

Lesson 3a

process, devices, drivers, and extended services

Operating System Design
Degree in Computer Science and Engineering, Double Degree CS&E + BA

Recommended readings

Base



1. Carretero 2007:
 1. Cap.7

Recommended

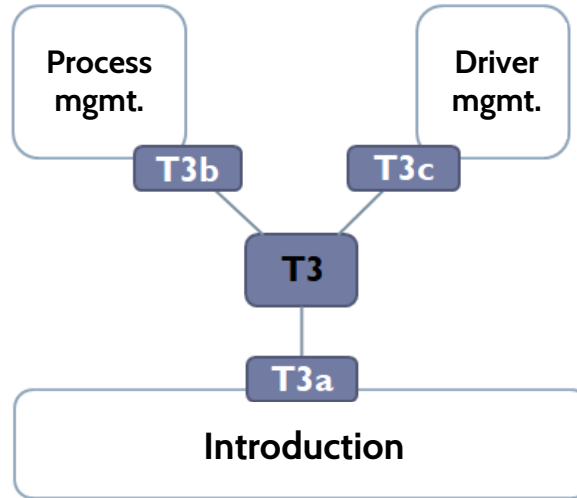


1. Tanenbaum 2006(en):
 1. Cap.3
1. Stallings 2005(en):
 1. Parte tres
1. Silberschatz 2006:
 1. Cap. Sistemas Module

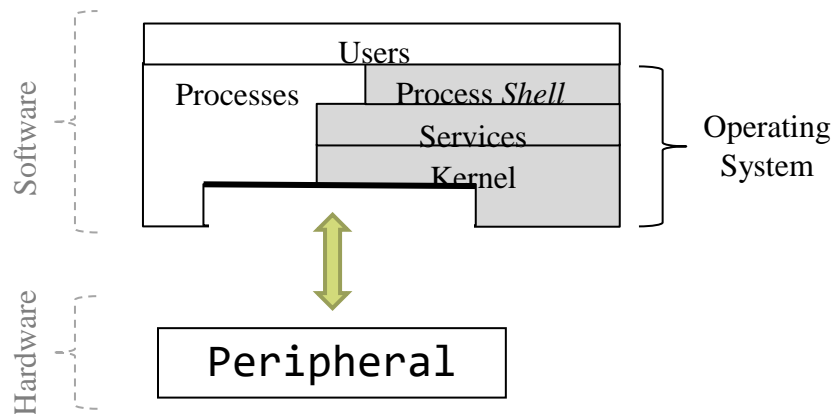
To remember...

1. To prepare and review the class explanations.
 - ▶ Study the bibliography material: only slides are not enough.
 - ▶ Ask your doubts.
1. To exercise skills and abilities.
 - ▶ Solve as much exercises as possible.
 - ▶ Perform the guided laboratories progressively.
 - ▶ Build laboratories progressively.

General context...



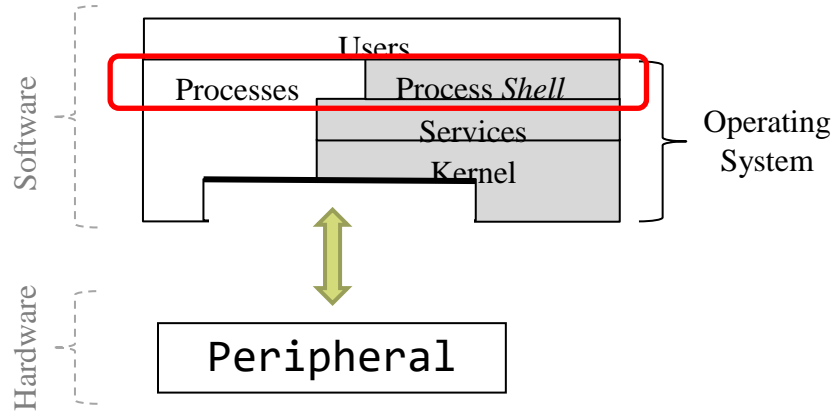
Overview



▶ Processes

▶ Peripheral

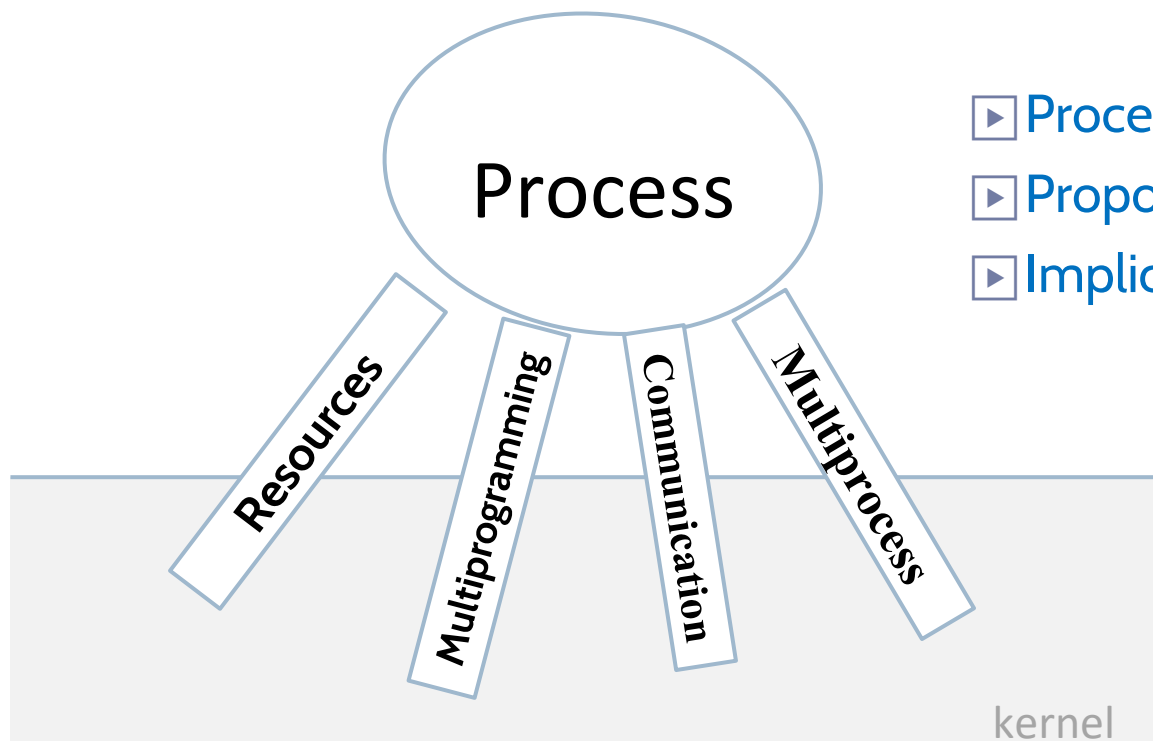
Overview



▶ **Processes**

▶ **Peripheral**

Introduction



- ▶ Process concept
- ▶ Proposed model
- ▶ Implications in the O.S.

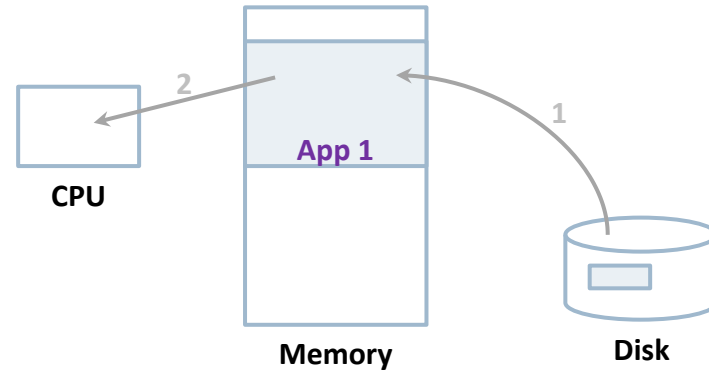
Introduction



Process

▶ **Process concept**

Process concept



▶ Process

- ▶ Programm in execution

- ▶ Processing unit managed by the Operating System (O.S.)

Introduction

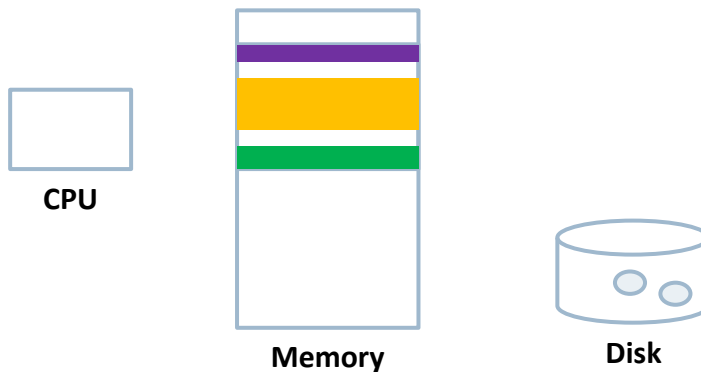


▶ **Process concept**

▶ **Proposed model**

Proposed model

- **resource**
- multiprogramming
 - isolation/sharing
 - process hierarchy
- multitasking
- multiprocess



▶ Associated resources

▶ Areas of memory

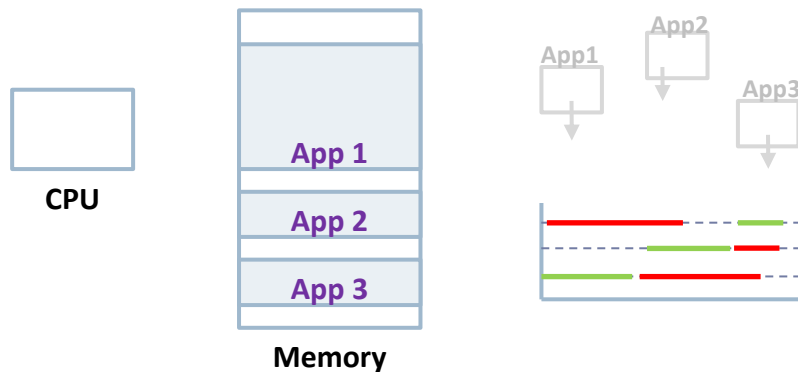
▶ At least: **code**, **data**, and stack

▶ Open files

▶ Signals

Proposed model

- resource
- **multiprogramming**
 - isolation/sharing
 - process hierarchy
- multitasking
- multiprocess

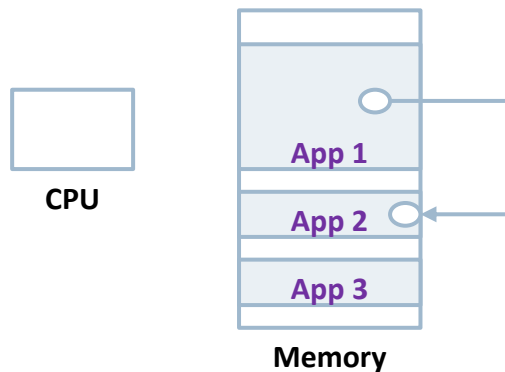


▶ Multiprogramming

- ▶ Several applications loaded in main memory
- ▶ If one blocks because request some slow I/O then another is executed until this new one get blocket too
 - ▶ Voluntary Context Switching (V.C.S.)
- ▶ Efficiency in the use of the processor.
- ▶ Degree of multiprogramming = number of applications loaded in main memory

Proposed model

- resource
- multiprogramming
 - **isolation/sharing**
 - process hierarchy
- multitasking
- multiprocess

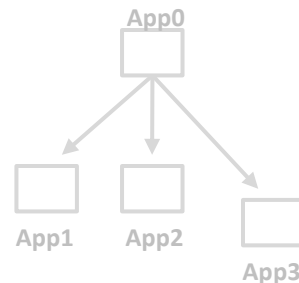
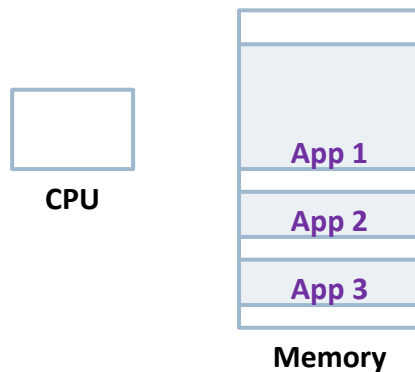


▶ Isolation / Sharing

- ▶ Private address space per application, but
- ▶ Possibility of communicating data between two applications
 - ▶ Message passing
 - ▶ Sharing memory

Proposed model

- resource
- multiprogramming
 - isolation/sharing
 - **process hierarchy**
- multitasking
- multiprocess



▶ Process hierarchy

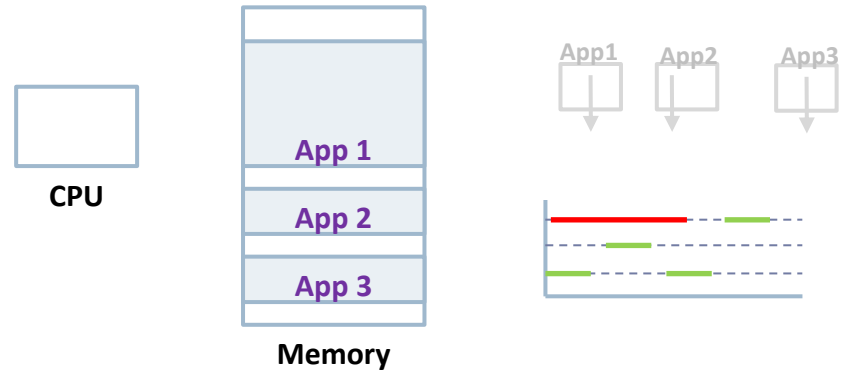
▶ Create process

- ▶ As a copy of another existing process
- ▶ From an application on disk
- ▶ As boot process

▶ Group of processes that share the same treatment

Proposed model

- resource
- multiprogramming
 - isolation/sharing
 - process hierarchy
- multitasking**
- multiprocess

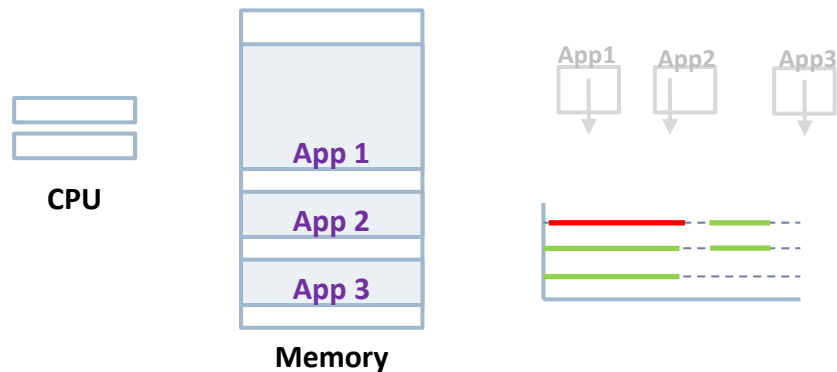


▶ Multitasking

- ▶ Each process is executed a quantum of time (E.g .: 5 ms), and the turn is rotated to execute another ready processes
 - ▶ Involuntary Context Switching (I.C.S.)
- ▶ Sharing the use of the processor
 - ▶ It seems that everything is running at the same time

Proposed model

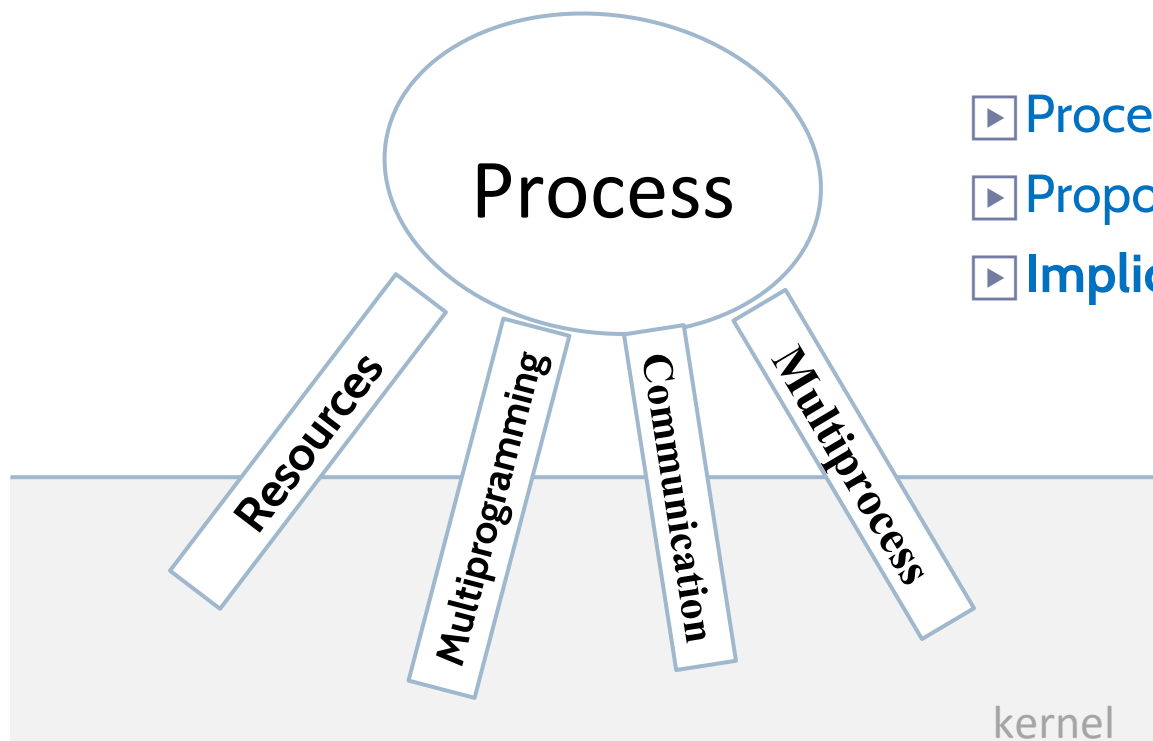
- resource
- multiprogramming
 - isolation/sharing
 - process hierarchy
- multitasking
- multiprocess**



► Multiprocess

- Several processors are available (multicore / multiprocessor)
- In addition to the distribution of each CPU (multitasking), there is real parallelism between several tasks (as many as processors)
 - It usually uses a scheduler and data structures per processor, with some load balancing mechanism

Introduction



- ▶ **Process concept**
- ▶ **Proposed model**
- ▶ **Implications in the O.S.**

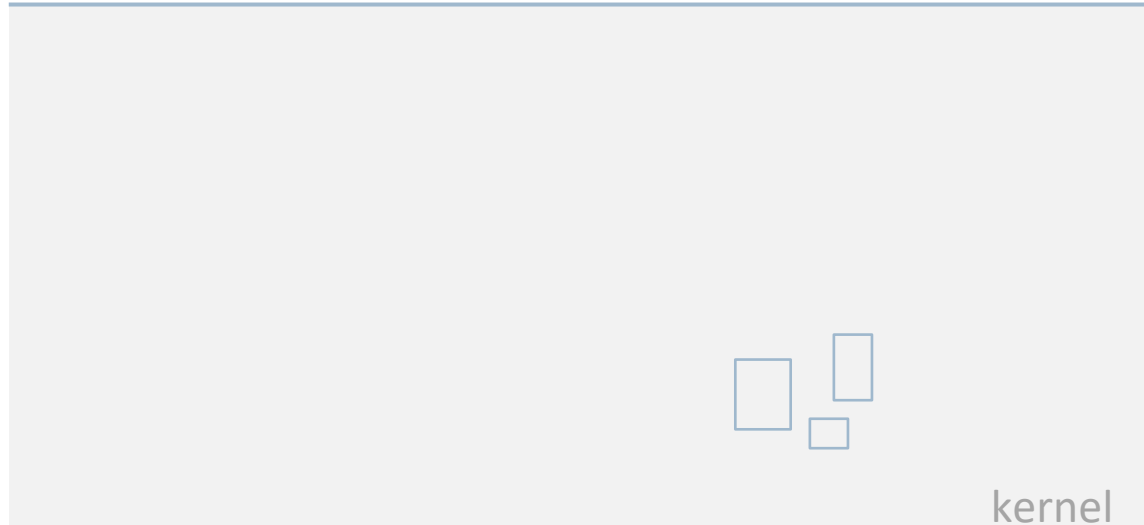
Implications in the operating system

1. Data structures

Requirements	Information (in data structures)
Resources	<ul style="list-style-type: none">• Areas of memory (code, data and stack)• Open files• Activated signals
Multiprogramming	<ul style="list-style-type: none">• Execution state• Context: CPU registers...• Process list
○ Insolation / Sharing	<ul style="list-style-type: none">• Message passing<ul style="list-style-type: none">• Cola de mensajes de recepción• Memory compartida<ul style="list-style-type: none">• Zones, locks and conditions
○ Hierarchy of processes	<ul style="list-style-type: none">• Family relationship• Related sets of processes• Processes from the same session
Multitasking	<ul style="list-style-type: none">• Quantum restante• Priority
Multiprocess	<ul style="list-style-type: none">• Affinity

Implications in the operating system

1. Data structures



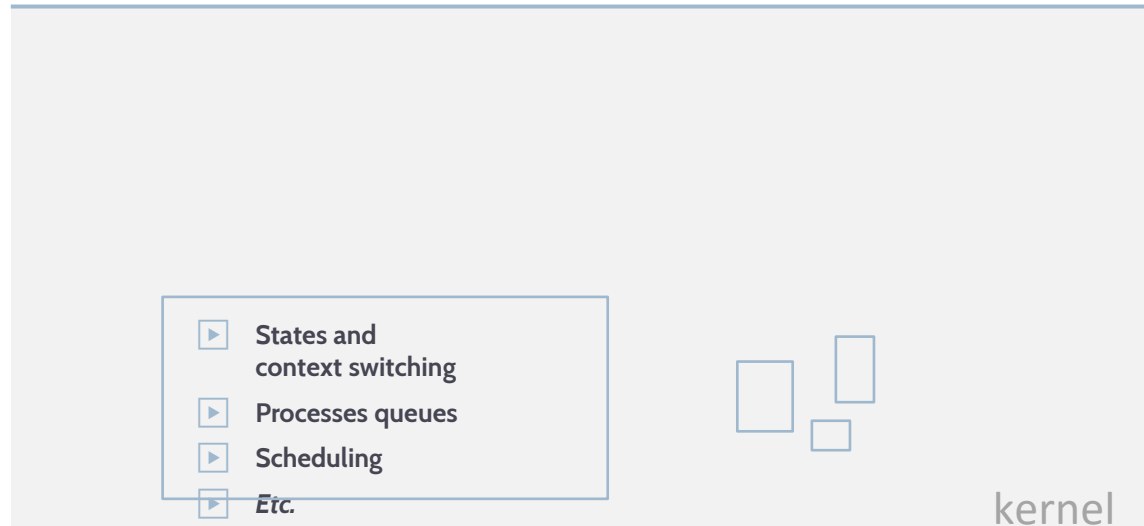
Implications in the operating system

2. Functions: internal management

Requirements	Information (in data structures)	Functions (Internals, services, and API)
Resources	<ul style="list-style-type: none">• Areas of memory (code, data and stack)• Open files• Activated signals	<ul style="list-style-type: none">• Several internal functions• Several service function for memory, files, etc.
Multiprogramming	<ul style="list-style-type: none">• Execution state• Context: CPU registers...• Process list	<ul style="list-style-type: none">• Hw./Sw. int. from devices• Scheduler• Create/Destroy/Schedule process
○ Insolation / Sharing	<ul style="list-style-type: none">• Message passing<ul style="list-style-type: none">• Cola de mensajes de recepción• Memory compartida<ul style="list-style-type: none">• Zones, locks and conditions	<ul style="list-style-type: none">• Send/Receive message and management of the message queue• API for concurrency control (access to data structures)
○ Hierarchy of processes	<ul style="list-style-type: none">• Family relationship• Related sets of processes• Processes from the same session	<ul style="list-style-type: none">• Clonar/Cambiar imagen de proceso• Associate process and leader selection
Multitasking	<ul style="list-style-type: none">• Quantum restante• Priority	<ul style="list-style-type: none">• Hw./Sw. int. from clock device• Scheduler• Create/Destroy/Schedule process
Multiprocess	<ul style="list-style-type: none">• Affinity	<ul style="list-style-type: none">• Hw./Sw. int. from clock device• Scheduler• Create/Destroy/Schedule process

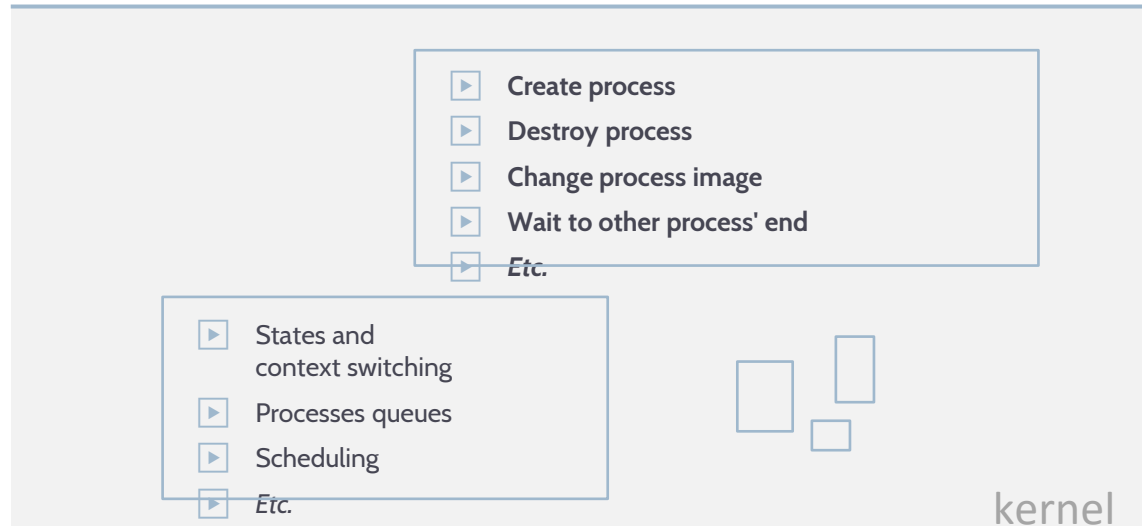
Implications in the operating system

2. Functions: internal management



Implications in the operating system

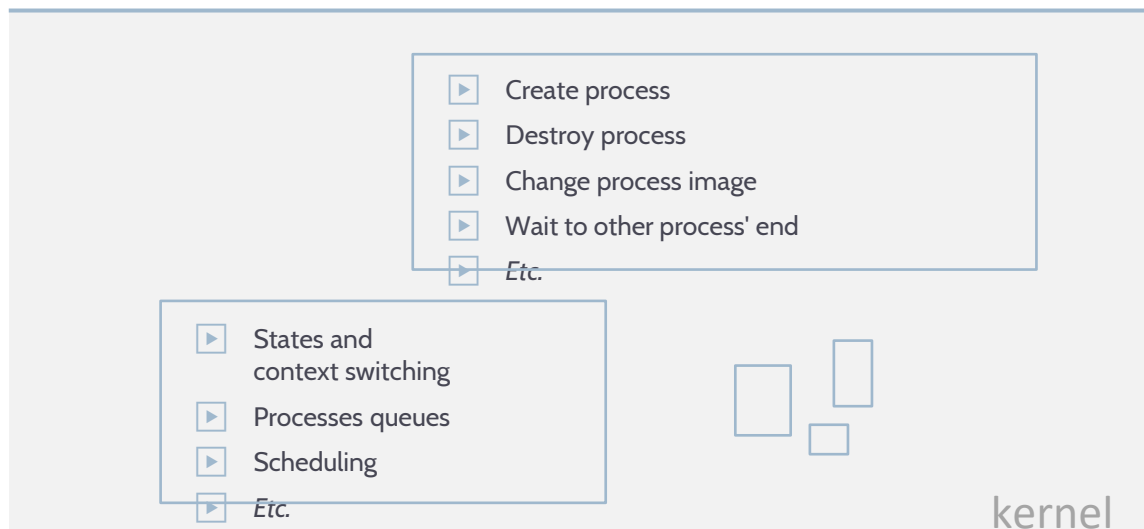
3. Functions: services



Implications in the operating system

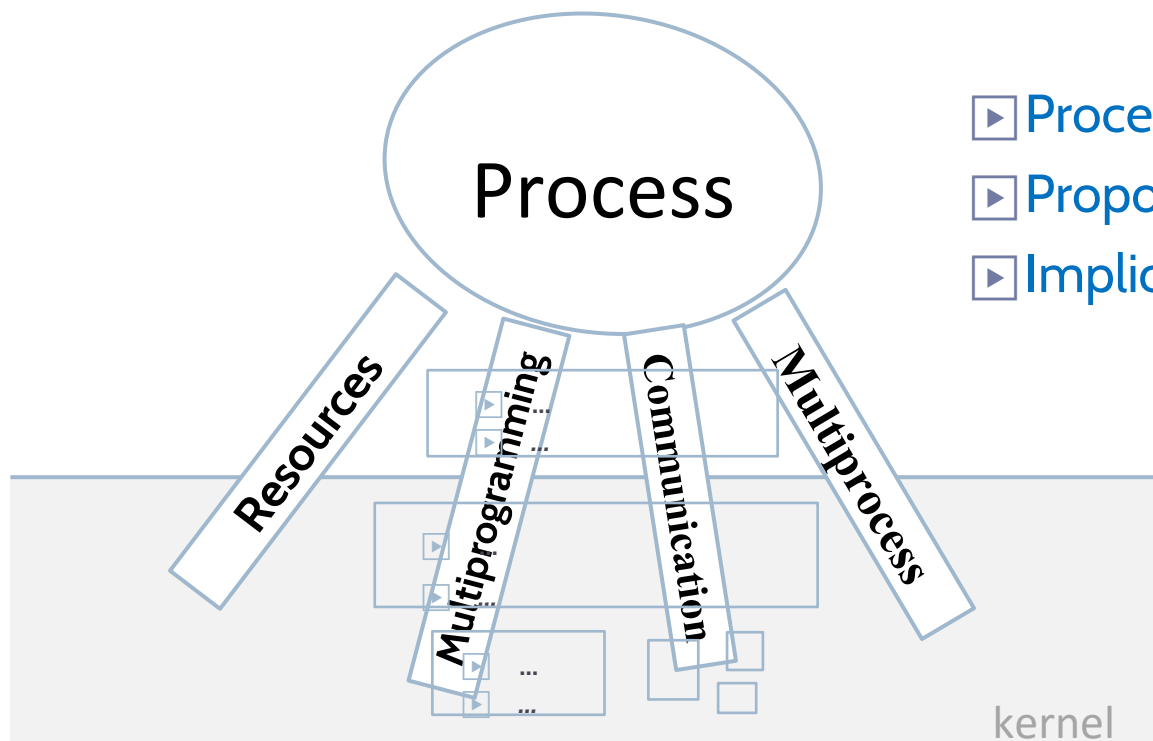
3. Functions: service API

- ▶ fork, exit, exec, wait, ...
- ▶ *pthread_create, pthread...*



Introduction

summary

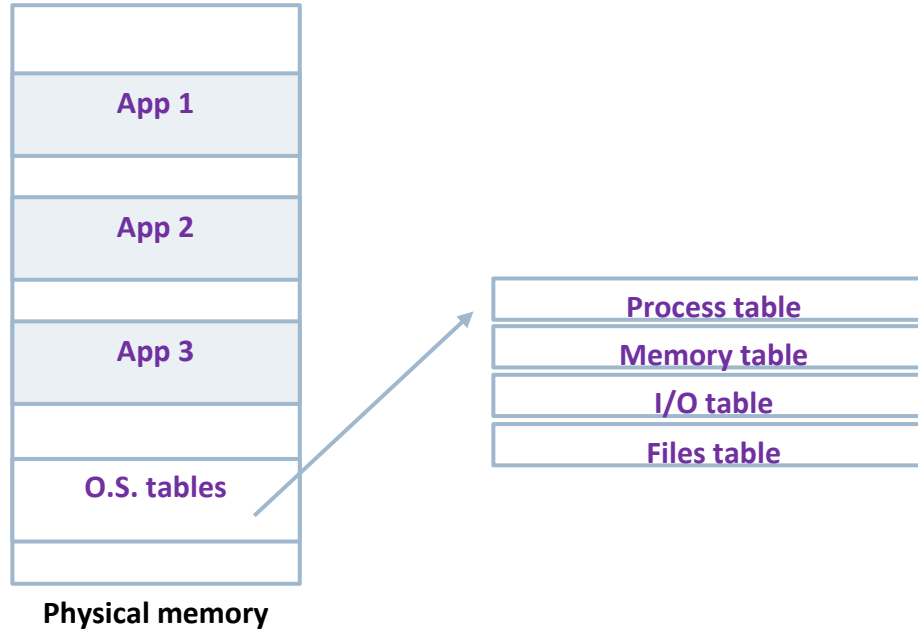


- ▶ Process concept
- ▶ Proposed model
- ▶ Implications in the O.S.

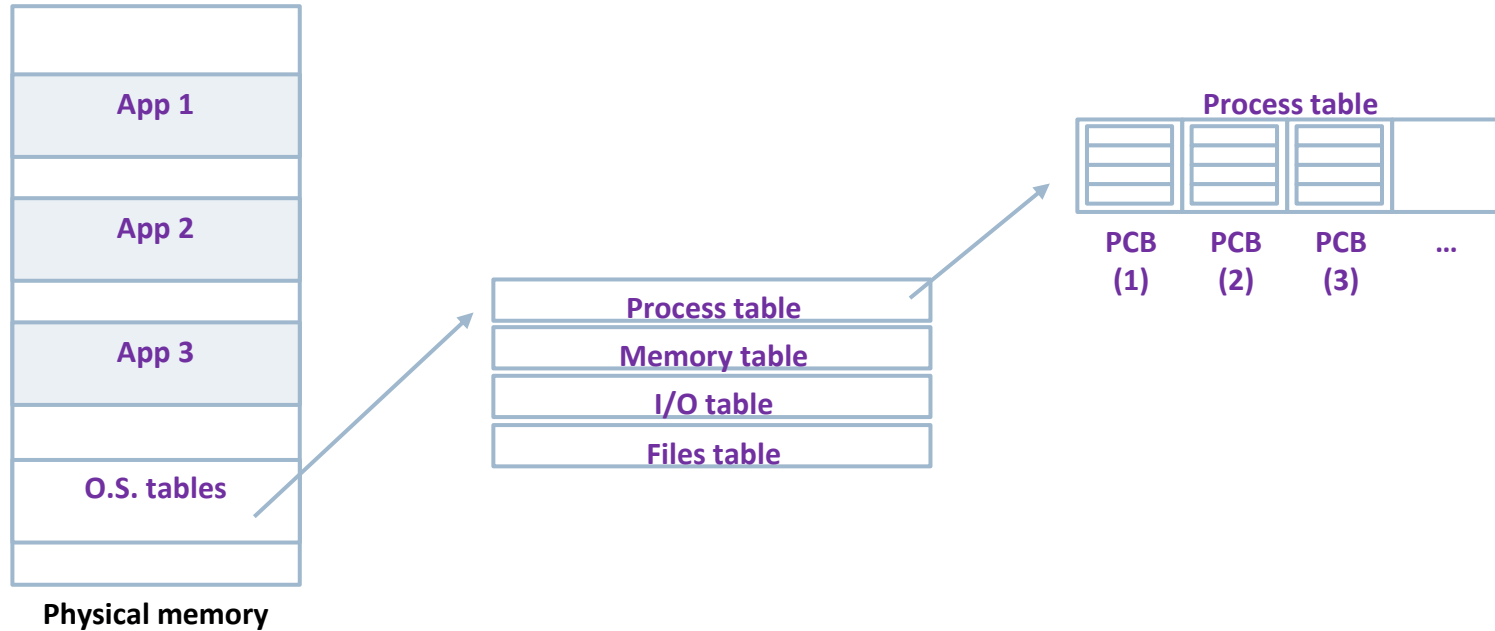
Main data structures



Information in the operating system



Information associated with a process



PCB: Process Table unit

▶ Process management

State

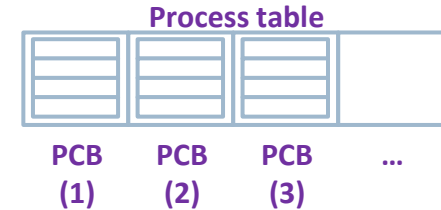
- ▶ General purpose registers
- ▶ Program counter
- ▶ State register
- ▶ Stack pointer

Id.

- ▶ Process identification
- ▶ Father process
- ▶ Process group

Mgmr.

- ▶ Priority
- ▶ Scheduler params
- ▶ Signals
- ▶ Timestamp when execution started
- ▶ Time of CPU used
- ▶ Time to next alarm



▶ *Process Control Block* (PCB / PCB)

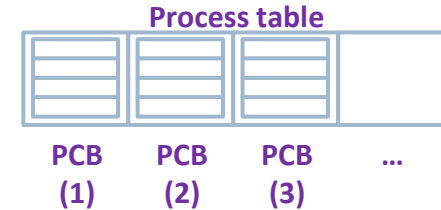
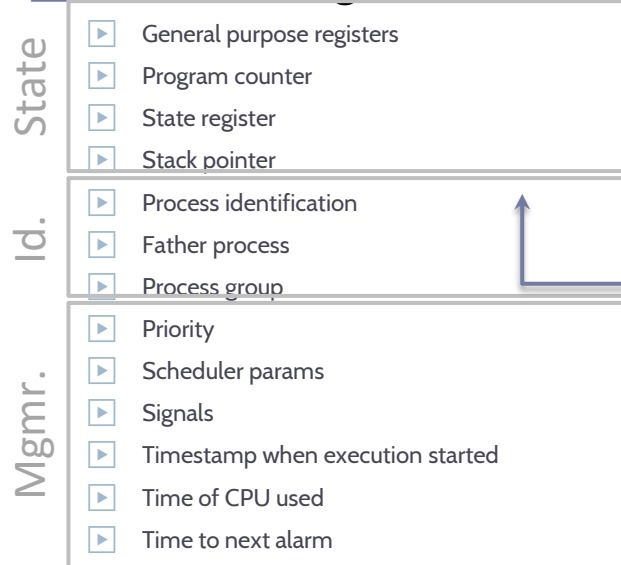
- ▶ Data structure with all related information needed for the management of a particular process
- ▶ Manifestation of a process in the kernel

▶ *Thread Control Block* (TCB / BCT)

- ▶ Similar to PCB for each thread in the process

PCB: Process Table unit

▶ Process management



▶ *Process Identification* (PID)

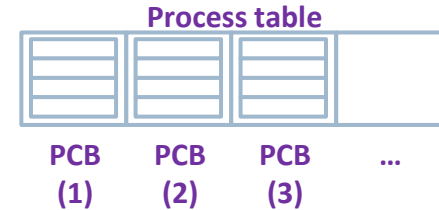
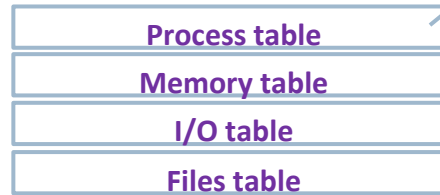
- ▶ Identification used by users
- ▶ Use to be a positive number of 16 bits (32767) dynamically assigned, reused not immediately

▶ *Address of process descriptor* (APD)

- ▶ Identification within the kernel
- ▶ Use to be a translation PID -> APD (E.g.: hash)

Where?: information of a process

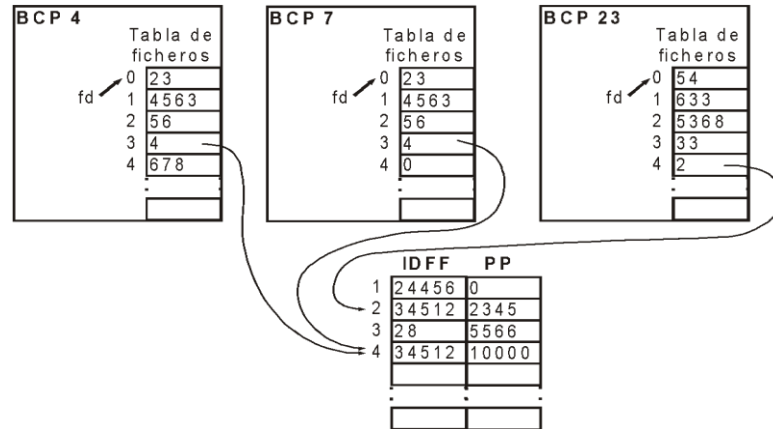
- ▶ The information of a process is on its PCB...
- ▶ But some information is outside PCB:
 - ▶ Because better efficiency
 - ▶ In order to share information among processes



- ▶ Examples:
 - ▶ Table of **memory** segments and pages
 - ▶ Table of **file placeholder**
 - ▶ List of requests to **devices**

Where?: information of a process

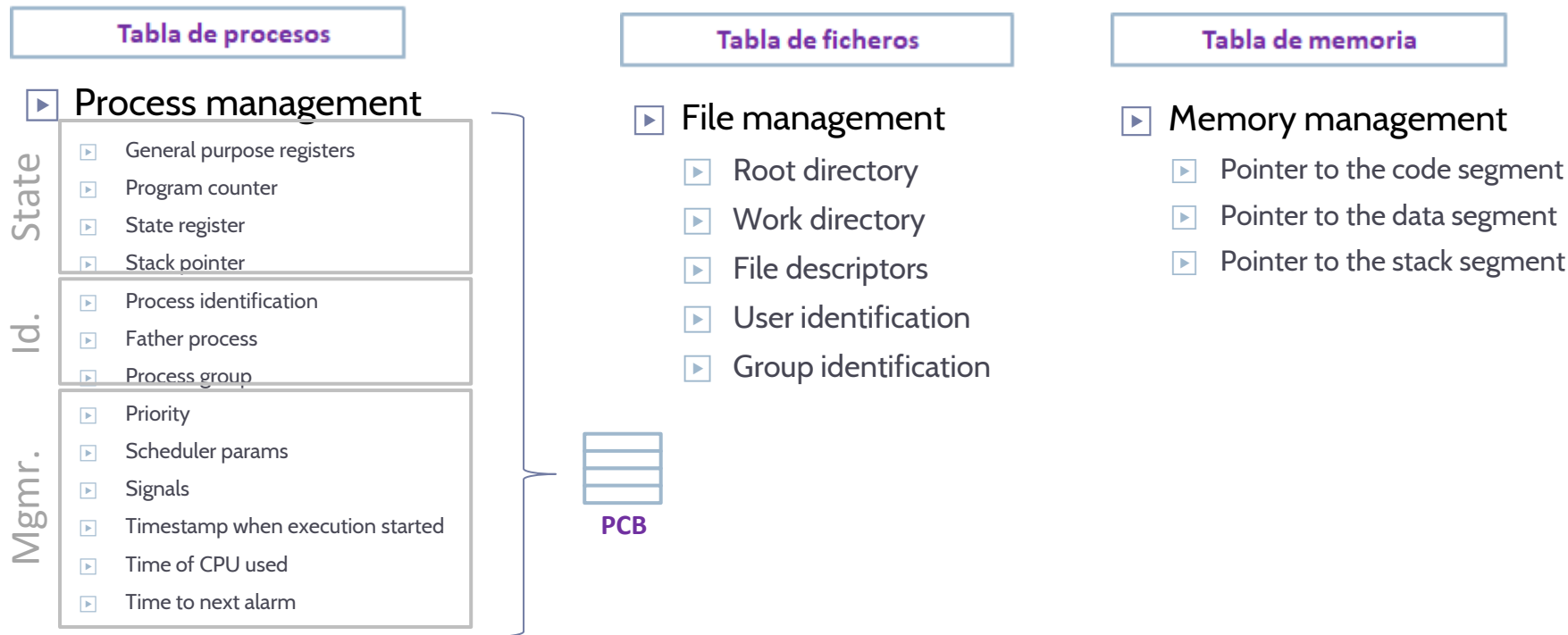
▶ Table of file position pointer (seek pointer):



- ▶ Describe the read/write position of open files.
- ▶ In order to share the state of the file among process, this part has to be external to PCB.
- ▶ The PCB contains the index of the element in the table that contains the information of the open file: the i-node, and the seek position.

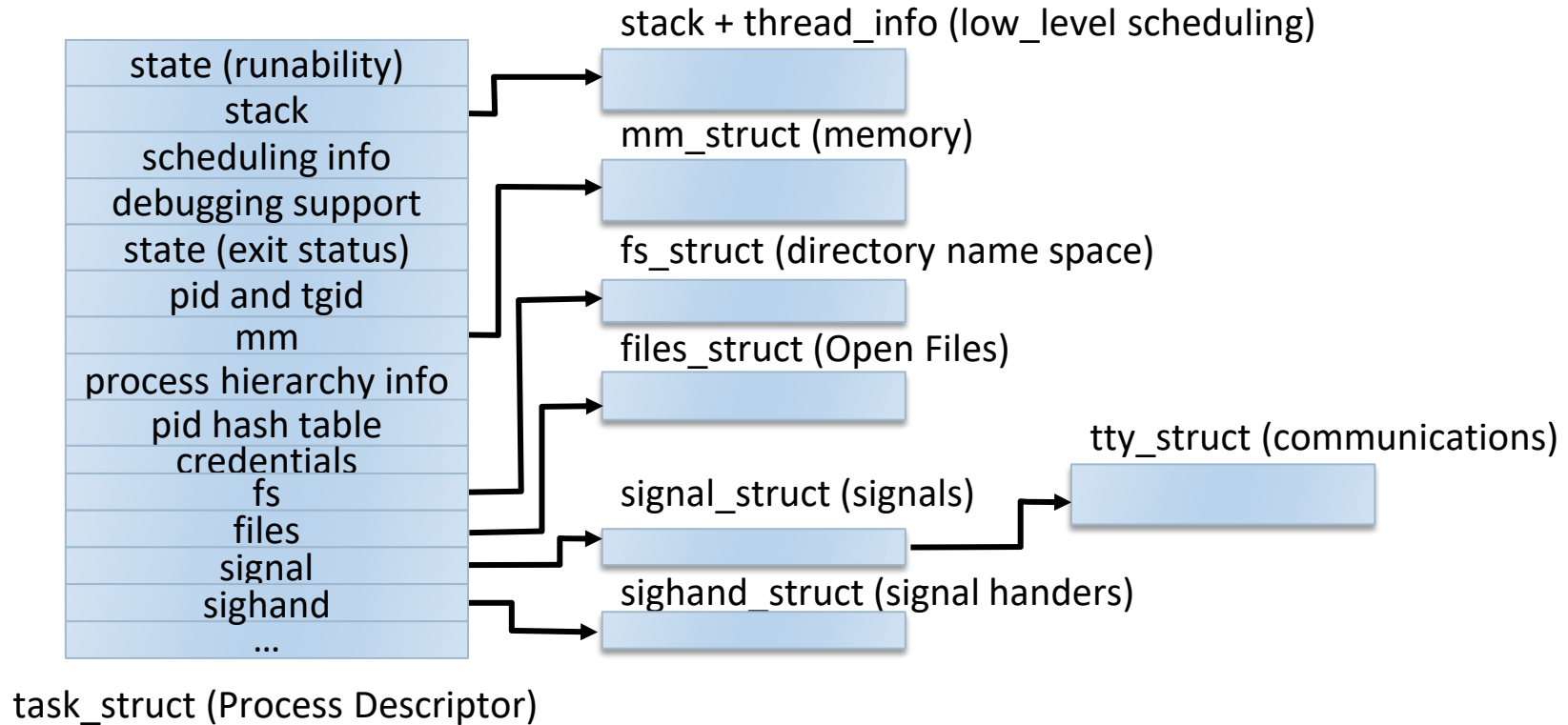
Process information

summary



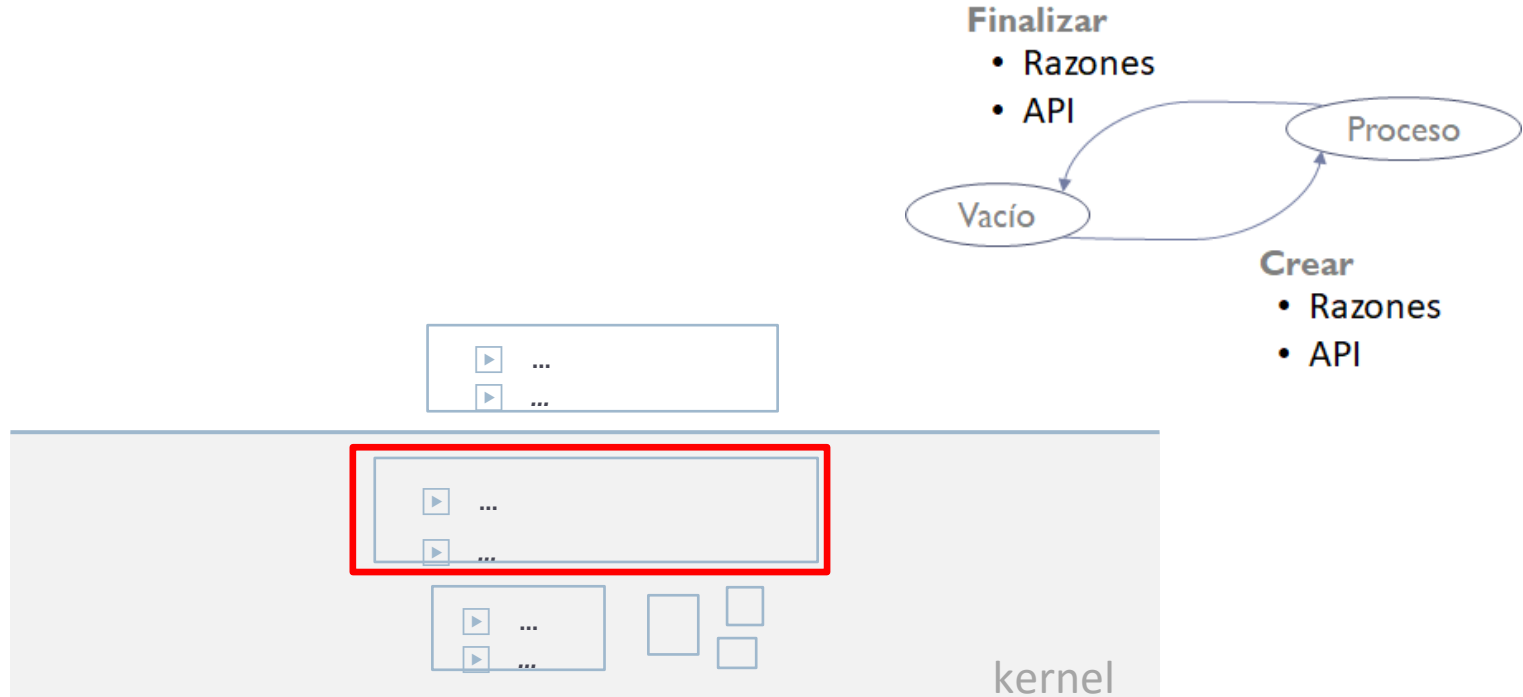
Information of a process

Linux



Operating System Services

Initialization and completion of processes.



Create process

- ▶ A process is created:

- ▶ During system boot

- ▶ Kernel threads + first process (E.g.: init, swapper, etc.)

- ▶ When one process performs a system call to create another process:

- ▶ When the operating system starts a new work

- ▶ When an user starts a new application

- ▶ When an running application needs a new process

Destroy a process

▶ A process ends:

▶ In a voluntary way:

- ▶ Normal ending
- ▶ Ending by error

▶ In a non-voluntary way:

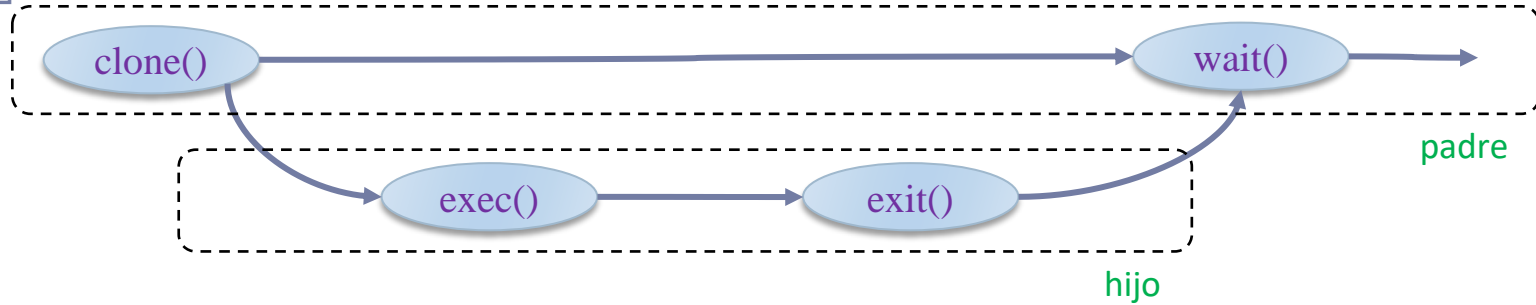
- ▶ End by system (E.g.: exception, no available resources, etc.)
- ▶ End by another process (E.g.: through a 'kill' system call)
- ▶ End by user (E.g.: press Ctrl-C in the keyboard)

- ▶ In Unix/Linux signals are used as mechanism
- ▶ Signals can be captured and handled (but SIGKILL) to avoid some non-voluntary ways of ending

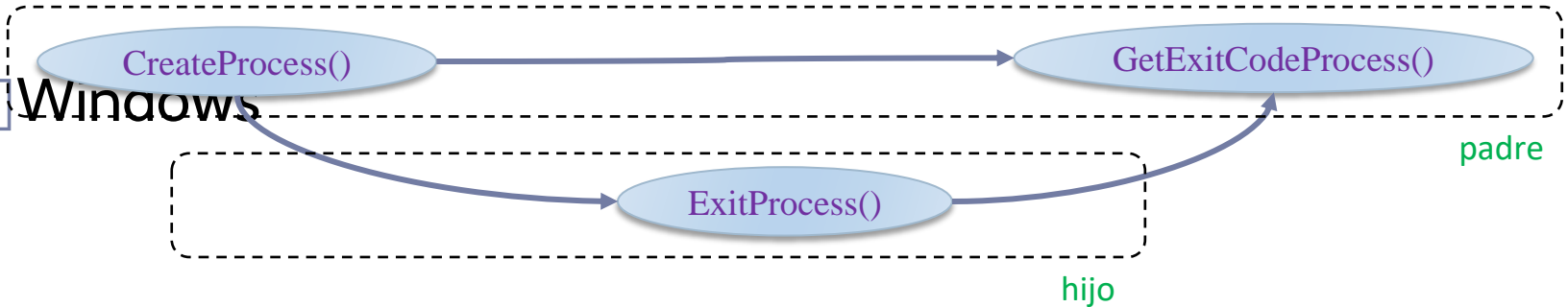
Creation and termination of processes

System calls

Linux

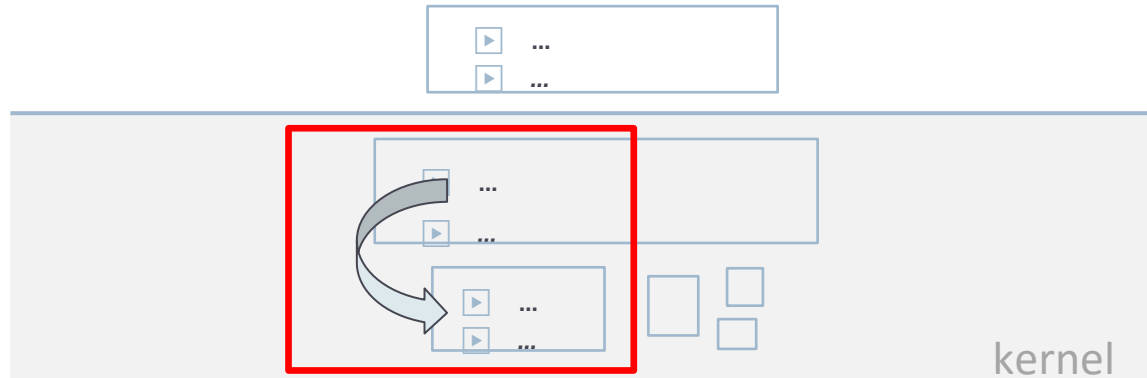


Windows



Operating System Services

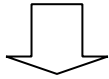
Initialization and completion of processes.



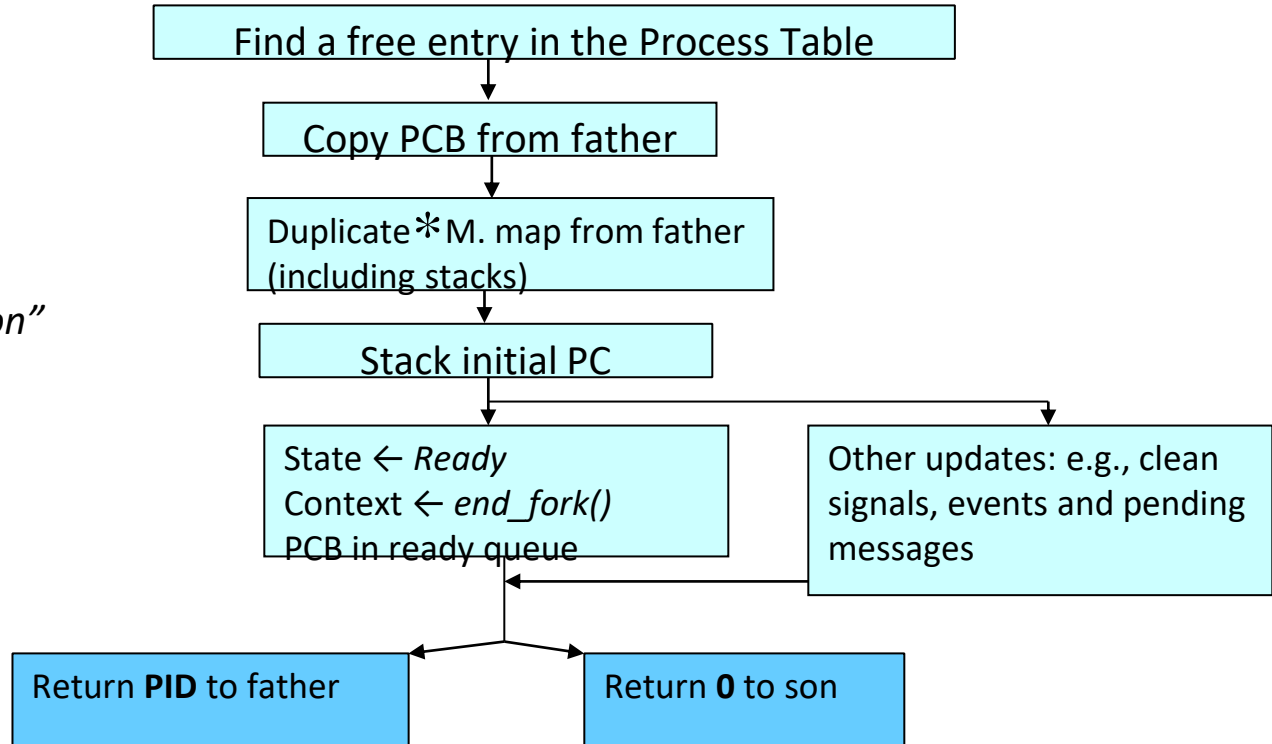
Create process

Linux: clone

clone:



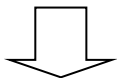
“Clone the father process and gives a new identity to the son”



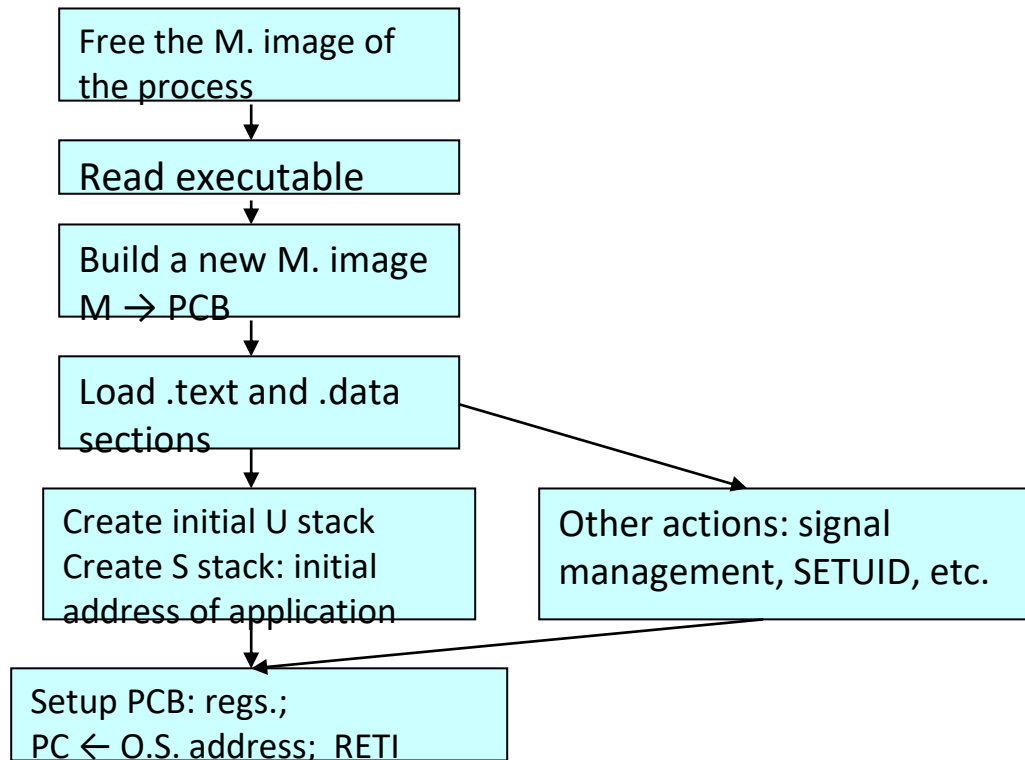
Change process image

Linux: exec

exec:



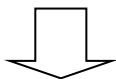
“Change the memory image of a process using as a previous one as ‘container’”



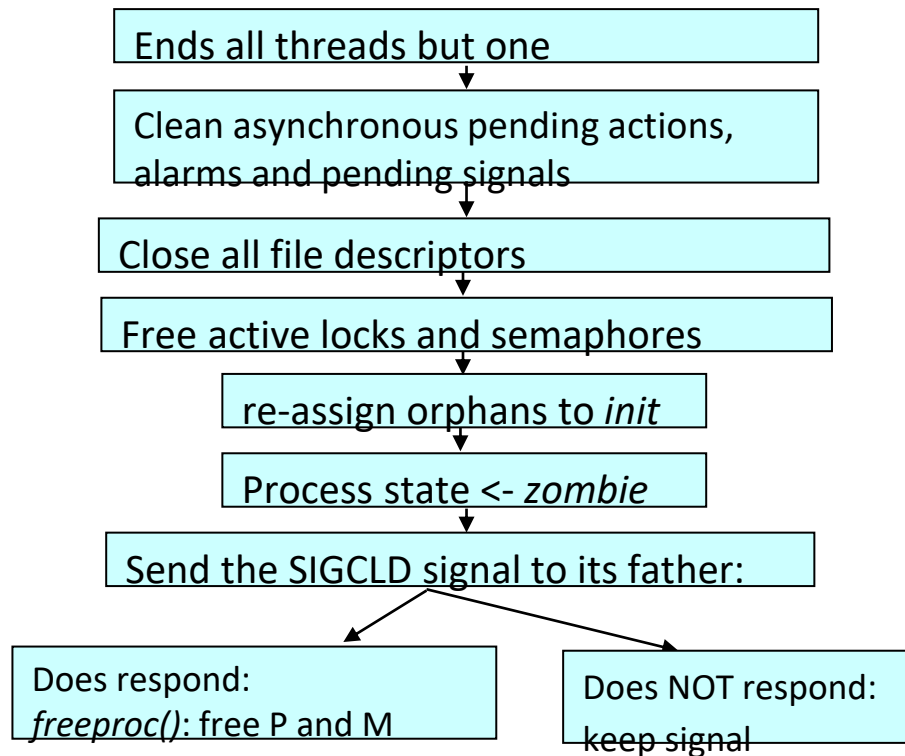
Destroy process

Linux: `exit`

`exit:`

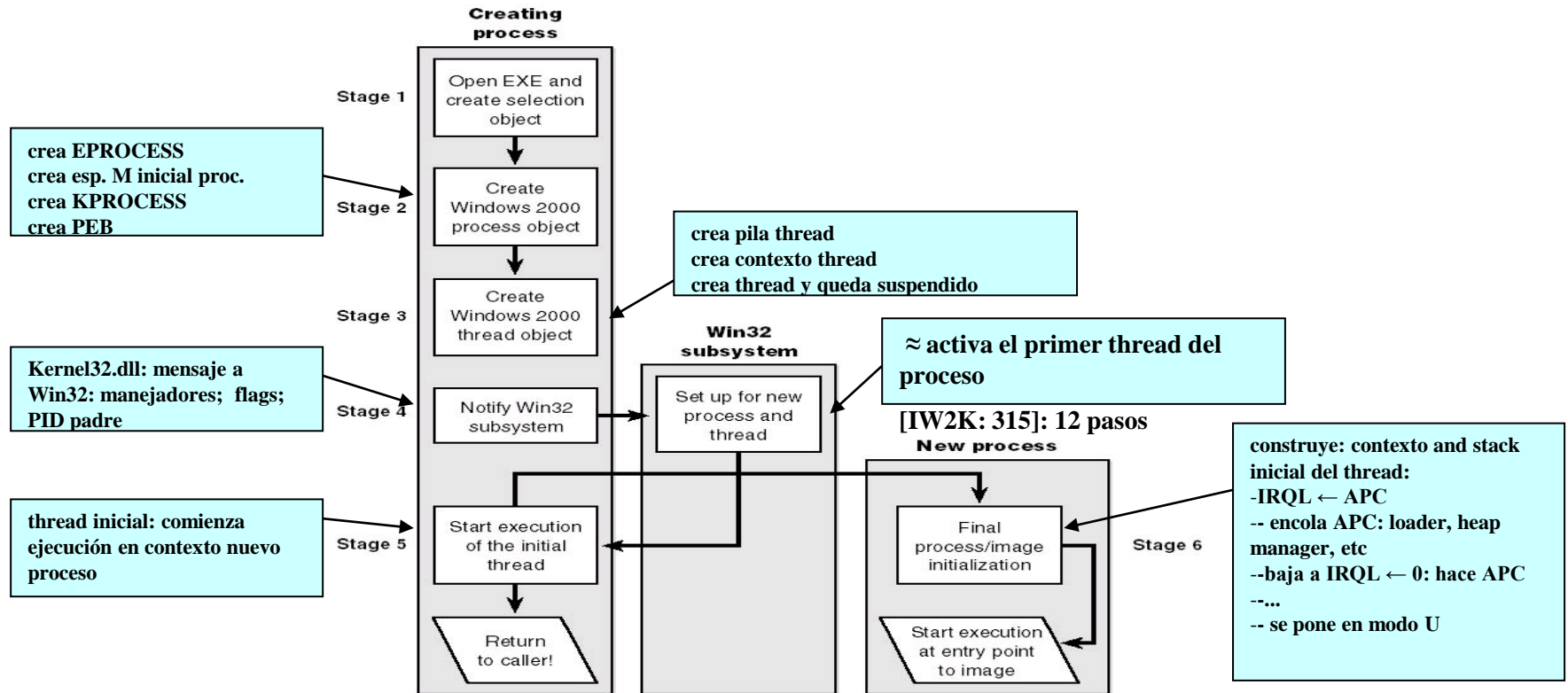


“It ends the execution of a process and release its associated resources”

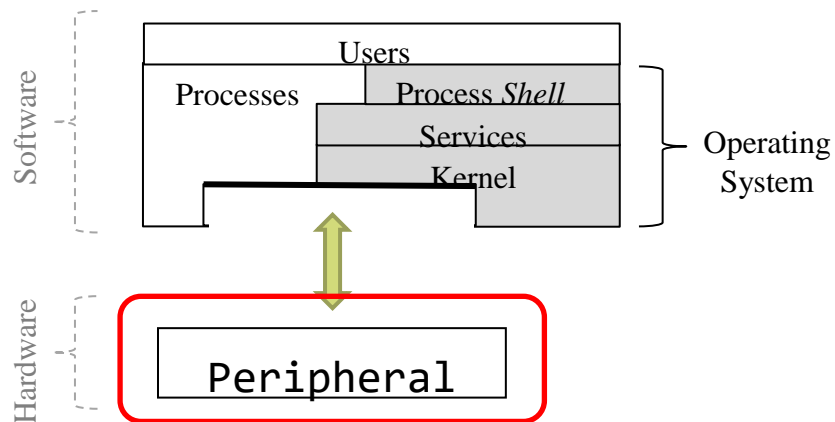


Create process

Windows: CreateProcess



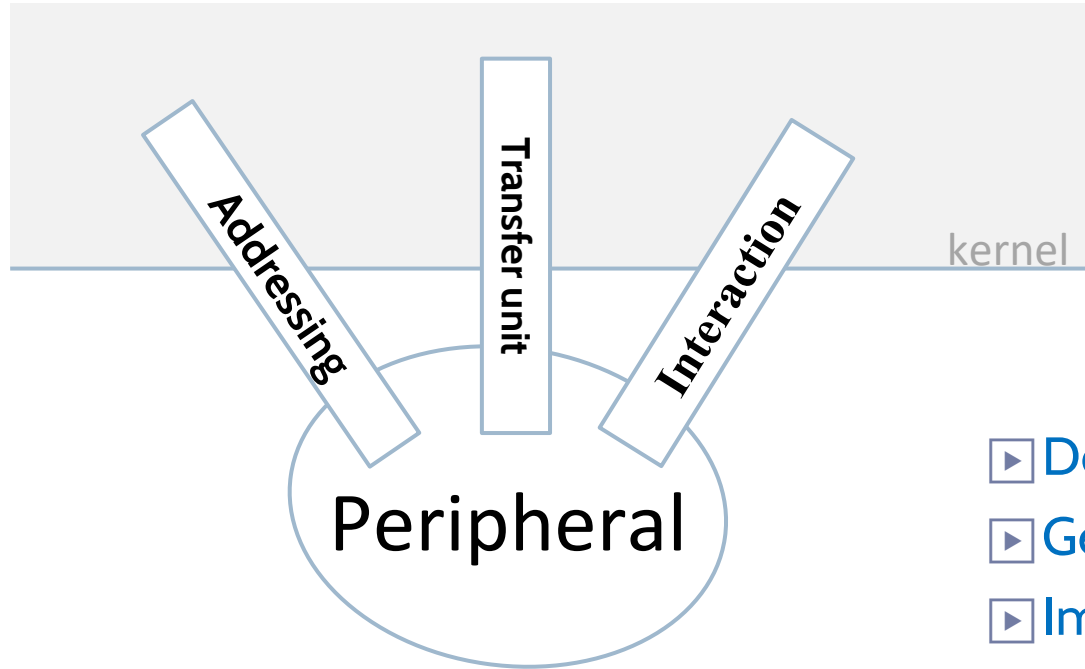
Overview



▶ Processes

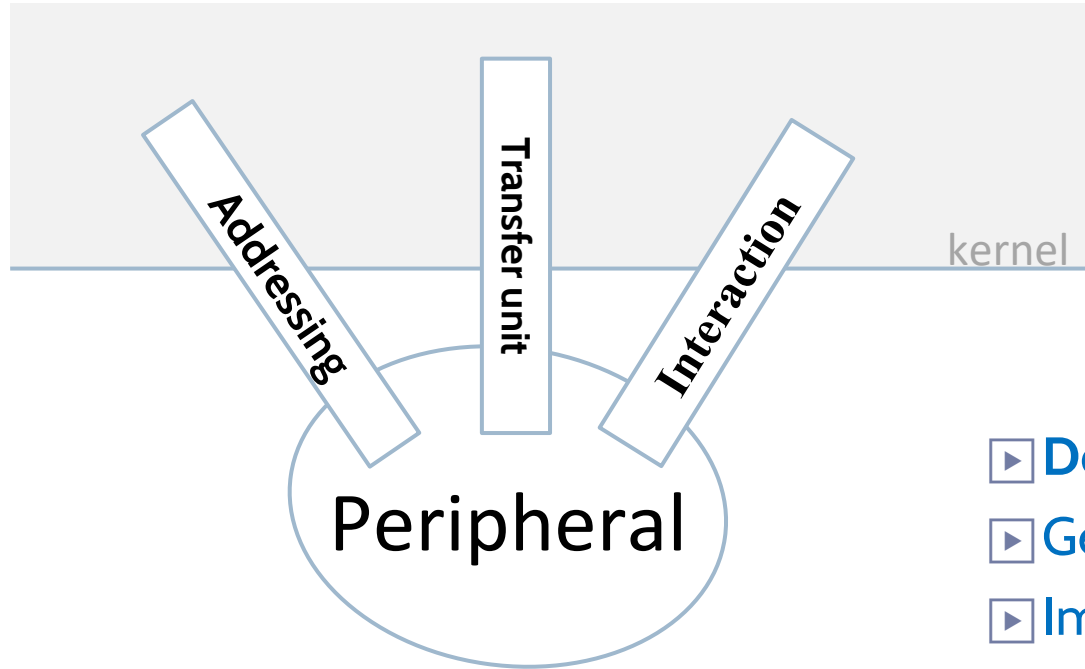
▶ Peripheral

Introduction



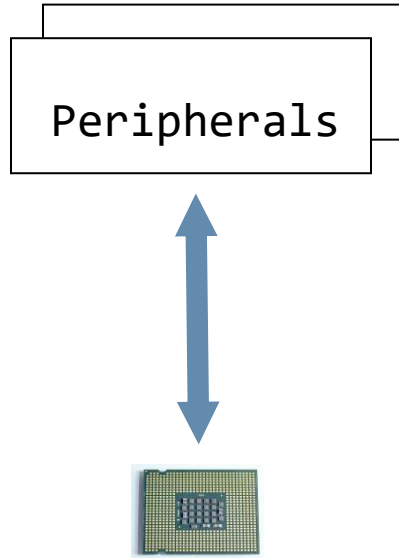
- ▶ Definition of Peripheral
- ▶ General structure
- ▶ Implications in the O.S.

Introduction



- ▶ **Definition of Peripheral**
- ▶ **General structure**
- ▶ **Implications in the O.S.**

Concept of peripheral



▶ Peripheral:

- ▶ All external element connected to a CPU through the Input/Output (I/O) modules.
- ▶ They let store information or communicate the computer with the exterior world.

Peripheral classification (by usage)



▶ Communication:

▶ Human - machine

- (Terminal) keyboard, mouse, ...
- (Printed) plotter, scanner, ...

▶ Machine - machine (Módem, ...)

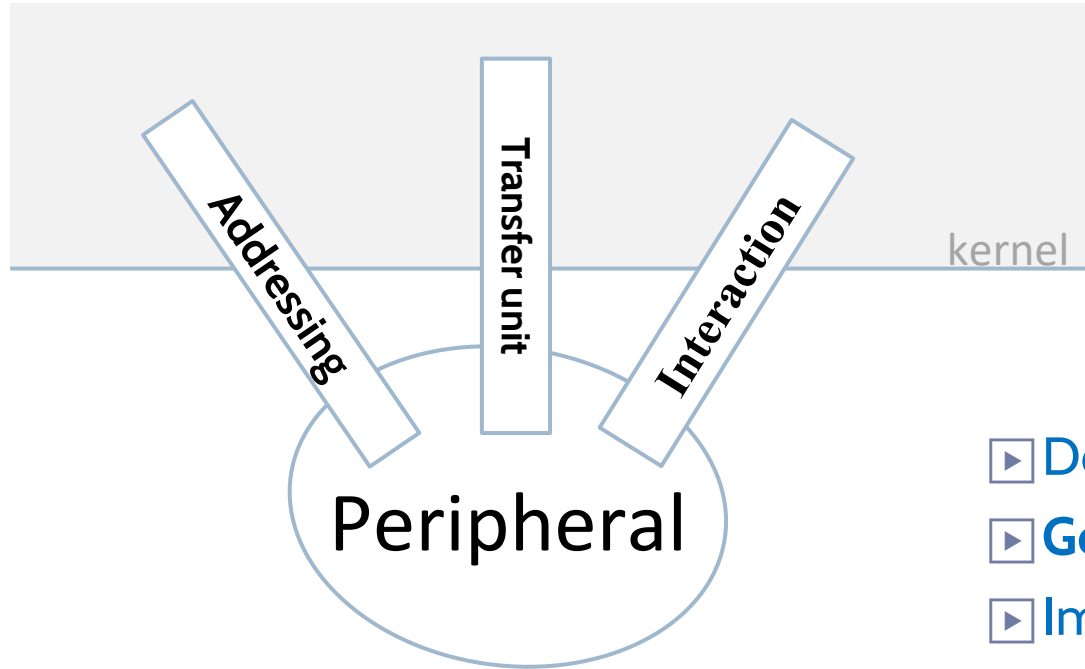
▶ Physical environment - machine

- (Read/accionamiento) x (analogic/digital)

▶ Storage:

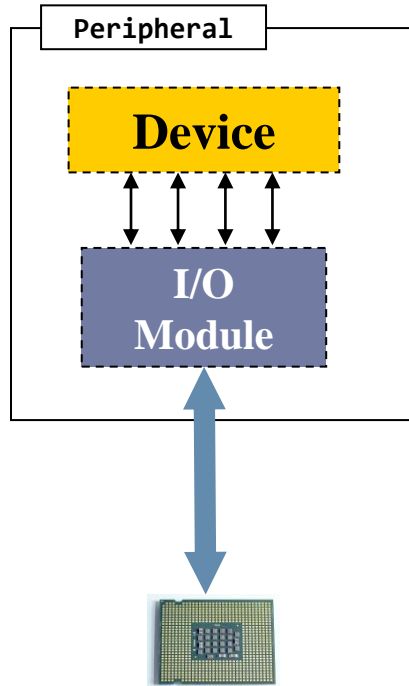
- ▶ Direct access (Disks, DVD, ...)
- ▶ Sequential access (Tapes)

Introduction



- ▶ Definition of Peripheral
- ▶ General structure
- ▶ Implications in the O.S.

General structure of a peripheral



▶ Compound of:

▶ **Device**

▶ Hardware that interacts with the environment

▶ **I/O module**

▶ Also known as **controller**

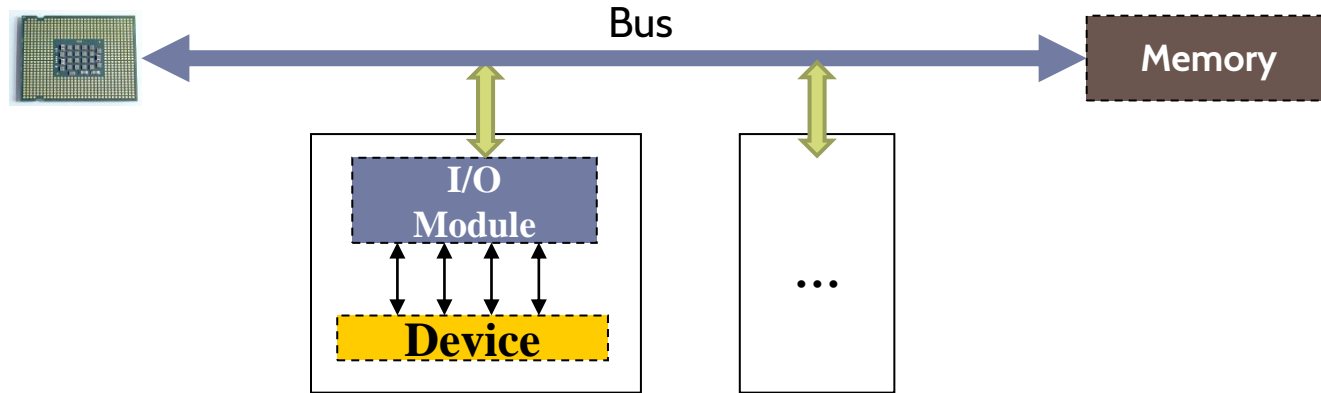
▶ Interface between the device and the CPU, which hides the particularities of this

Peripheral = Device + I/O module

I/O module

What are they

- ▶ The **I/O module** makes the connection between the CPU and the device.



I/O module necessity

▶ There are necessary because:

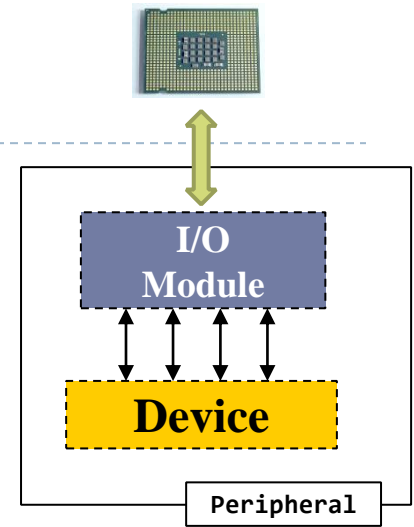
▶ Many types peripherals.

▶ Peripherals use to be 'weird'

▶ The data transfer speed of the peripherals use to be smaller than memory or processor (CPU).

▶ Peripherals use to be 'slower'

▶ Data formats and data sizes from the peripherals could be different to the ones used in the computer that are connected.



I/O module

structure: interface

Interaction between CPU and I/O Module through:

▶ **3 types** of registers:

▶ **Control** register

- ▶ Request for the peripheral

▶ **State** register

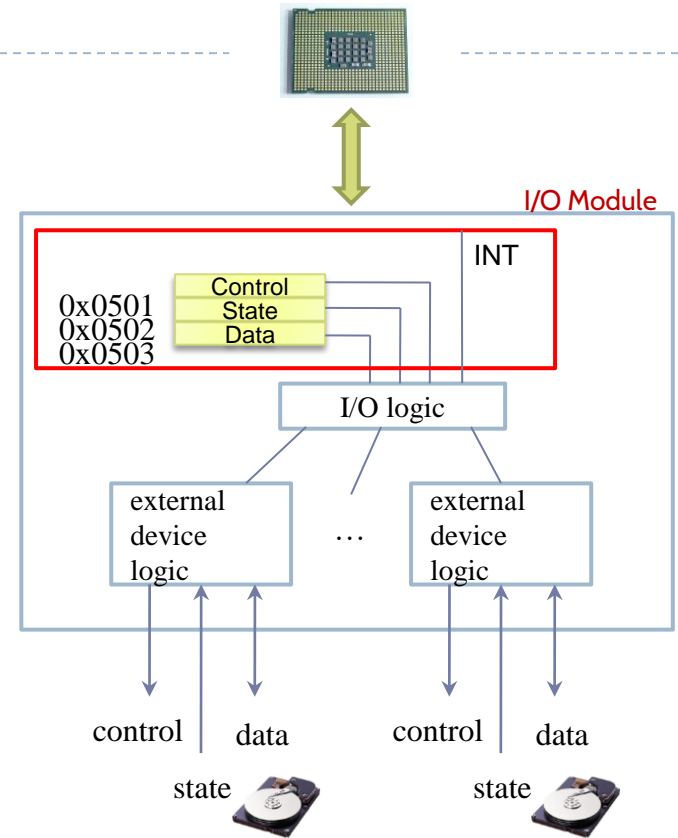
- ▶ Result of the last request performed

▶ **Data** register

- ▶ Interchange data between CPU/peripheral

▶ **1 type** of interrupt line:

▶ **Notification** interrupt



I/O module

characteristics to know

► Important aspects:

► Addressing:

- Memory-mapped, Port-mapped

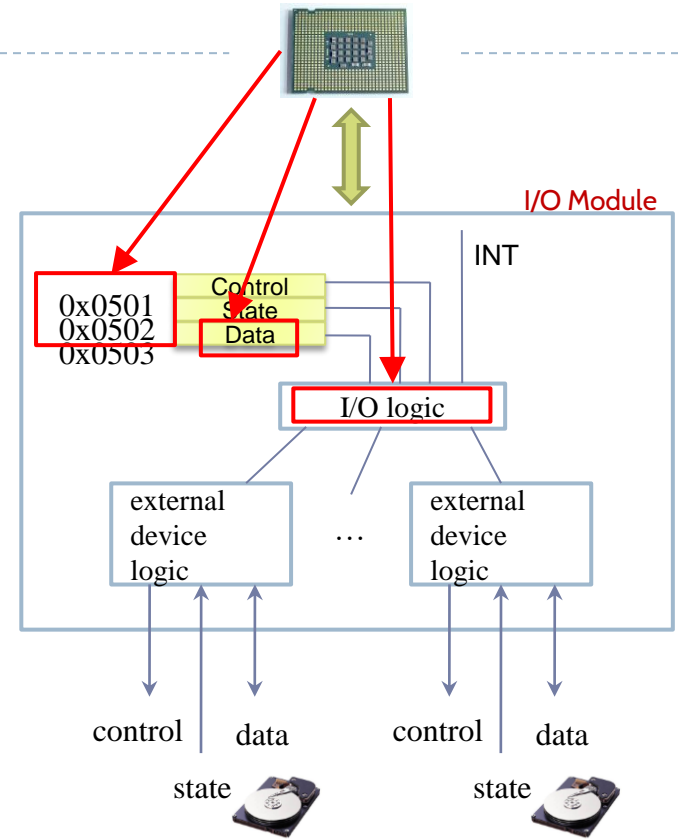
► Transfer unit:

- Character, block

► Interaction

computador-controlador:

- Direct, Interrupted, DMA



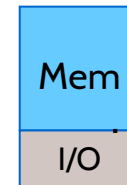
(1 / 3) Addressing Module

0x0501	Control
0x0502	State
0x0503	Data

▶ Memory-mapped I/O

- ▶ The I/O module registers are 'projected' into the main memory space and a memory area is used to associate address to I/O module + register of this module.

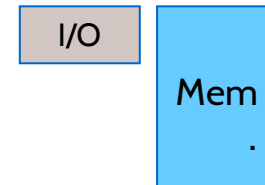
▶ E.g.: `int * rctrl = 0x105A ;`
`(*rctrl) = 1 ;`



▶ Port-mapped I/O

- ▶ With special assembler instructions (In / Out) you access the I/O module registers as special addresses (called ports).

▶ E.g.: `out(0x105A, 1) ;`



(2/3) Transfer unit

0x0501
0x0502
0x0503

Control
State
Data

▶ Block device:

- ▶ Unit: blocks of bytes
- ▶ Access: sequential or direct
- ▶ Actions: read, write, situarase, ...
- ▶ Examples: tapes and disk

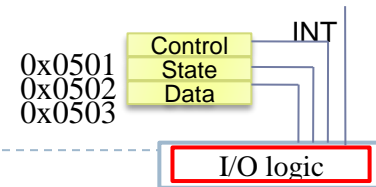


▶ Character device:

- ▶ Unit: characters (ASCII, Unicode, etc.)
- ▶ Access: sequential
- ▶ Actions: get, put,
- ▶ Example: terminals, printers, etc.



(3/3) Interaction with computer



▶ Direct I/O

▶ CPU does all I/O: busy wait → transfer

'polling'

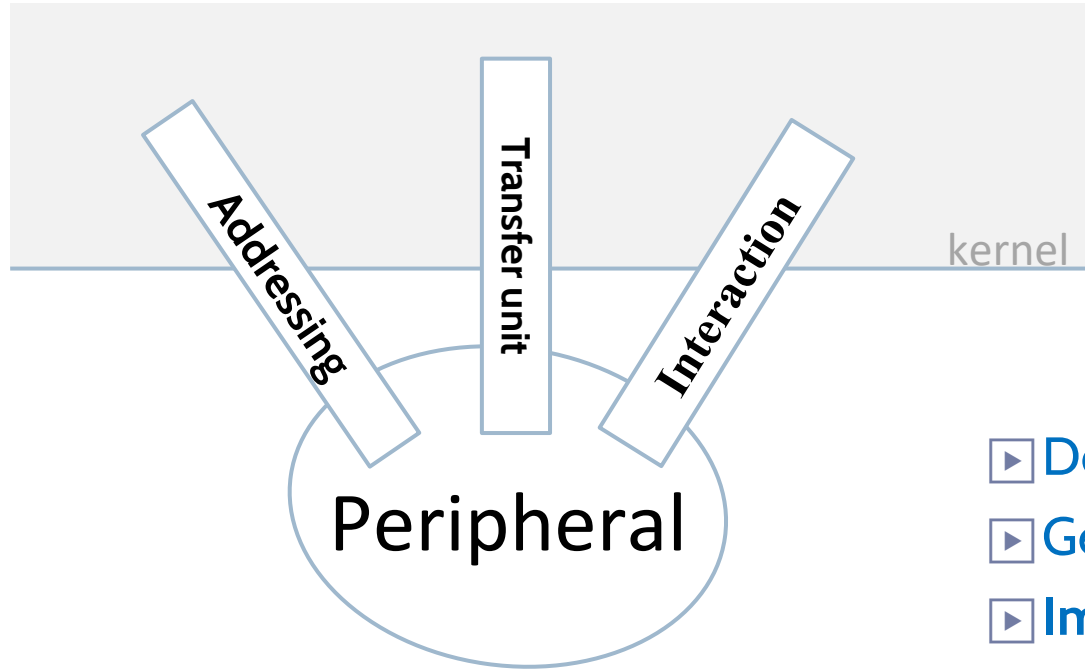
▶ Interrupted I/O

▶ CPU does not wait, only transfer data

▶ DMA I/O (direct memory access)

- ▶ CPU neither wait, nor transfer, it is notified at the end of data transfers
 - I/O module is more sophisticated (cost more, better performance)
 - Try to reduce the overhead when transferring blocks of data

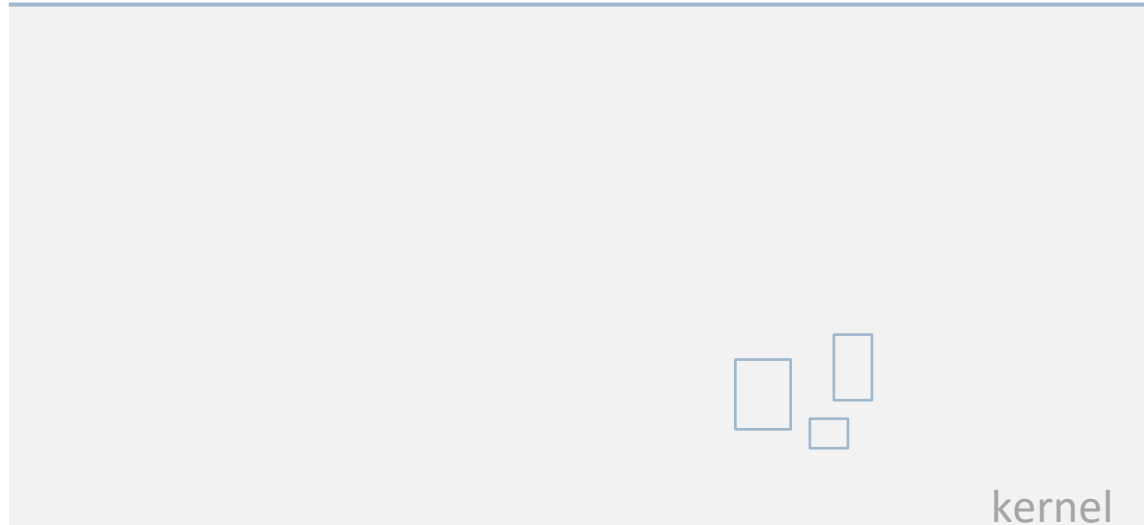
Introduction



- ▶ Definition of Peripheral
- ▶ General structure
- ▶ Implications in the O.S.

Implications in the operating system

1. Data structures



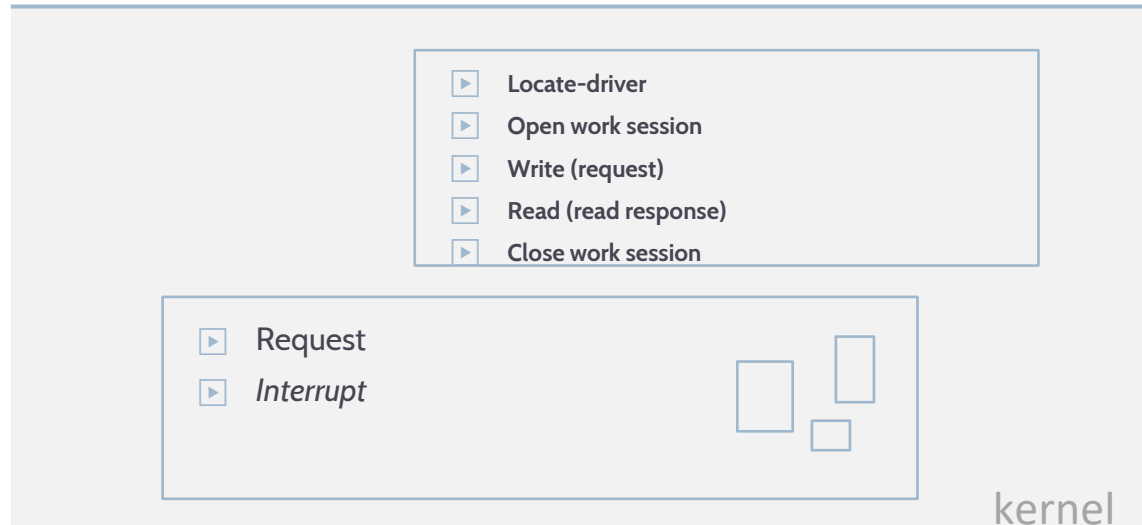
Implications in the operating system

2. Functions: internal management



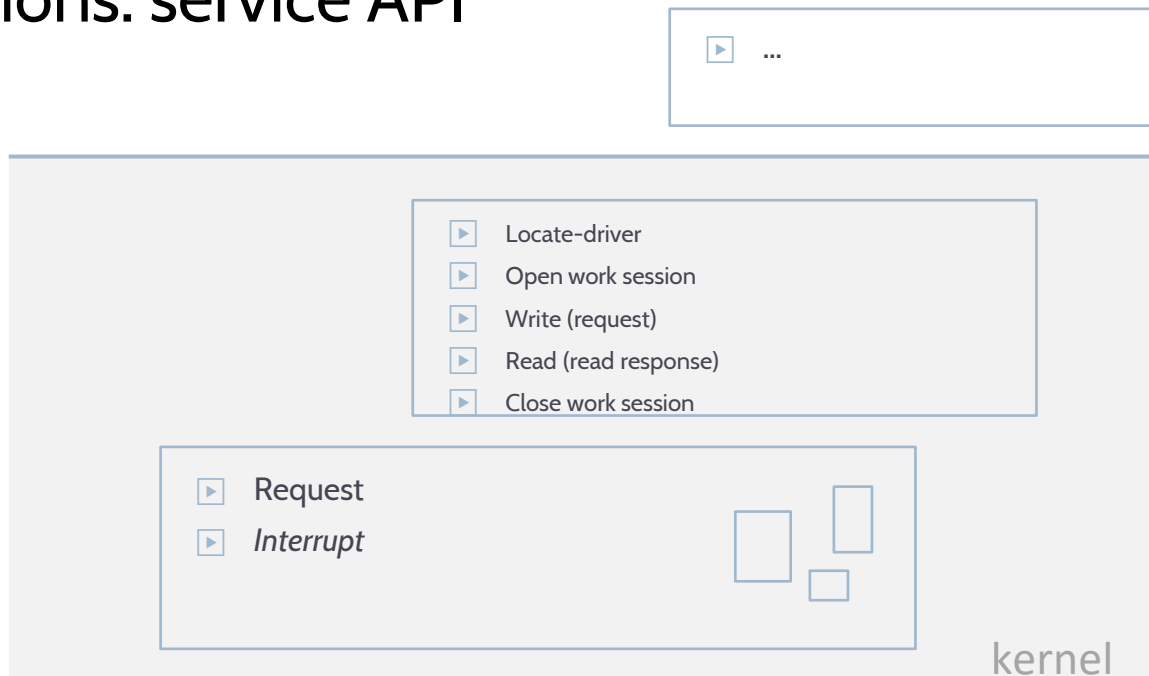
Implications in the operating system

3. Functions: services



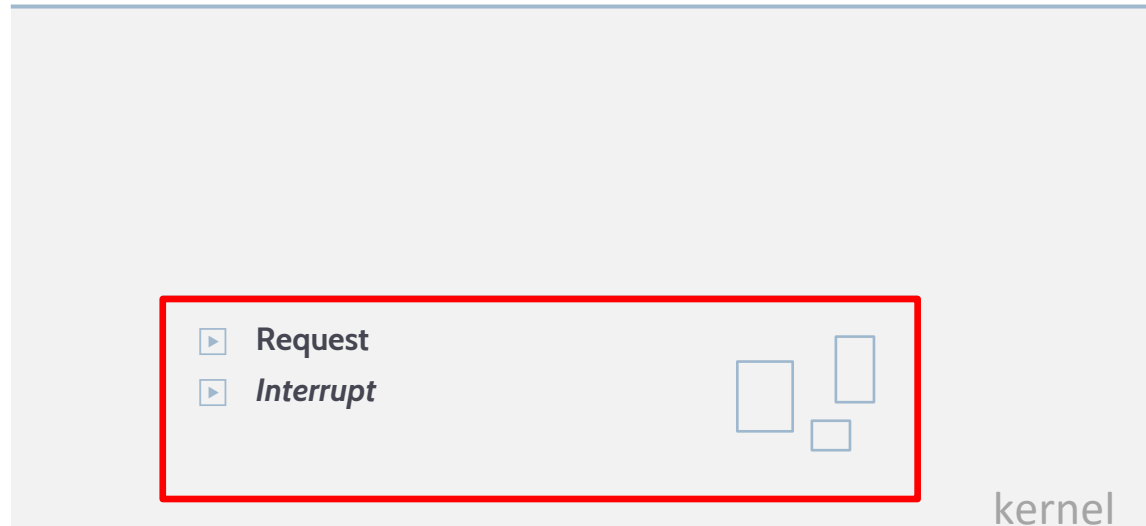
Implications in the operating system

3. Functions: service API



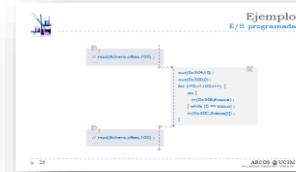
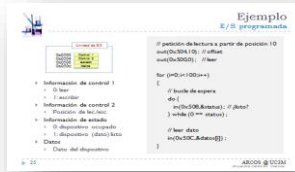
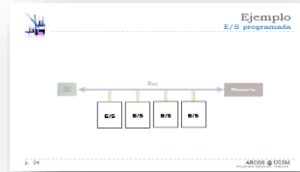
Implications in the operating system

(1 + 2) Data structures + internal mgmt. functions = driver

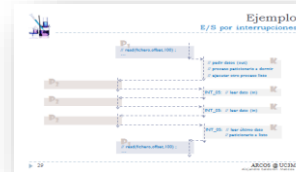
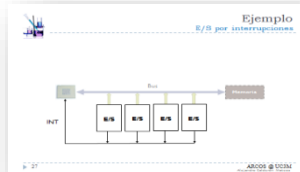


Impact in the Operating System of the device handling

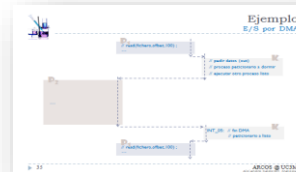
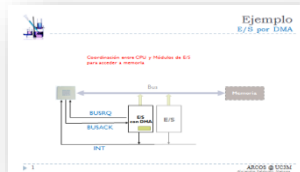
▶ Direct I/O



▶ Interrupted I/O



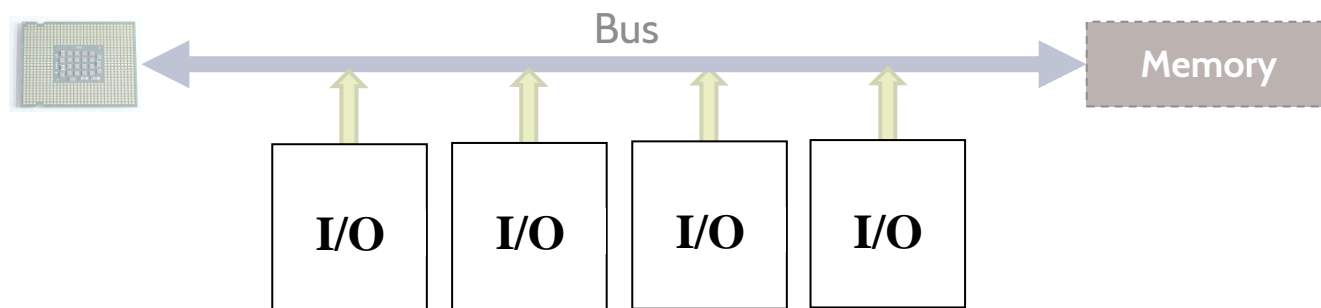
▶ DMA I/O





Example

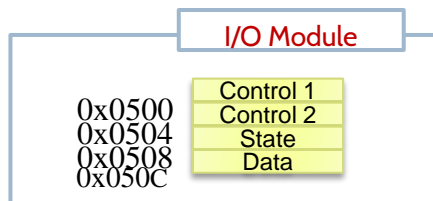
Direct I/O





Example

Direct I/O



- ▶ Control 1 information
 - ▶ 0: read
 - ▶ 1: write
- ▶ State information
 - ▶ 0: busy device
 - ▶ 1: device ready (data available)
- ▶ Data
 - ▶ Data from device

```
request:
for (i=0; i<100;i++)
{
    // read request
    out(0x500, 0);

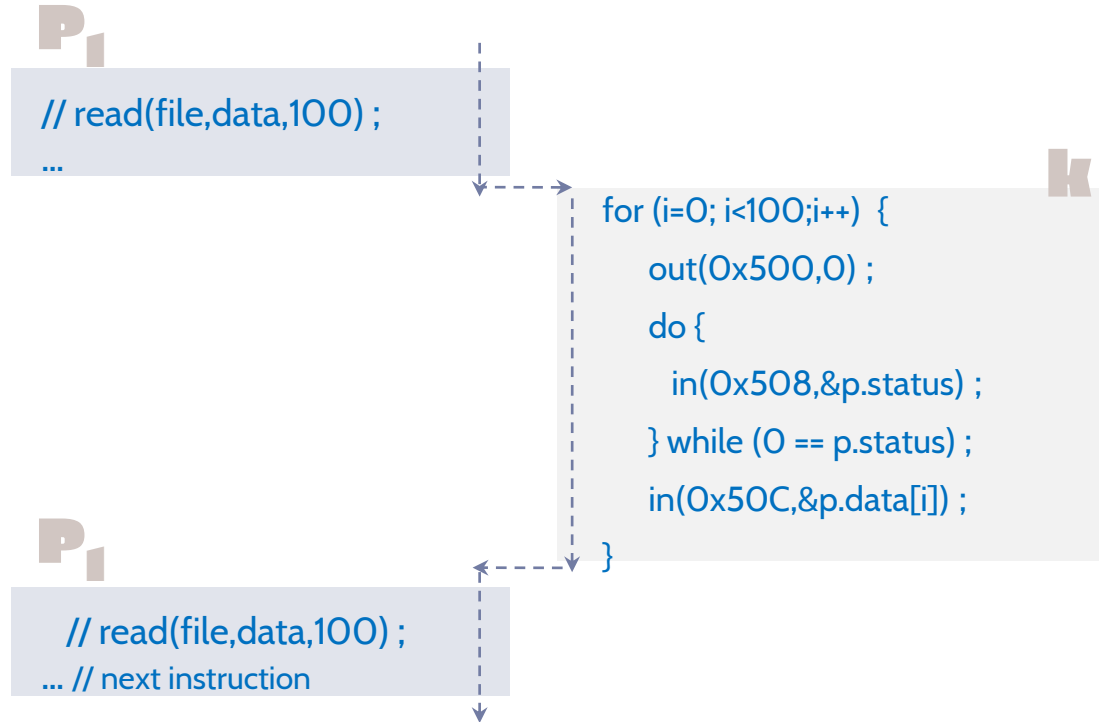
    // wait loop (busy wait)
    do {
        in(0x508, &(p.status)); // ready?
    } while (0 == (p.status));

    // read data
    in(0x50C, &(p.data[i]));
}
```



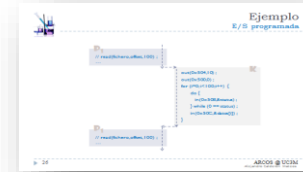
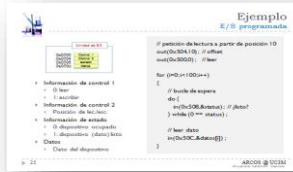
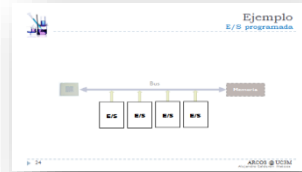
Example

Direct I/O

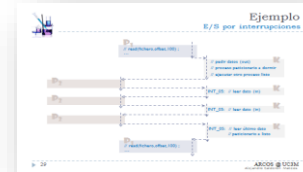
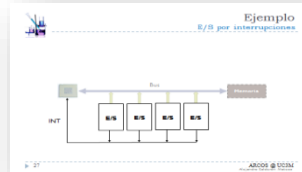


Impact in the Operating System of the device handling

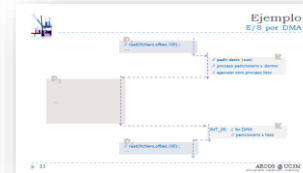
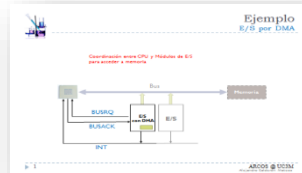
Direct I/O



Interrupted I/O



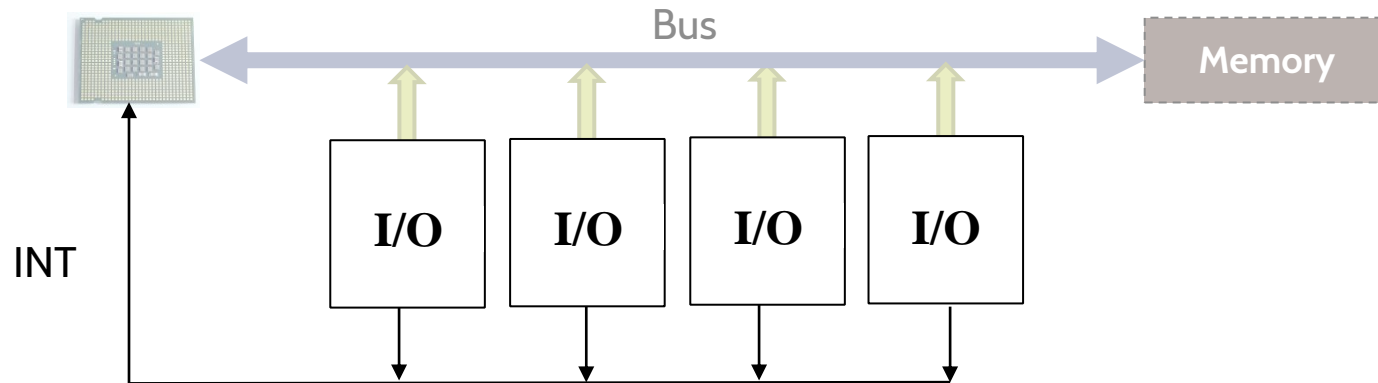
DMA I/O





Example

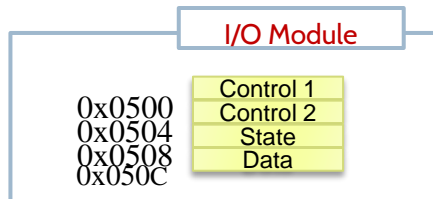
Interrupted I/O





Example

Interrupted I/O



- ▣ Control 1 information
 - ▣ 0: read
 - ▣ 1: write
- ▣ State information
 - ▣ 0: busy device
 - ▣ 1: device ready (data available)
- ▣ Data
 - ▣ Data from device

request:

```
// read request
p.counter = 0;
p.neltos = 100;
out(0x500, 0); // read
// Voluntary context switching (V.C.S.)
```

INT_O5:

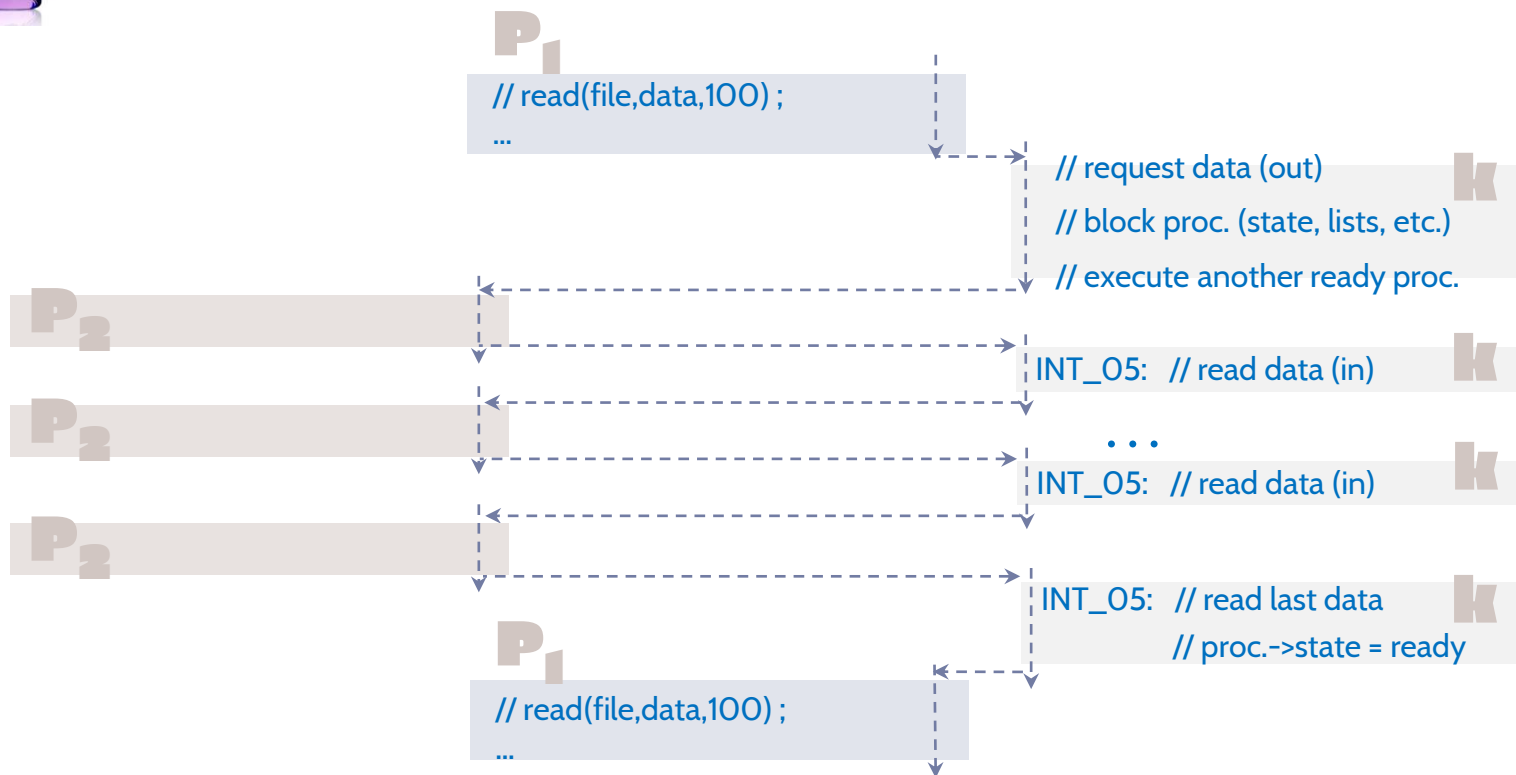
```
in(0x508, &(p.status));           // read state
in(0x50C, &(p.data[p.counter]));  // read data
if ((p.counter < p.neltos) && (p.status == OK)) {
    p.counter++;
    out(0x500, 0); // read
} else { // process->state = ready }

ret_int # restore registers & return
```



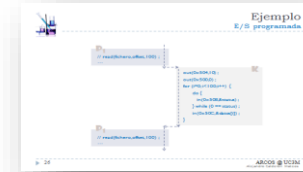
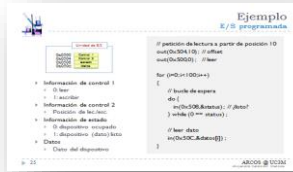
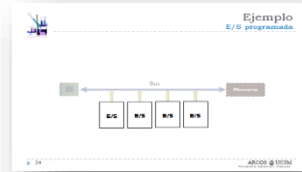
Example

Interrupted I/O

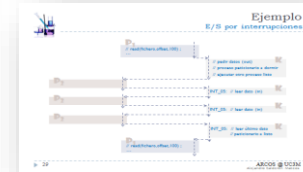
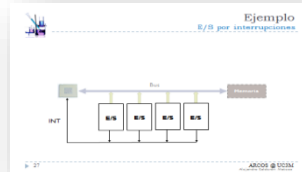


Impact in the Operating System of the device handling

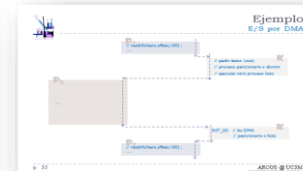
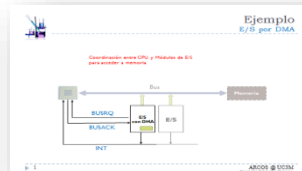
Direct I/O



Interrupted I/O



DMA I/O

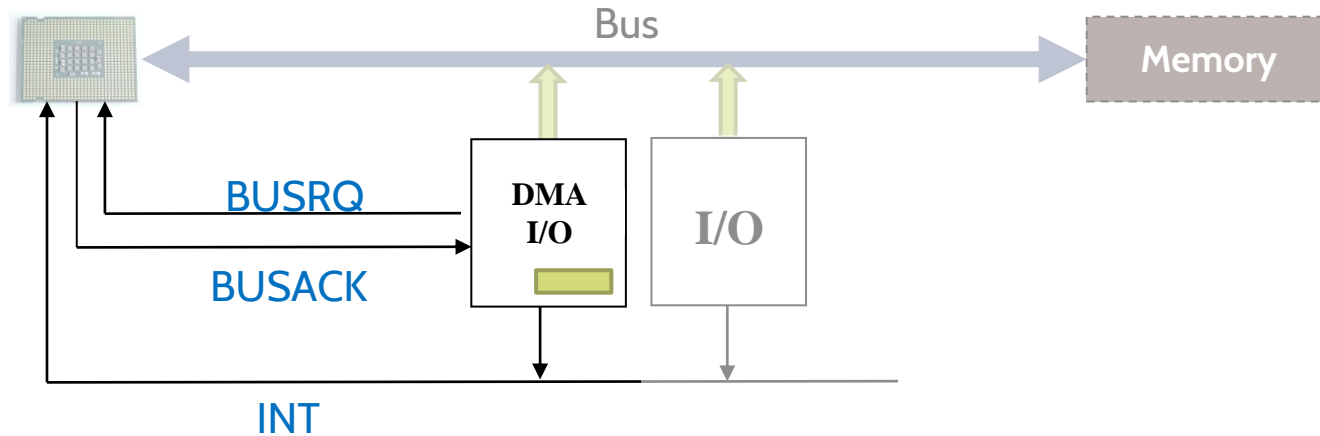




Example

DMA I/O

Coordination between CPU and I/O Modules
in order to access to memory



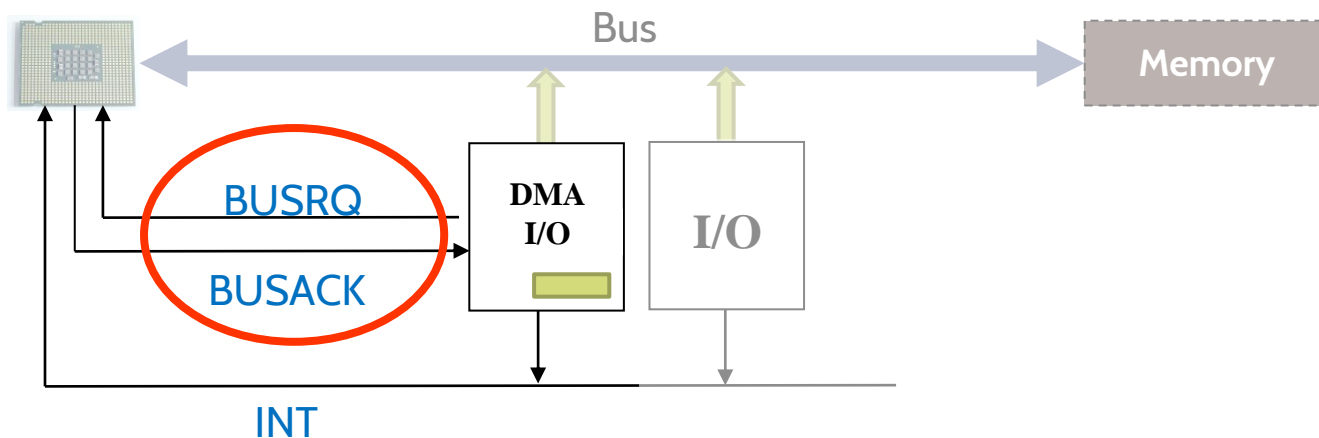


Example

DMA I/O

Each data transferred to memory implies:

- To ask permission for accessing memory (BUSRQ)
- To wait permission grant (BUSACK)
- To transfer to memory
- To disable request permission (BUSRQ)

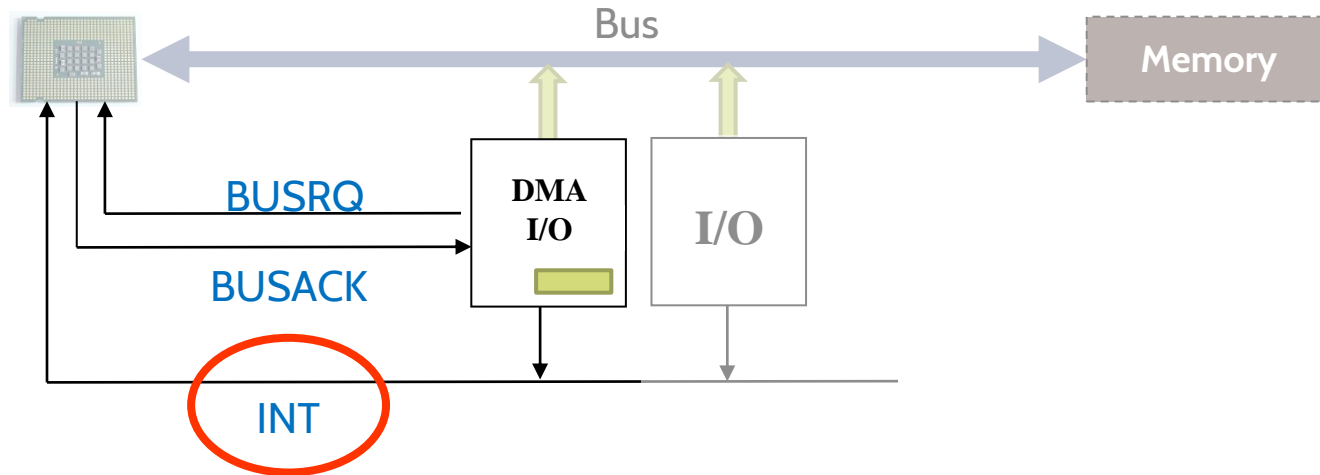




Example

DMA I/O

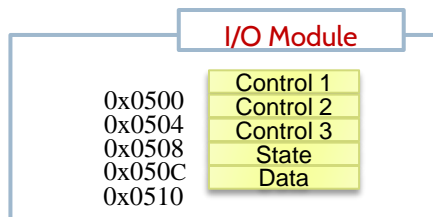
- Once all data has been transferred:
- Fire an interrupt (INT) to notify the CPU





Example

DMA I/O



- ▶ Control 1 information
 - ▶ 0: read, 1: write
- ▶ Control 2 information
 - ▶ Memory address.
- ▶ Control 3 information
 - ▶ Number of elements
- ▶ State information
 - ▶ 0: busy device
 - ▶ 1: device ready (data available)
- ▶ Data
 - ▶ Data from device

request:

// perform block request

out(0x500,0); // read

out(0x504,p.data); // vector address

out(0x508,100); // # eltos

// Voluntary Context Switching (V.C.S.)

INT_05: // read state y data
in(0x50C, &status);

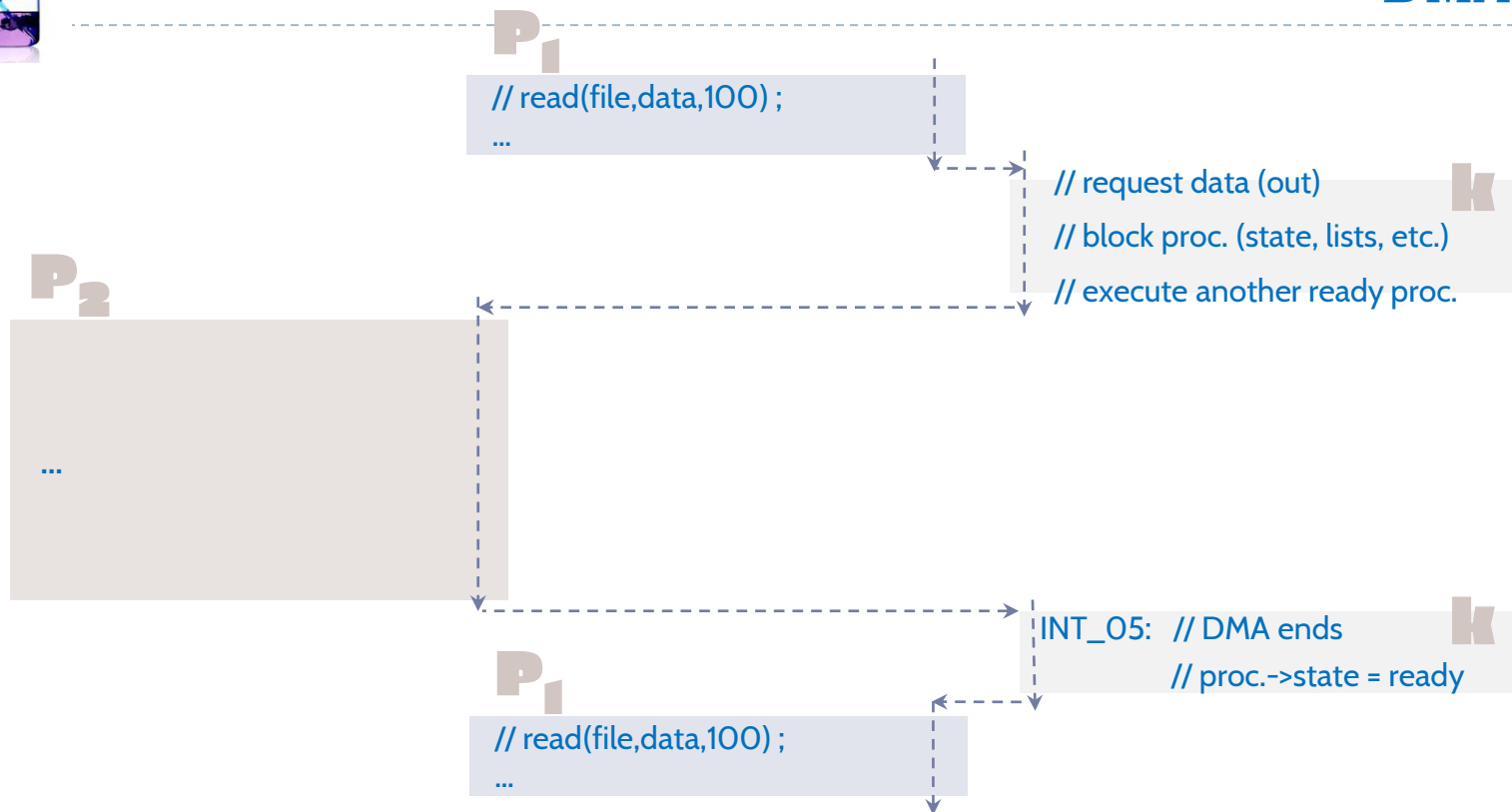
if (p.status...

// process->state = ready
ret_int # restore registers & return



Example

DMA I/O



Main types of protocols

- ▶ Request -> individual response

- ▶ Most devices

- ▶ Only request

- ▶ E.g.: graphic card
 - ▶ Direct I/O (faster or real-time)

- ▶ Only response

- ▶ E.g.: clock
 - ▶ Interrupted I/O (fire data without former request)

- ▶ Request -> shared response

- ▶ E.g.: hard disk

Lesson 3a

process, devices, drivers, and extended services

Operating System Design
Degree in Computer Science and Engineering, Double Degree CS&E + BA