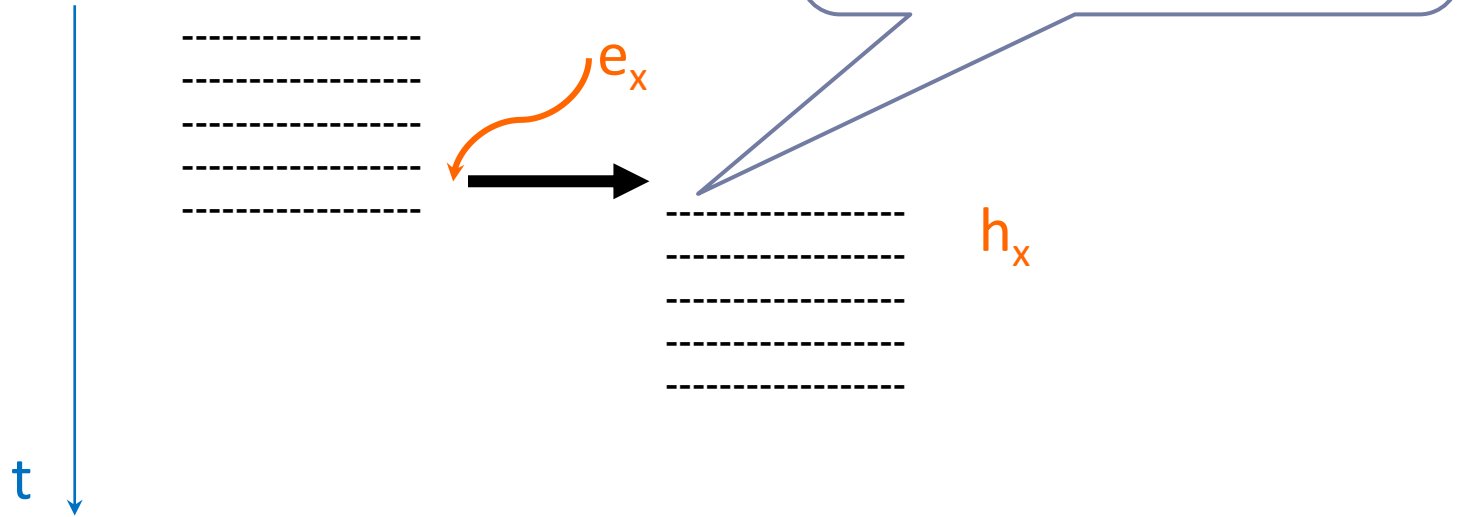
Asynchronous execution

Execution (general)



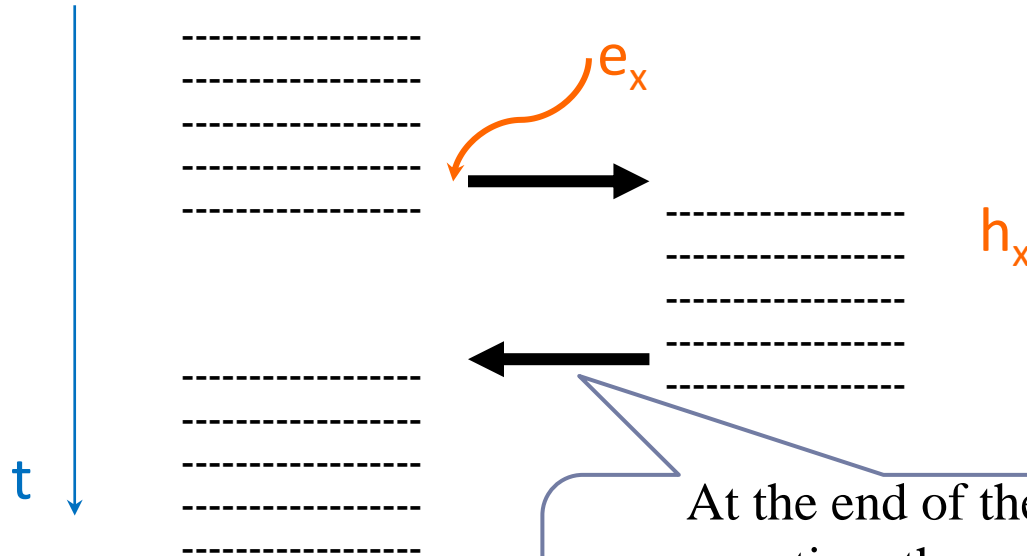
Asynchronous execution

execution (general)



Asynchronous execution

Execution (general)




At the end of the handler execution, the execution is resumed at the point it was interrupted.

Asynchrhonous execution

Source code (general)

```
int main ( ... )  
{  
    ...  
    On (event1, handler1) ;  
    ...  
}
```



1) Asociate handler 1
to event 1

Asynchronous execution

Source code (general)

```
void handler1 ( ... )  
{  
}
```

2) Implement the event handler
function

```
int main ( ... )  
{  
    ...  
    On (event1, handler1) ;  
    ...  
}
```

1) Associate handler
1 to event 1

Asynchronous execution

Source code (general)

```
int global1;
```

```
...
```

```
void handler1 ( ... )
```

```
{  
}
```

```
int main ( ... )
```

```
{
```

```
...
```

```
On (event1, handler1);
```

```
...
```

```
}
```

3) To communicate functions , we employ global variables.

2) Implement the event handler function

Example of asynchronous execution

Signals

signal.h

```
#include<stdio.h>
#include<signal.h>
#include<unistd.h>

void sig_handler (int signo)
{
    if (signo == SIGINT)
        printf("received SIGINT\n");
}

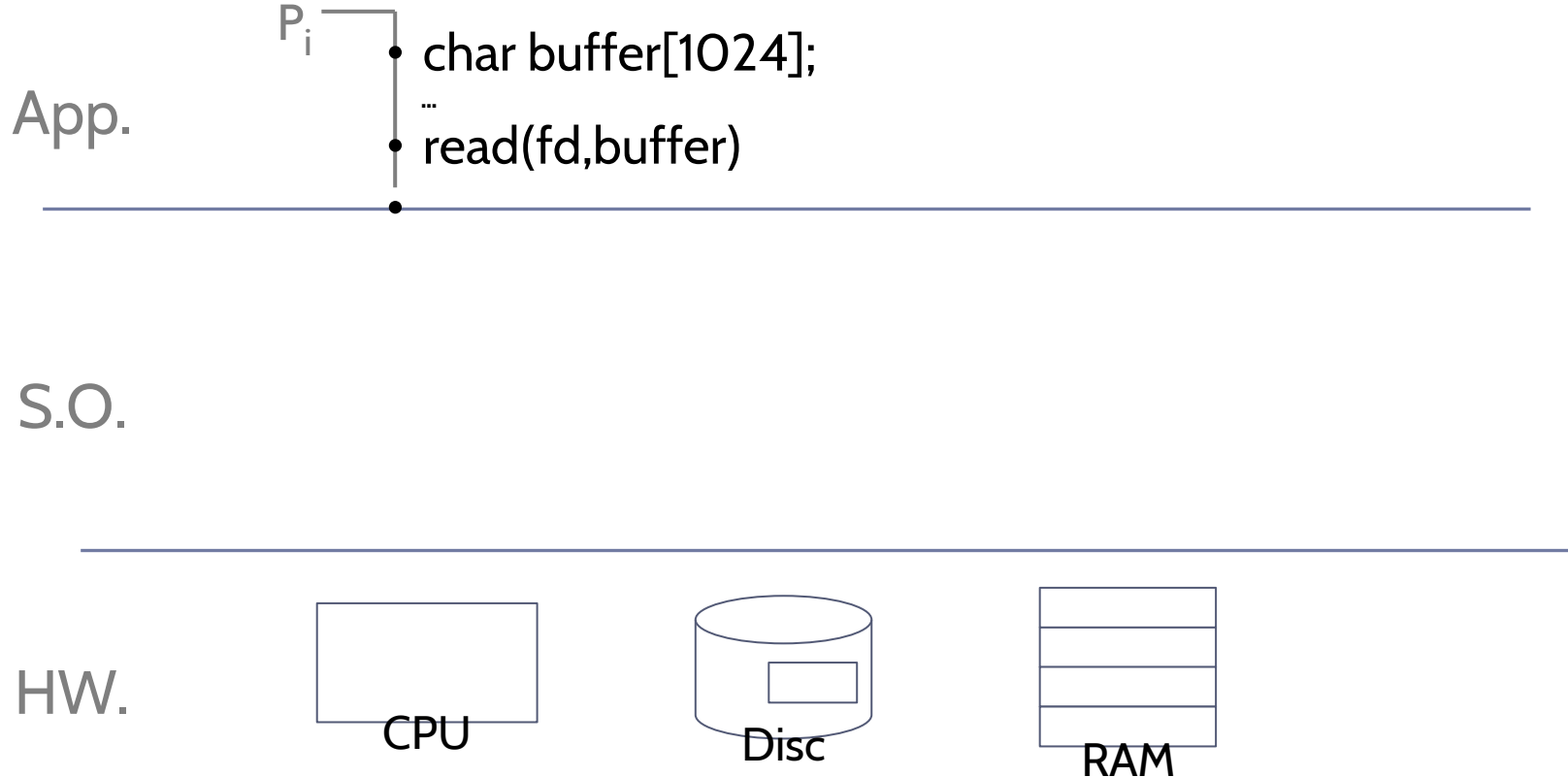
int main(void)
{
    if (signal(SIGINT, sig_handler) == SIG_ERR)
        printf("\n can't catch SIGINT\n");

    sleep(60); // simula un proceso largo.

    return 0;
}
```

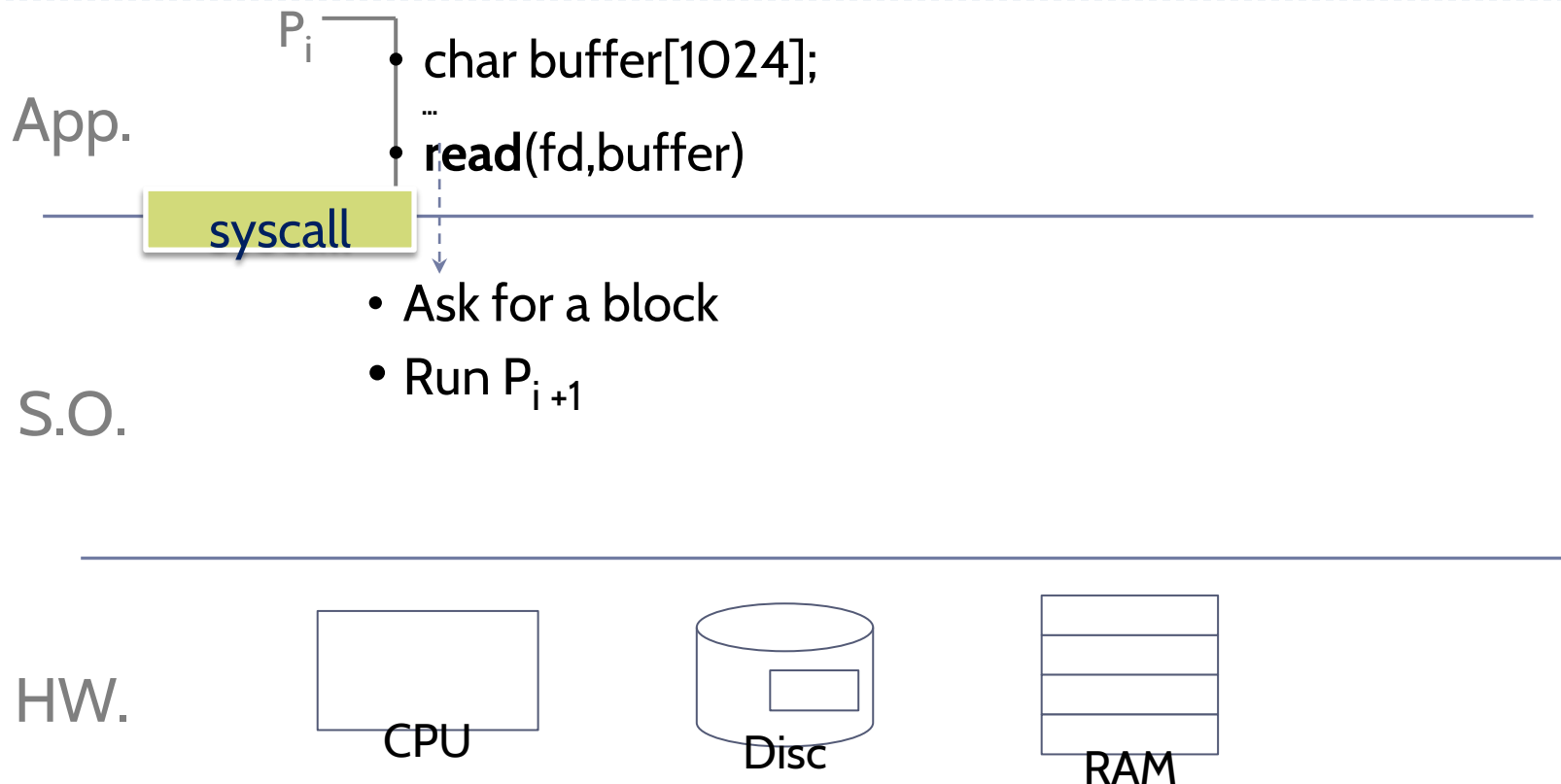

Asynchronous execution

Simplified example



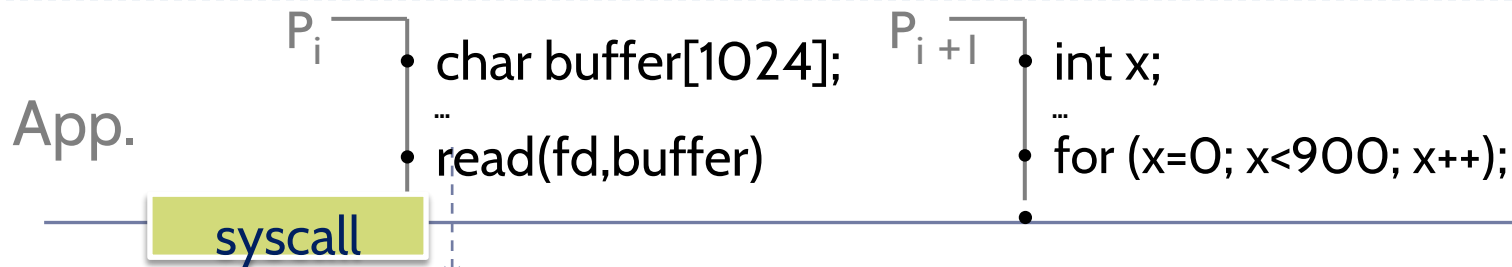
Asynchronous execution

Simplified example



Asynchronous execution

Simplified example

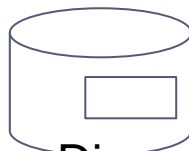


- Ask for a block
- Run P_{i+1}

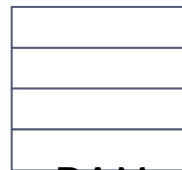
HW.



CPU



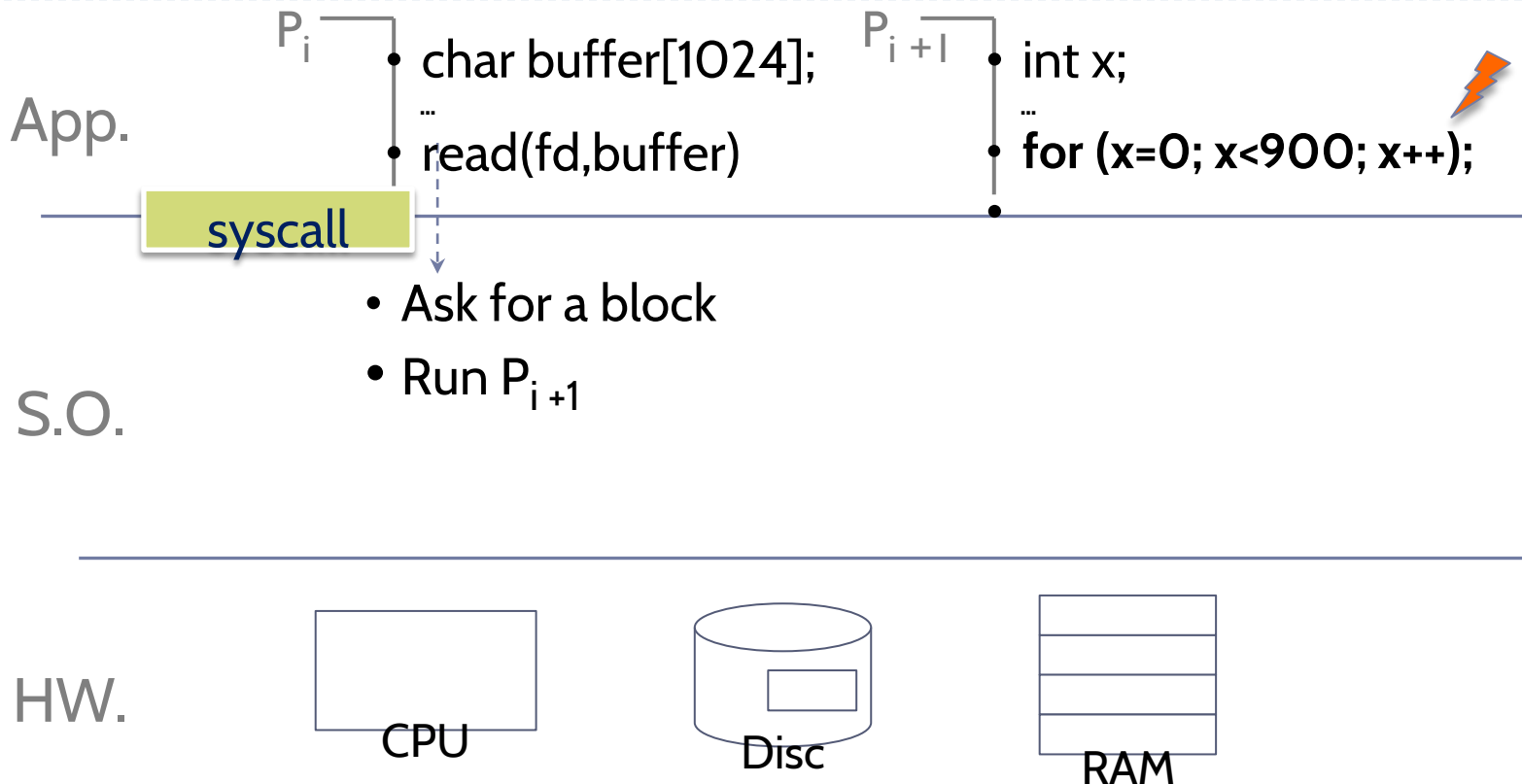
Disc



RAM

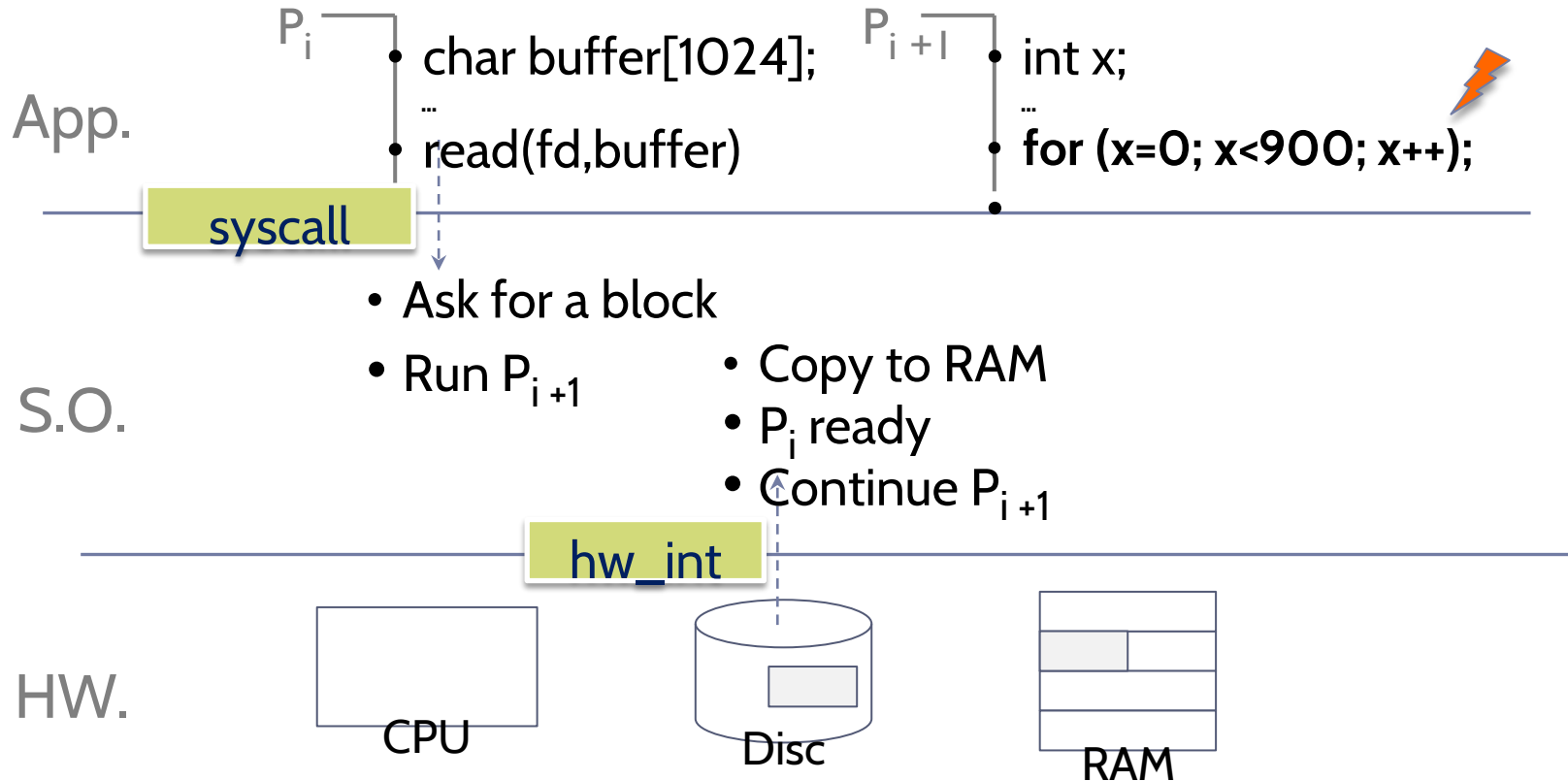
Asynchronous execution

Simplified exemple



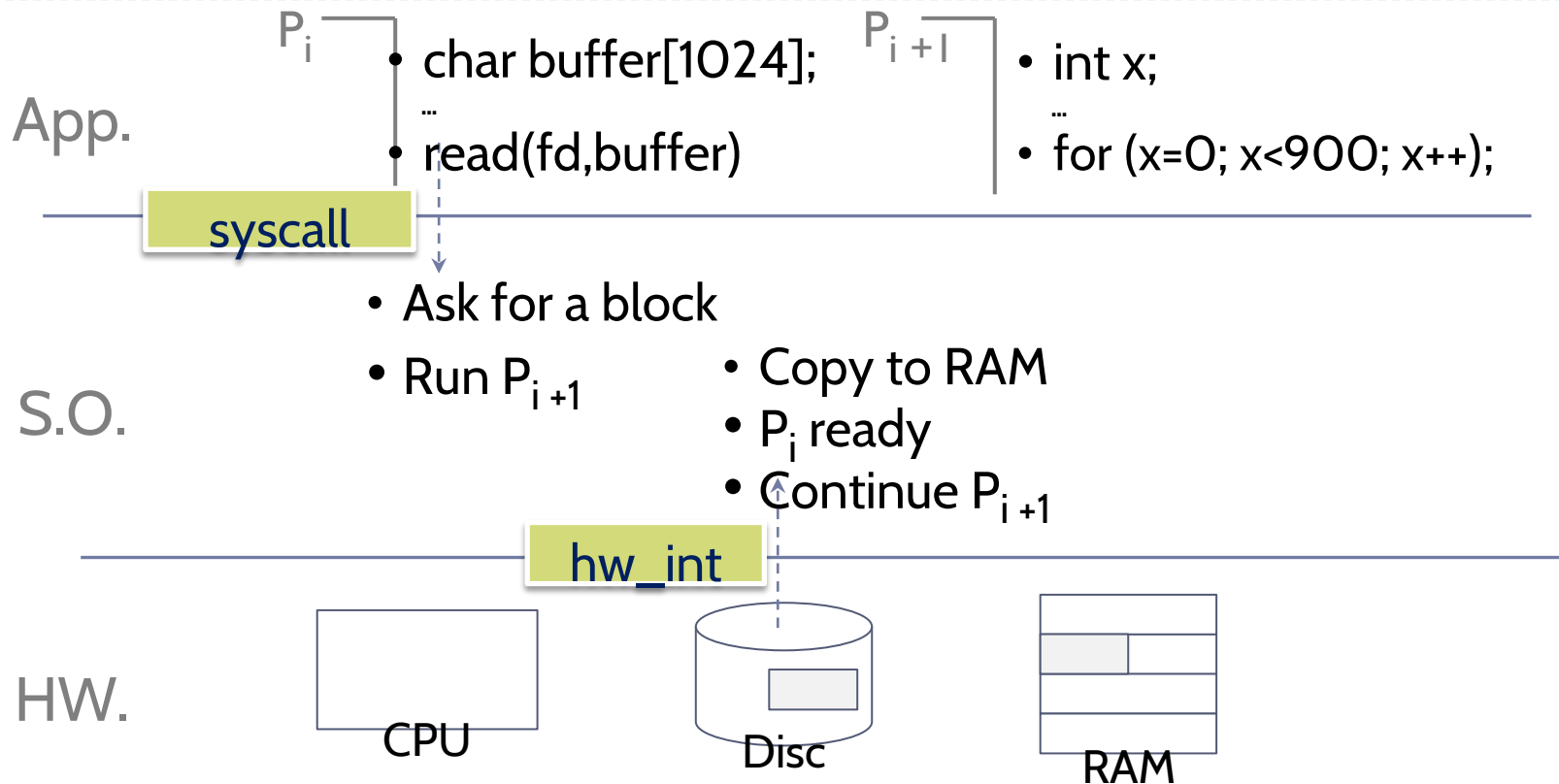
Asynchronous execution

Simplified example



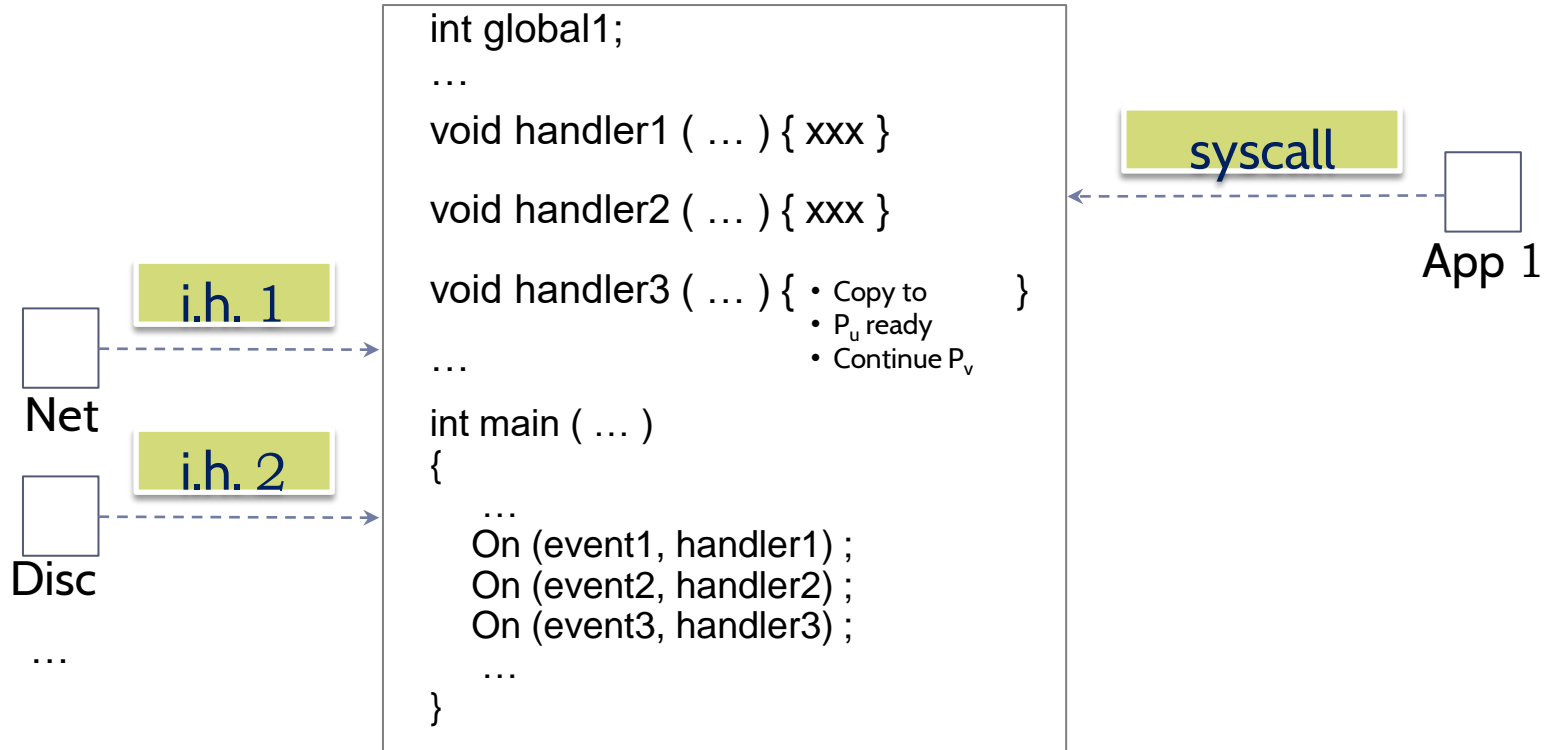
Asynchronous execution

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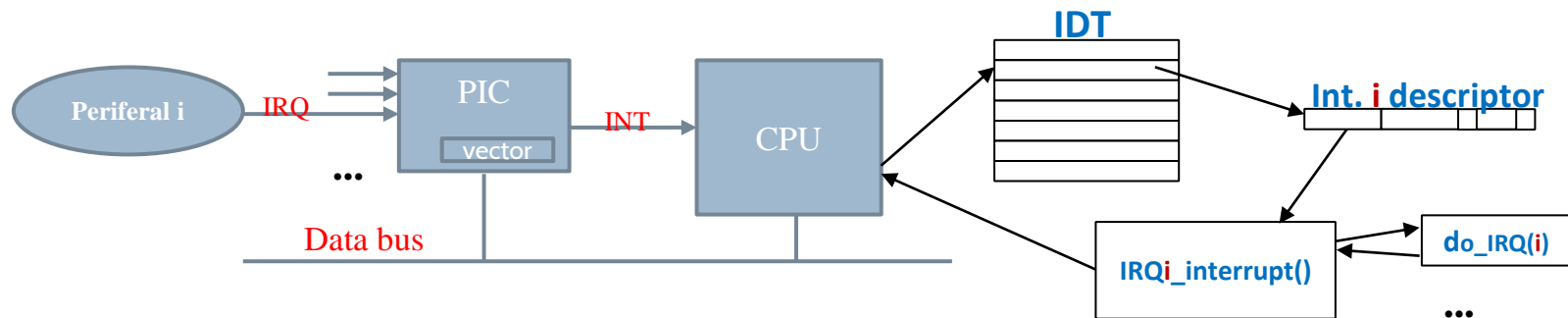


Operating system structure

Source code (general)

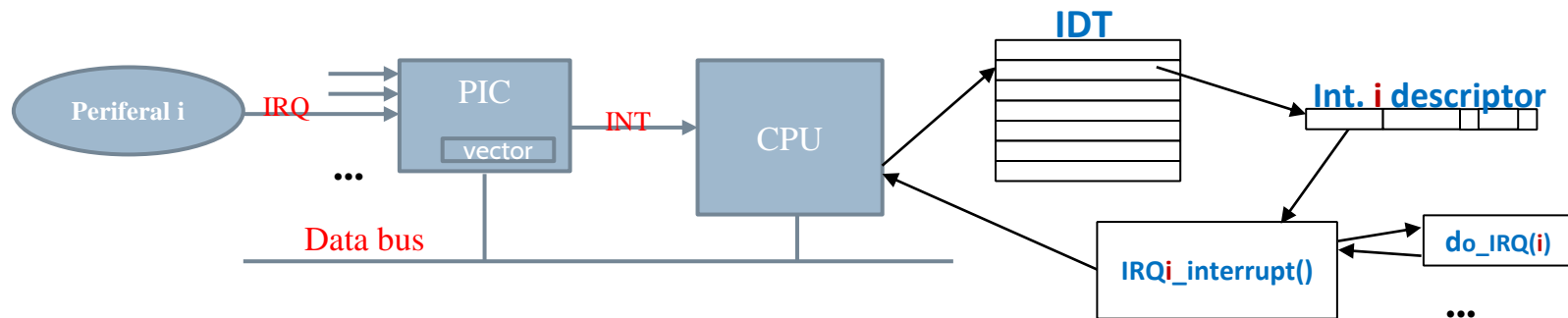


Hardware interrupts



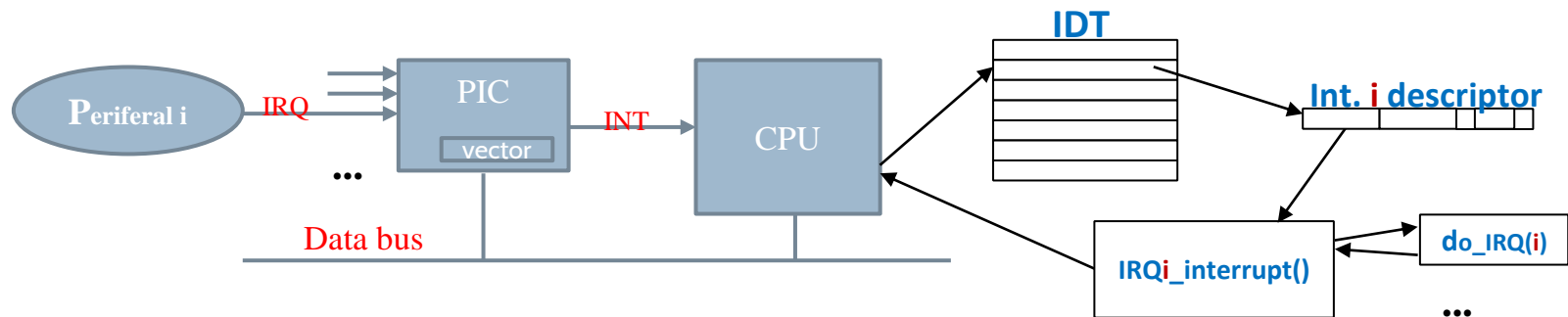
- ▶ Each **periferal** (able to generate an interrupt request) its associated to a given interrupt line or **IRQ** (*Interrupt ReQuest*)
- ▶ All lines are connected to a **PIC** (*Programmable Interrupt Controller*)
 - ▶ Currently, modern achitectures uses APIC (*Advanced Programmable Interrupt Controller*)
- ▶ The PIC is connected to the **CPU** by the pending interrupt line (**INT**)
- ▶ Both PIC and CPU are connected by **data bus**.

Hardware interrupts



- ▶ **PIC** monitors the IRQ lines waiting for a signal.
- ▶ When a signal arrives:
 - ▶ Associate the corresponding IRQ to a value stored in a given PIC register (namely **vector**)
 - ▶ Signals the CPU through the pending interrupt line (**INT**)
 - ▶ The CPU reads the **vector register** as an I/O port or memory address
 - ▶ The CPU writes in the PIC control register that it already accessed the vector
 - ▶ The PIC deactivates the pending interrupt line, clears the vector and starts monitoring again...

Hardware interrupts



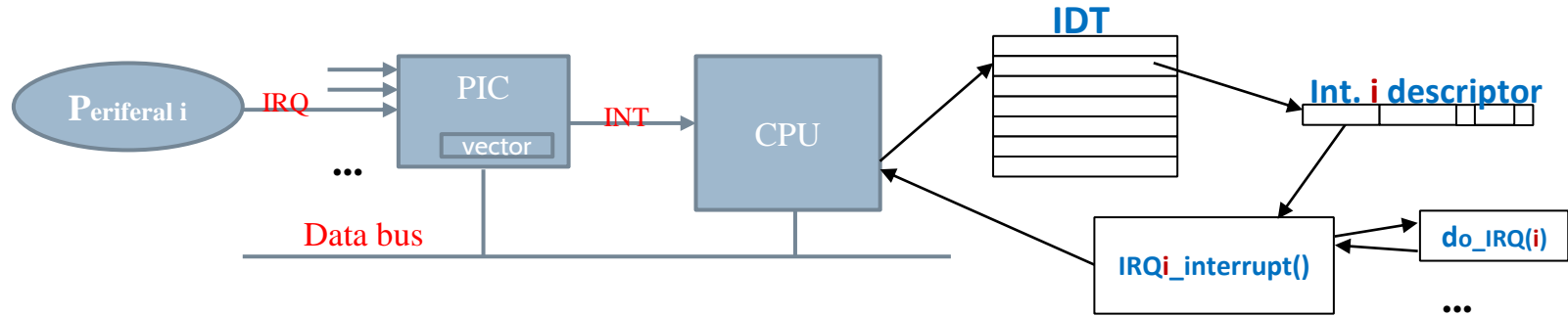
▶ PIC may allow **disable the IRQ**

- ▶ In that case, the PIC does not signal the CPU of a given IRQ and are enqueued until they are enabled.
- ▶ Disabling an interruption at the CPU level (mask/unmask) is different: the CPU ignores the INT.

▶ Additionally, the PIC may have **priority levels**

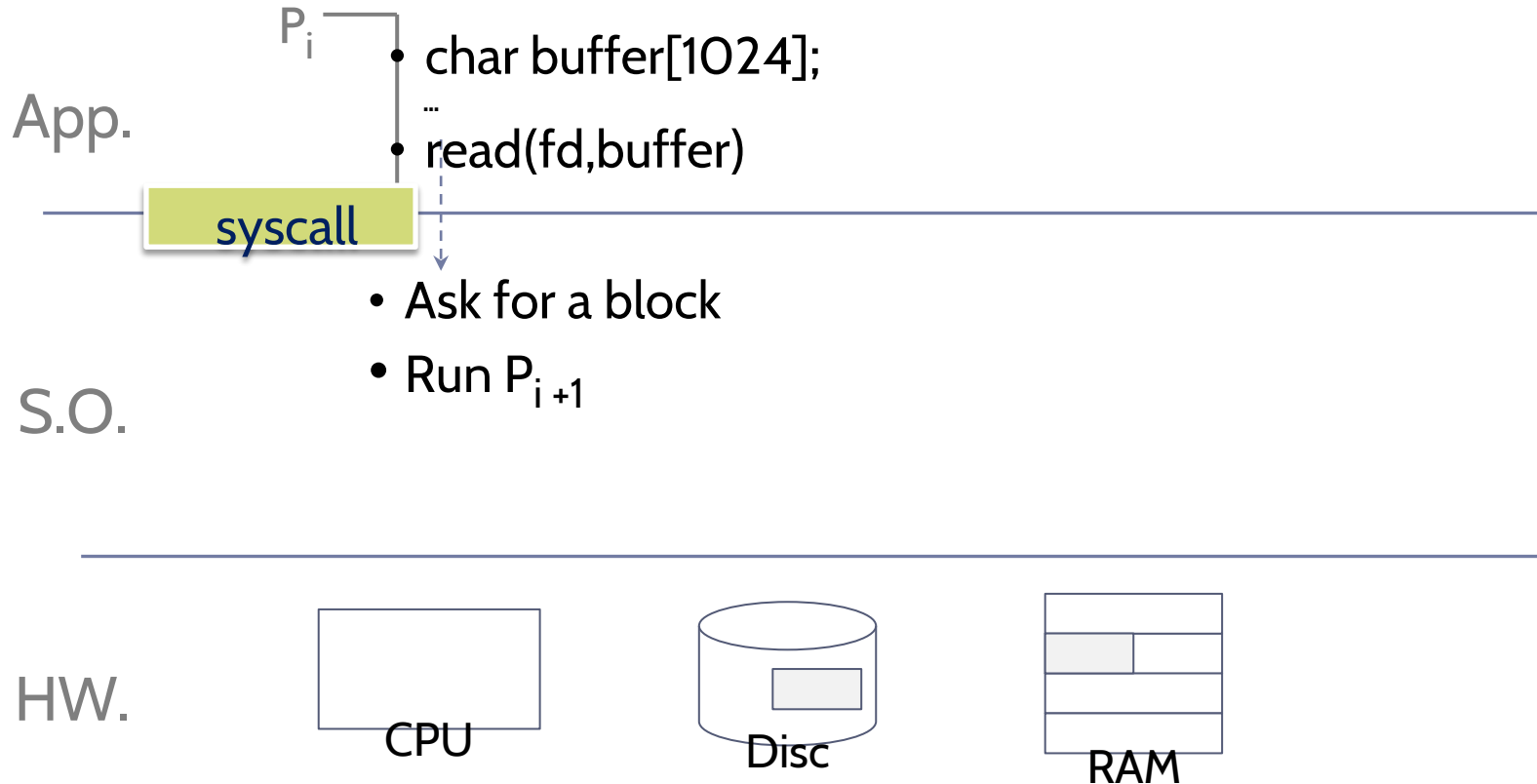
- ▶ Each IRQ is associated with a given priority level
- ▶ If there are multiple IRQ, the PIC 'processes' those with the highest priority
- ▶ If the PIC does not support priority level, it can be simulated by the operating system at software level.

Hardware interrupts

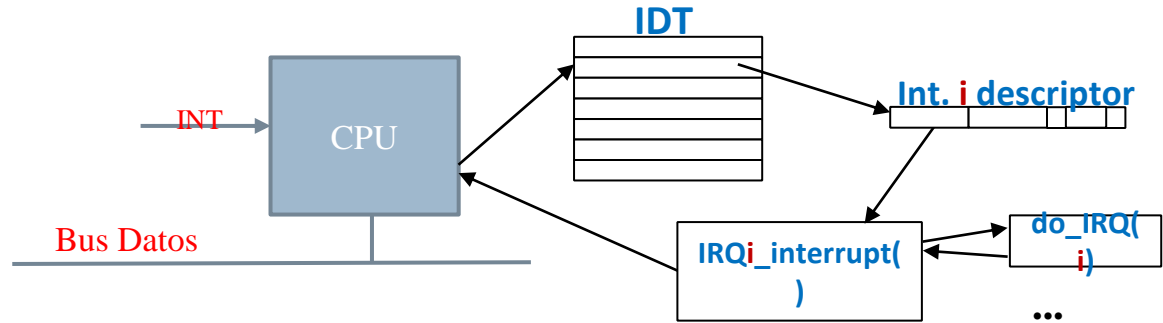


- ▶ The CPU receives the **INT** request
- ▶ Copies the vector through the data bus and notifies the PIC (ACK)
- ▶ Searches in the *Interrupt Descriptor Table* (**IDT**) for the associated function handler
- ▶ Stores the processor state at the stack, executes in **privileged mode** and runs the ISR
 - ▶ Multiple ISR (**do_IRQ**) may share the same interrupt
 - ▶ Multiple interrupt may share a generic handler function.
- ▶ Restore the state from the stack, and runs the **RETI** (goes to the previous mode and resume the execution)

System call



Llamada al sistema

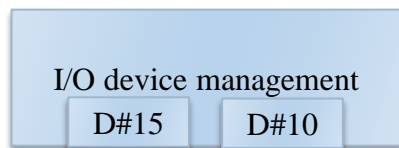


- ▣ There exists an assembly instruction to generate an interrupt by software
- ▣ Searches in the *Interrupt Descriptor Table* (IDT) for the associated function handler
- ▣ Stores the processor state at the stack, executes in **privileged mode** and runs the ISR
 - ▣ Multiple IST (**do_IRQ**) may share the same interrupt
 - ▣ Multiple interrupt may share a generic handler function.
- ▣ Restore the state from the stack, and runs the RETI (goes to the previous mode and resume the execution)

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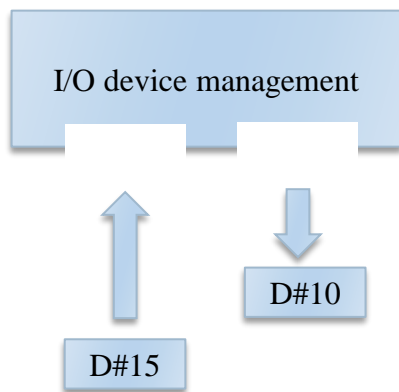
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Executables



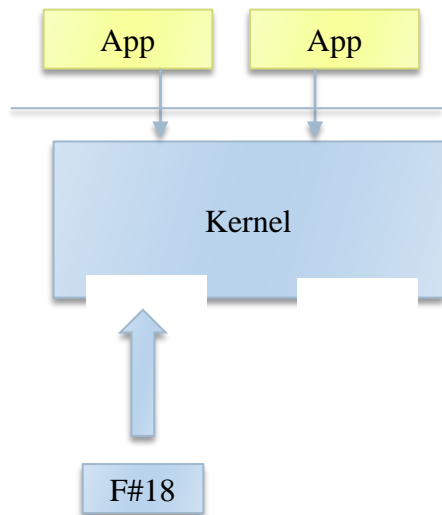
- ▶ Older kernels:
 - ▶ Included the code for **all possible devices**.
 - ▶ From time to time it was necessary to **recompile** the kernel to add support for new devices.
 - ▶ It was distributed as a **set of executables**.

Modules



- ▶ Were designed to **conditionally include device controllers** (*drivers*)
- ▶ They allow to **dynamically include pre-compiled drivers**.
- ▶ Are distributed as **dynamic libraries** for the kernel (.so/.dll).
- ▶ A given module may be **downloaded** when the device won't be used again.

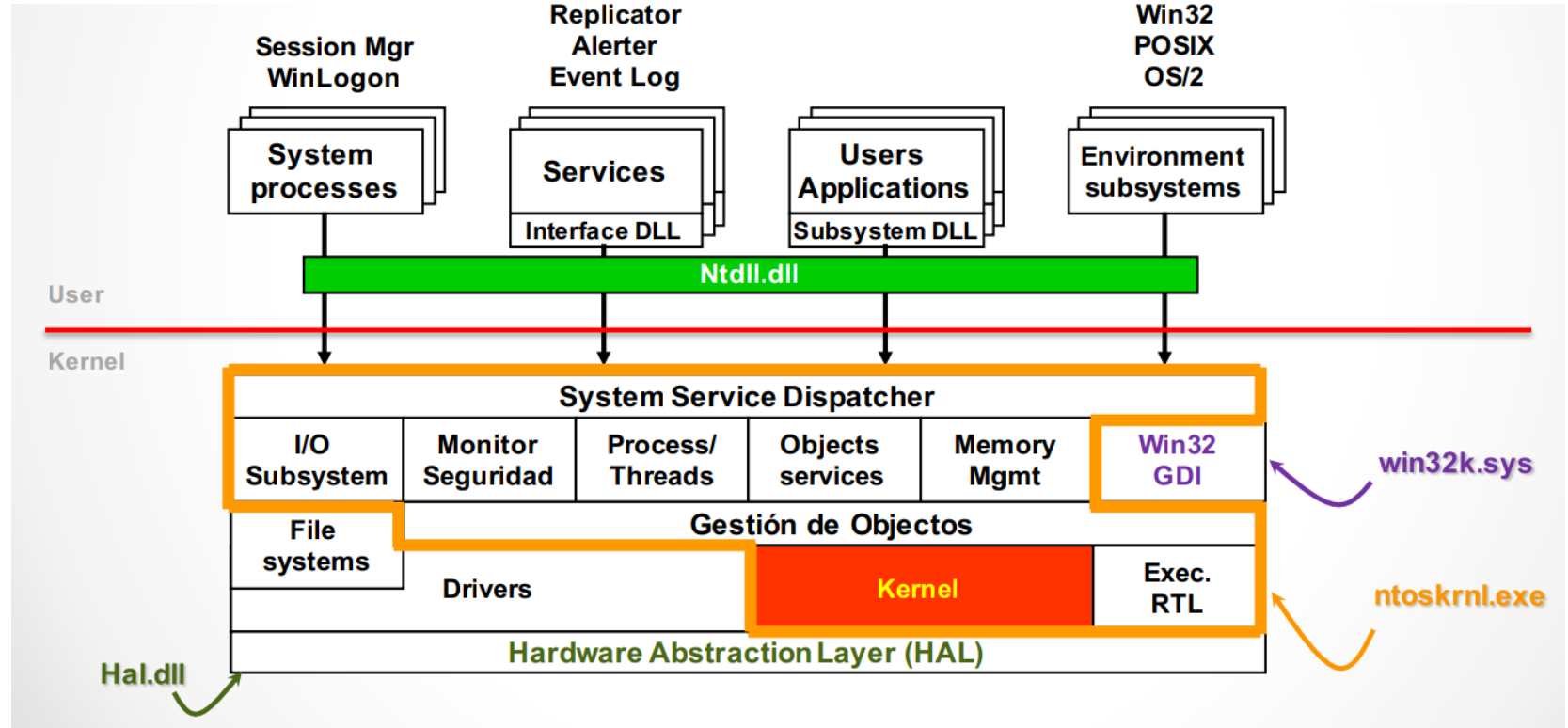
Módulos



- ▶ Most of the current **operating systems** support **modules**:
 - ▶ Linux, Solaris, BSD, Windows, etc.
- ▶ Currently, the modules are not only used for drivers, but also to **incorporate new functionalities**:
 - ▶ Eg.: Linux kernel extensively uses modules for file systems, network protocols, system calls, etc.

Modules

Windows 2000



Lesson 1

Introduction

Operating systems design
Degree in Computer Science and Engineering