

ARCOS Group

uc3m | Universidad **Carlos III** de Madrid

L3: Fundamentals of assembler programming Computer Structure

Bachelor in Computer Science and Engineering

Bachelor in Applied Mathematics and Computing

Dual Bachelor in Computer Science and Engineering and Business Administration

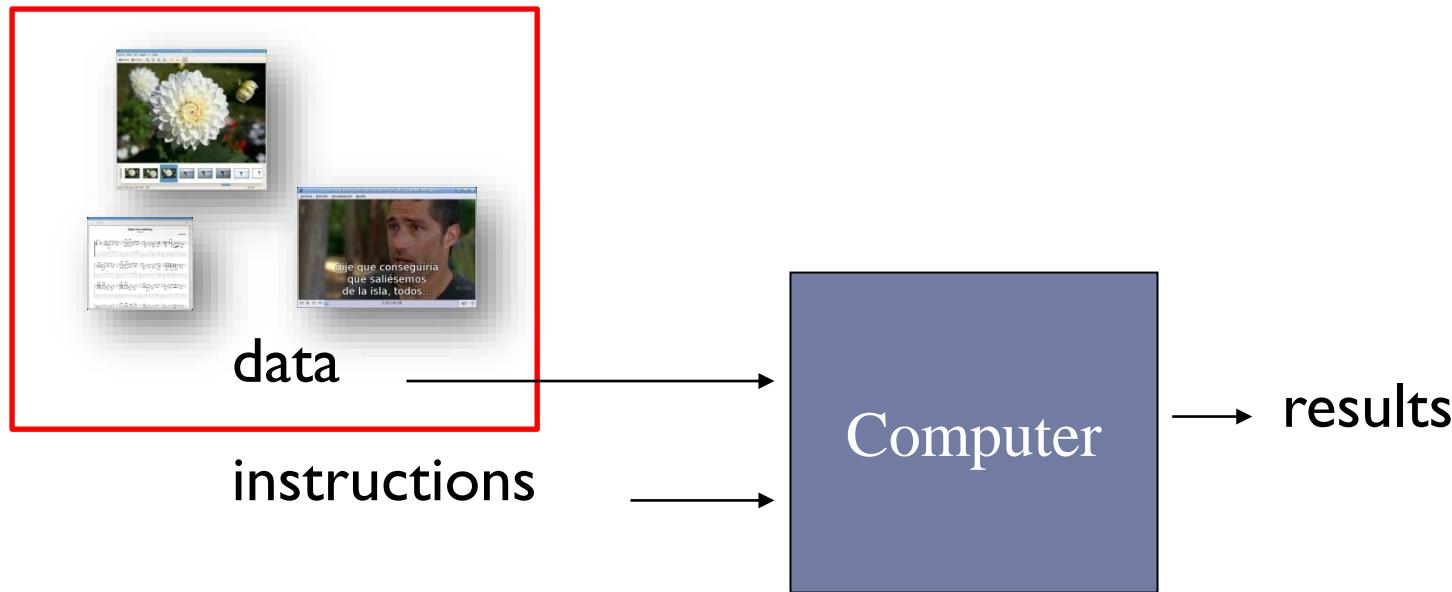


Contents

- I. Basic concepts on assembly programming
 - I. Motivations and goals
 - 2. Introduction to RISC-V32
- 2. RISC-V32 assembly language, memory model and data representation
- 3. Instruction formats and addressing modes
- 4. Procedure calls and stack convention

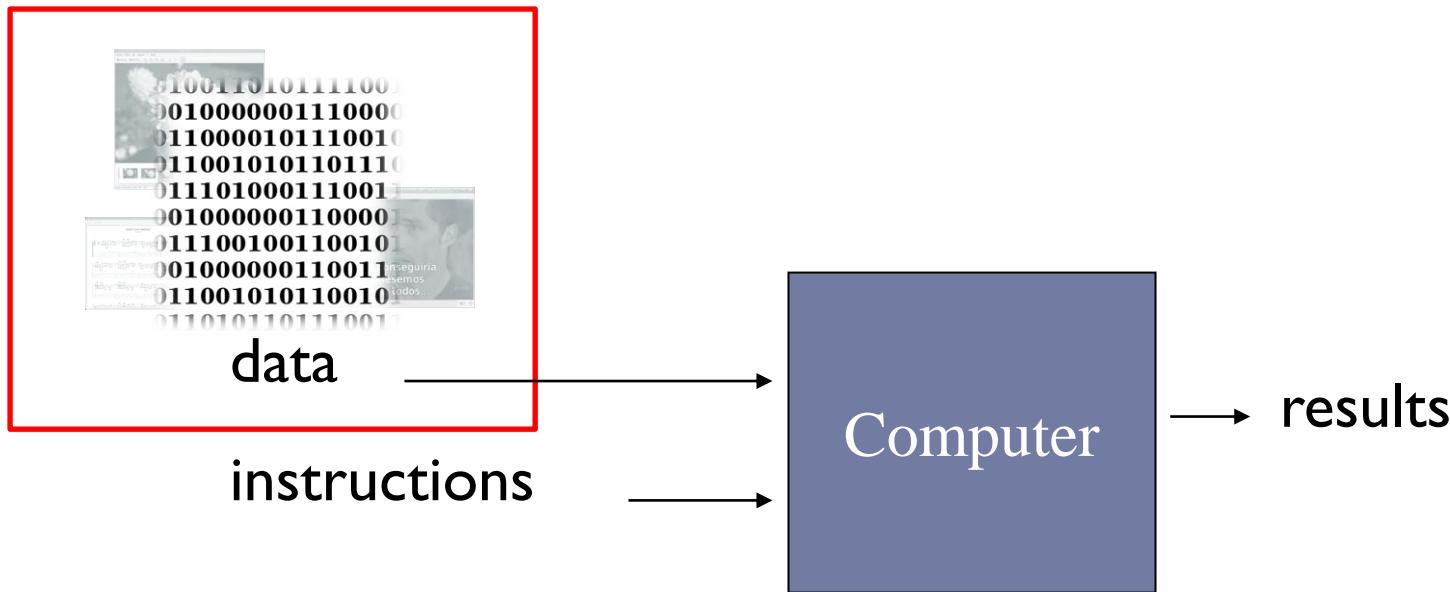
Types of information: instructions and data

► Data representation...



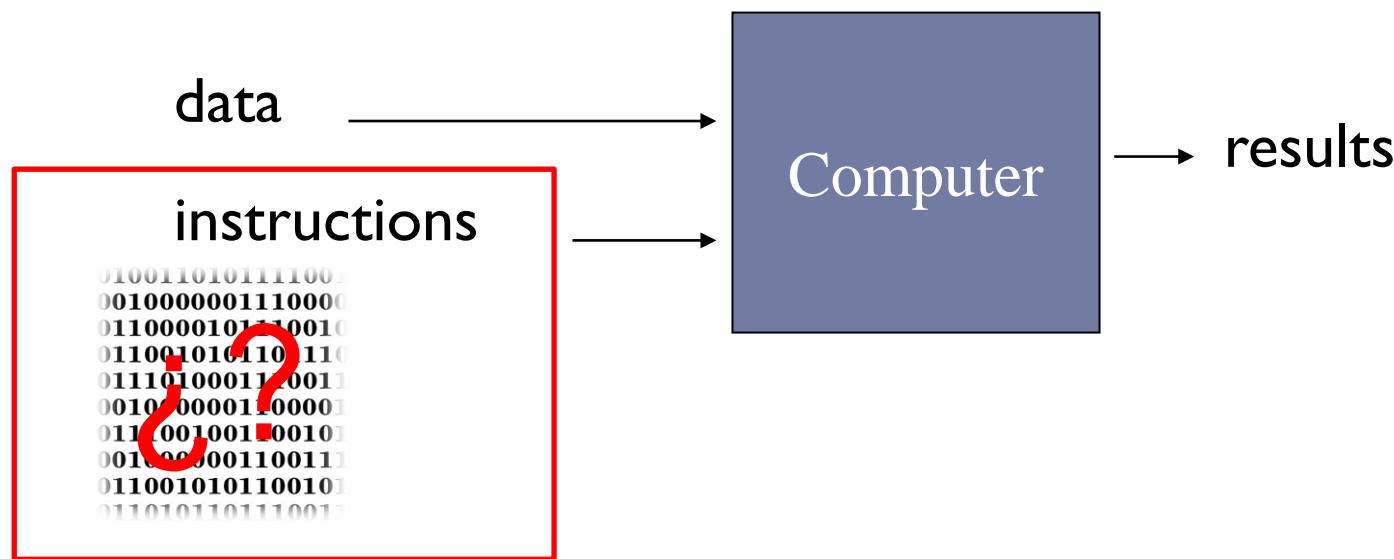
Types of information: instructions and data

- ▶ **Binary data representation.**



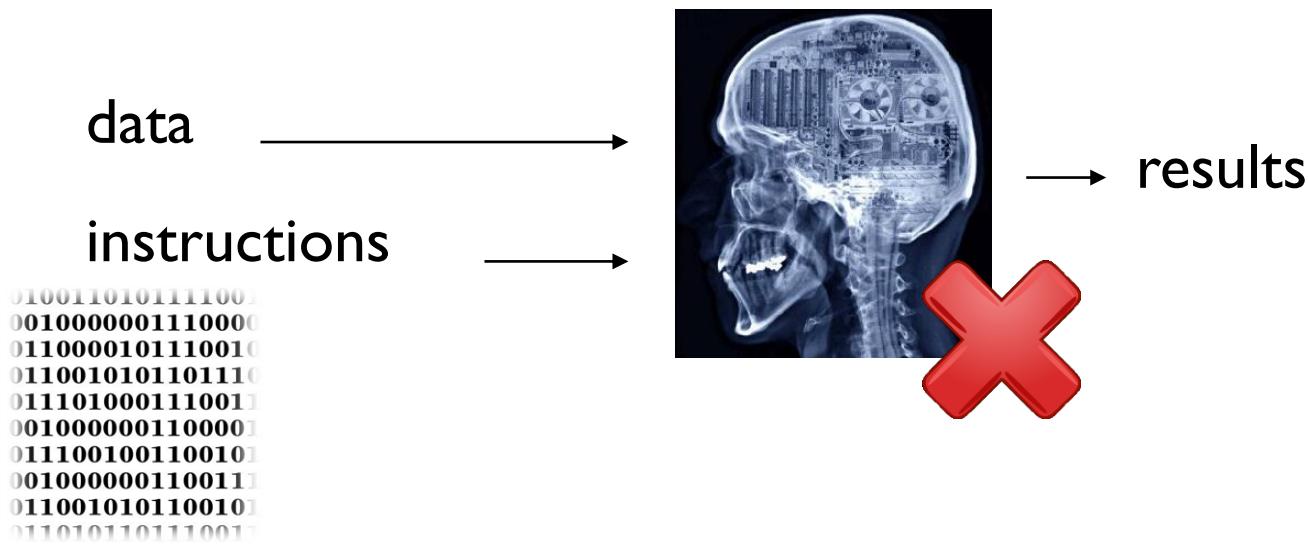
Types of information: instructions and data

- ▶ What about the instructions?
 - ▶ Machine instructions, properties and format



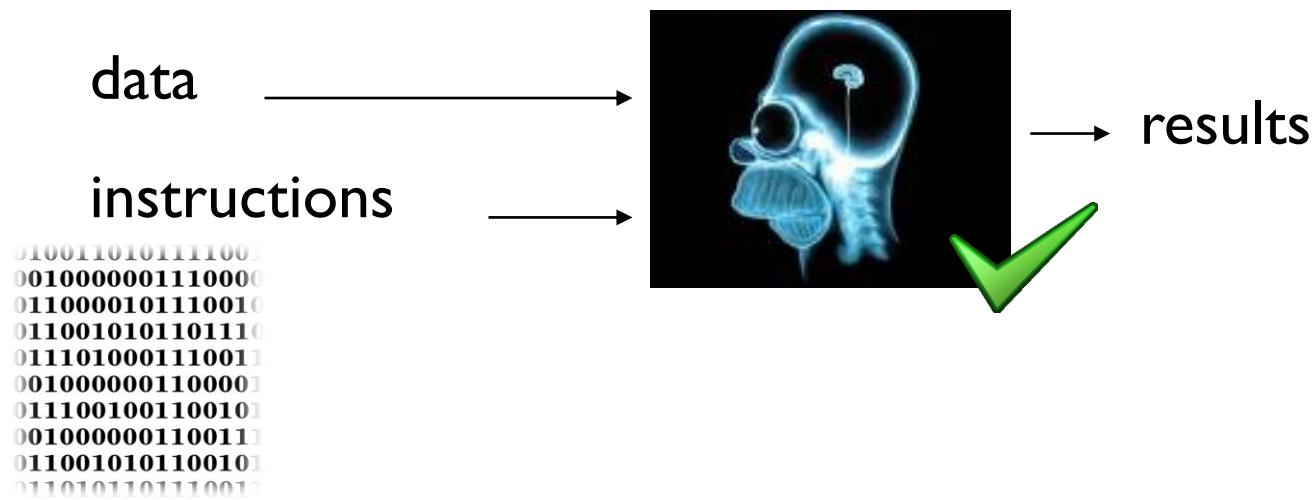
Machine instructions

- ▶ There are not complex instructions...



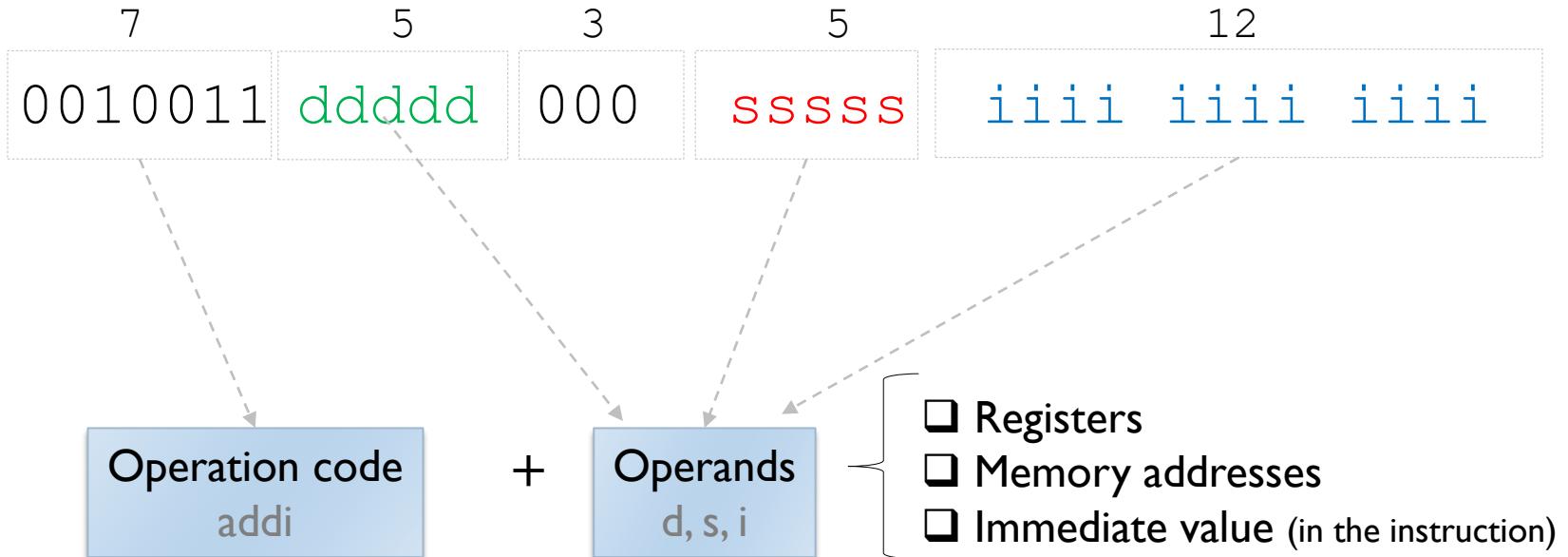
Machine instructions

- ▶ ... but very simple tasks...



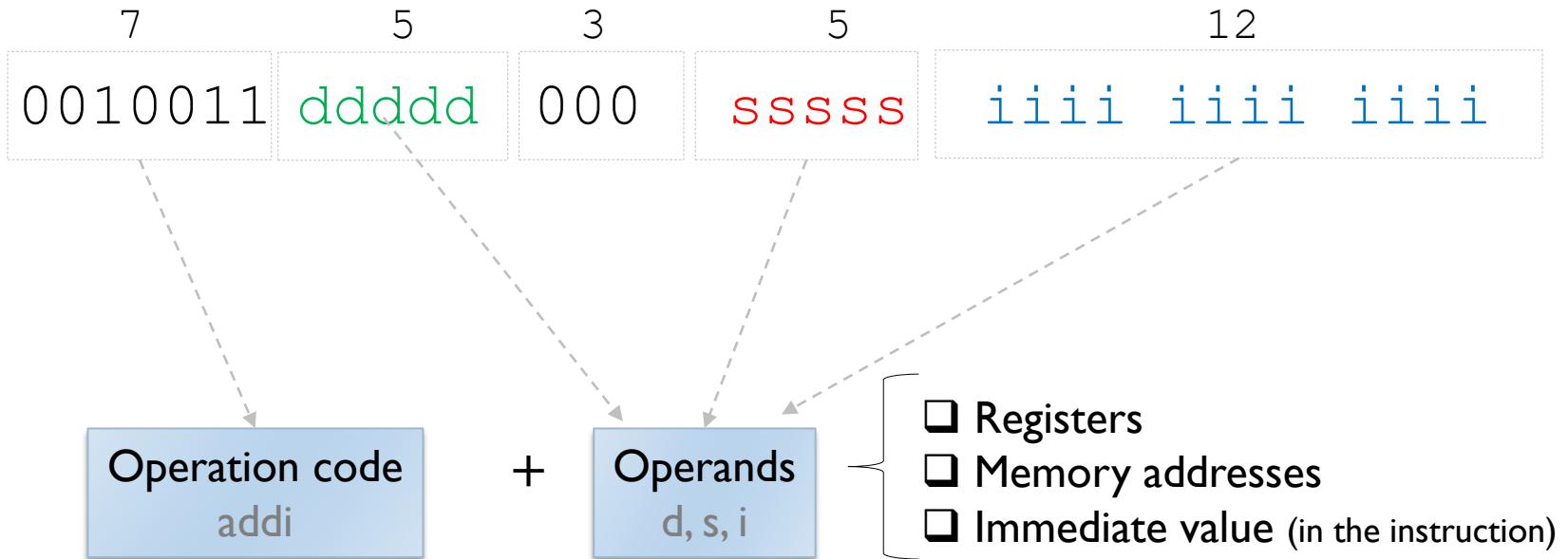
Machine instruction: definition

- ▶ **Machine instruction:** elementary operation that can be executed directly by the processor.
- ▶ Example: instruction of immediate add (addi) for 32 bits
 - ▶ $(d) = \text{register } (s) + \text{immediate value } (i)$



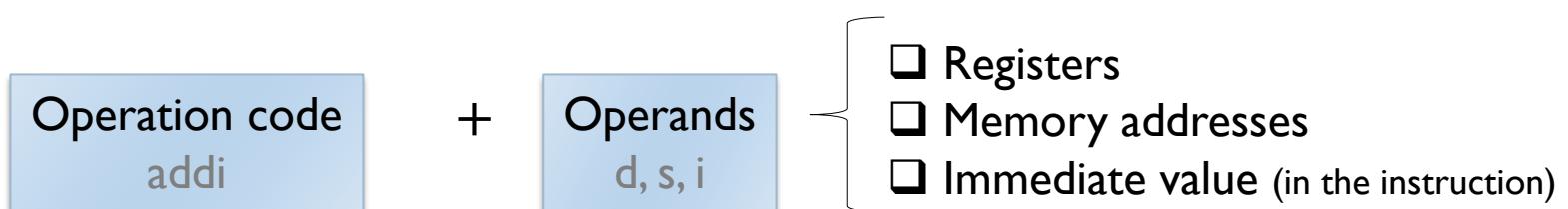
Machine instruction: properties

- ▶ Perform a single, simple task
- ▶ Operate on a fixed number of operands
- ▶ Include all the information necessary for its execution



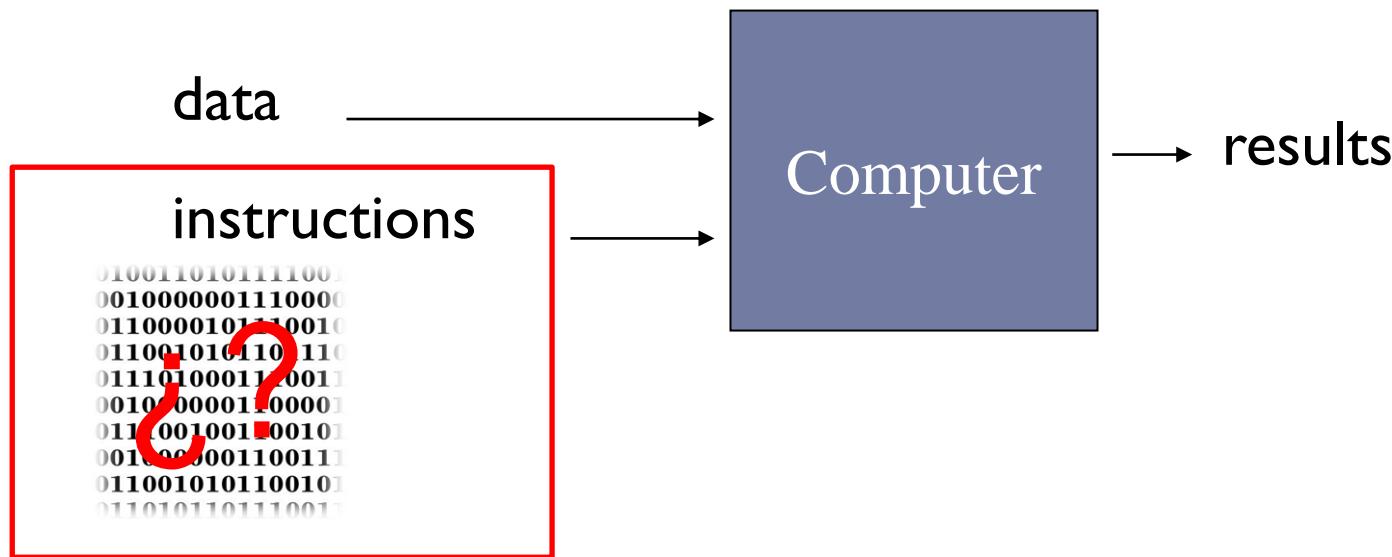
Machine instruction: included information

- ▶ The **operation to be performed**.
- ▶ Where the **operands** are located:
 - ▶ In registers
 - ▶ In memory
 - ▶ In the instruction itself (immediate)
- ▶ Where to leave the **results** (as operand)
- ▶ A reference to the **next instruction** to be executed
 - ▶ Implicitly: the following instruction
 - ▶ A program is a consecutive sequence of machine instructions.
 - ▶ Explicitly in branching instructions (as operand)



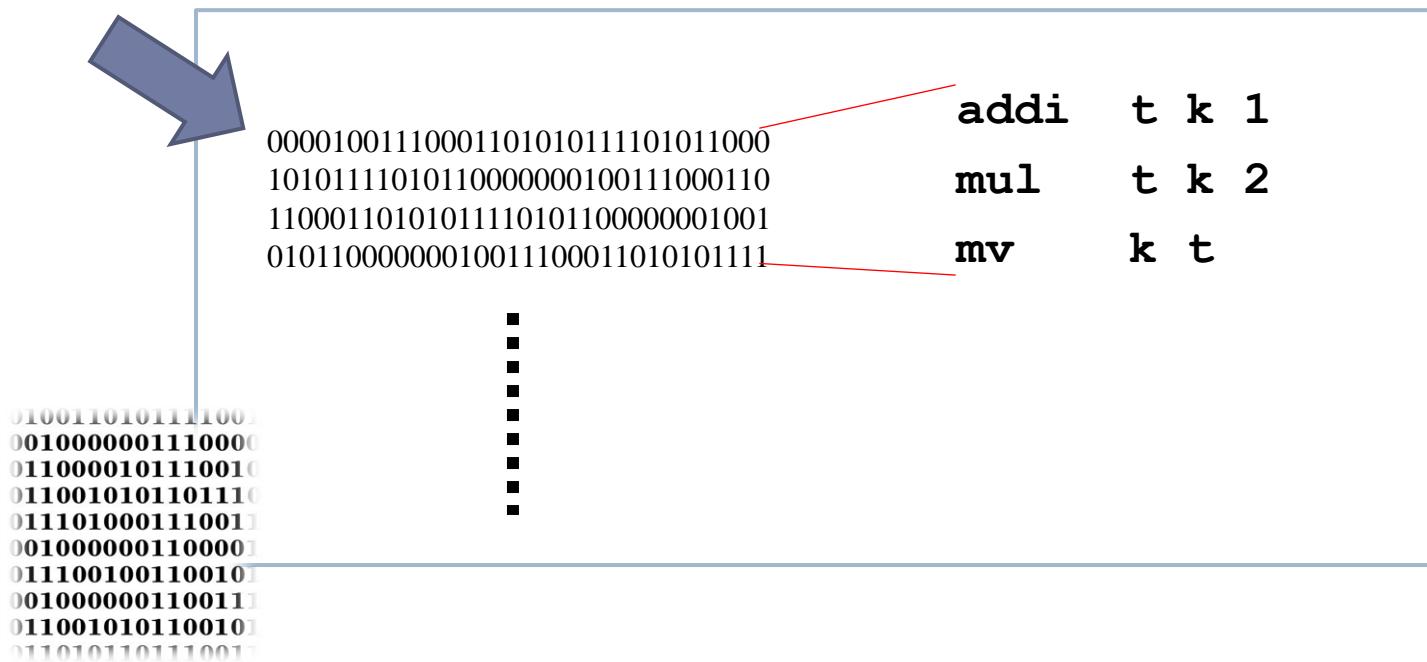
Types of information: instructions and data

- ▶ What about the instructions?
 - ▶ Program, assembly language, ISA



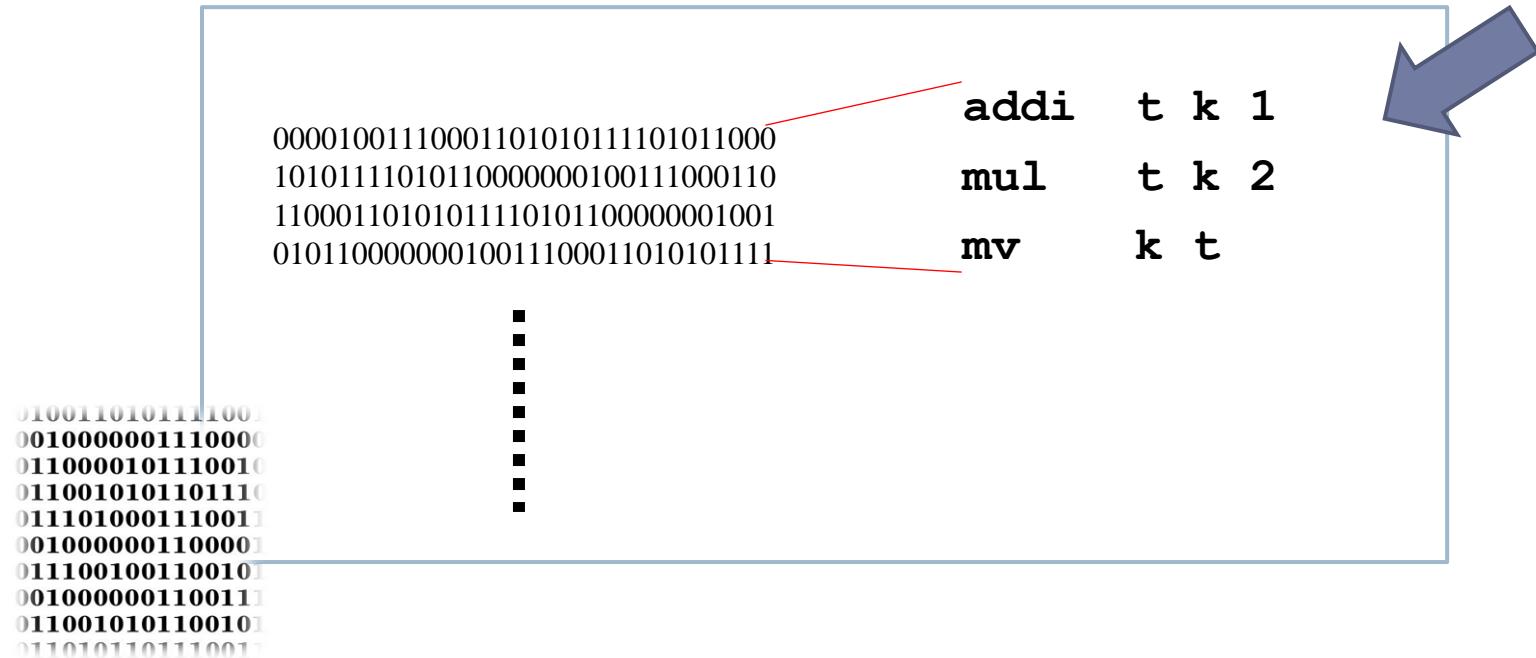
Definition of program

- ▶ **Program:** Ordered sequence of machine instructions that are executed by default in order.



Assembly language definition

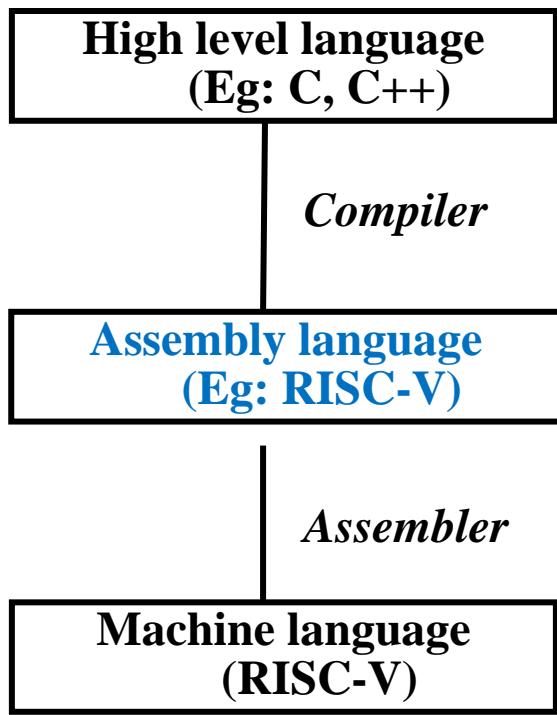
- ▶ **Assembly language:** programmer-readable language that is **the most direct representation of architecture-specific machine code.**



Assembly language definition

- ▶ **Assembly language:** programmer-readable language that is **the most direct representation of architecture-specific machine code.**
- ▶ **Uses symbolic codes to represent instructions**
 - ▶ add – addition
 - ▶ lw – Load a memory data
- ▶ **Uses symbolic codes for data and references**
 - ▶ t0 – register
- ▶ **There is an assembly instruction per machine instruction**
 - ▶ add t1, t2, t3

Languages levels



temp = v[k];
v[k] = v[k+1];
v[k+1] = temp;

lw t0, 0(x2)
lw t1, 4(x2)
sw t1, 0(x2)
sw t0, 4(x2)

0000	1001	1100	0110	1010	1111	0101	1000
1010	1111	0101	1000	0000	1001	1100	0110
1100	0110	1010	1111	0101	1000	0000	1001
0101	1000	0000	1001	1100	0110	1010	1111

Instruction sets

- ▶ **Instruction Set Architecture (ISA)**
 - ▶ Instruction set of a processor
 - ▶ Boundary between hardware and software
- ▶ **Examples:**
 - ▶ 80x86
 - ▶ ARM
 - ▶ MIPS
 - ▶ RISC-V
 - ▶ PowerPC
 - ▶ Etc.

Characteristics of an instruction set (1 / 2)

- ▶ Format and coding of the instruction set:
 - ▶ Fixed or variable length instructions
 - ▶ 80x86: variable (from 1 up to 18 bytes)
 - ▶ MIPS, ARM: fixed
- ▶ Operands:
 - ▶ Registers, memory, the instruction itself
- ▶ Type and size of operands:
 - ▶ bytes: 8 bits
 - ▶ integers: 16, 32, 64 bits
 - ▶ floating-point numbers: single precision, double precision, etc.
- ▶ Addressing modes:
 - ▶ They specify where and how to access operands (register, memory or the instruction itself)

Characteristics of an instruction set (2/2)

- ▶ **Operations:**
 - ▶ Arithmetic, logic, transfer, control, control, etc.
- ▶ **Flow control instructions:**
 - ▶ Unconditional jumps
 - ▶ Conditional jumps
 - ▶ Procedure calls
- ▶ **Memory addressing:**
 - ▶ Most of them use byte addressing
 - ▶ They provide instructions for accessing multi-byte elements from a given position

Programming model of a computer

- ▶ A computer offers a programming model that consists of:
 - ▶ Instruction set (assembly language)
 - ▶ ISA: *Instruction Set Architecture*
 - ▶ An instruction includes:
 - Operation code
 - Other elements: registers, memory address, numbers
 - ▶ Storing elements
 - ▶ Registers
 - ▶ Memory
 - ▶ Registers of I/O controllers
 - ▶ Execution modes

Motivation to learn assembly

High-level language

```
#include <stdio.h>
#define PI 3.1416
#define RADIO 20

int main ()
{
    int l;
    l=2*PI*RADIO;
    printf("long: %d\n",l);
    return (0);
}
```

Assembly language

```
.data
PI: .word 3.14156
RADIO: .word 20

.text
    li  a0 2
    la  t0 PI
    lw  t0 ($t0)
    la  t1 RADIO
    lw  t1 (t1)
    mul a0 a0 t0
    mul a0 a0 t1

    li a7 1
    ecall
```

Machine language

```
0100110101111001
0010000001110000
0110000101110010
0110010101101110
0111010001110011
0010000001100001
0111001001100101
0010000001100111
0110010101100101
0110101101110011
```

Motivation to learn assembly

```
#include <stdio.h>
#define PI 3.1416
#define RADIUS 20

int main ()
{
    register int l;
    l=2*PI*RADIUS;
    printf("long: %d\n",l);
    return (0);
}
```

```
.data
PI: .word RADIUS
.RDATA
    .word 3.1416
    .word 20
.TEXT
    li    a0 ,PI
    la    t0 ,RADIUS
    lw    t0 ,t0
    la    t1 ,RADIUS
    lw    t1 ,t1
    mul   a0 ,t0
    mul   a0 ,t1
    li    a7 ,1
    ecall
```

- ▶ Understand how high-level languages are executed
 - ▶ C, C++, Python, Java, ...
- ▶ Analyze the execution time of high-level instructions.
- ▶ Useful in specific domains:
 - ▶ Compilers
 - ▶ Operating Systems
 - ▶ Games
 - ▶ Embedded systems
 - ▶ Etc.

Goals

- ▶ Know how the elements of a high-level assembly language are represented.:
 - ▶ Data types (int, char, ...)
 - ▶ Control structures (if, while, ...)
- ▶ Be able to write small programs in assembler

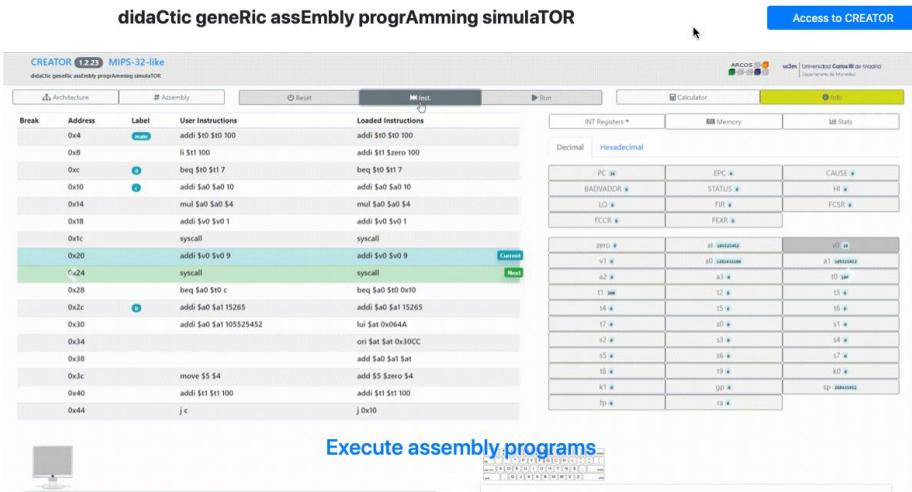
```
.data
PI: .word 3.14156
RADIUS: .word 20

.text
li a0 2
la t0 PI
lw t0 (t0)
la t1 RADIUS
lw t1 (t1)
mul a0 a0 t0
mul a0 a0 t1

li a7 1
ecall
```



Motivation to use CREATOR simulator

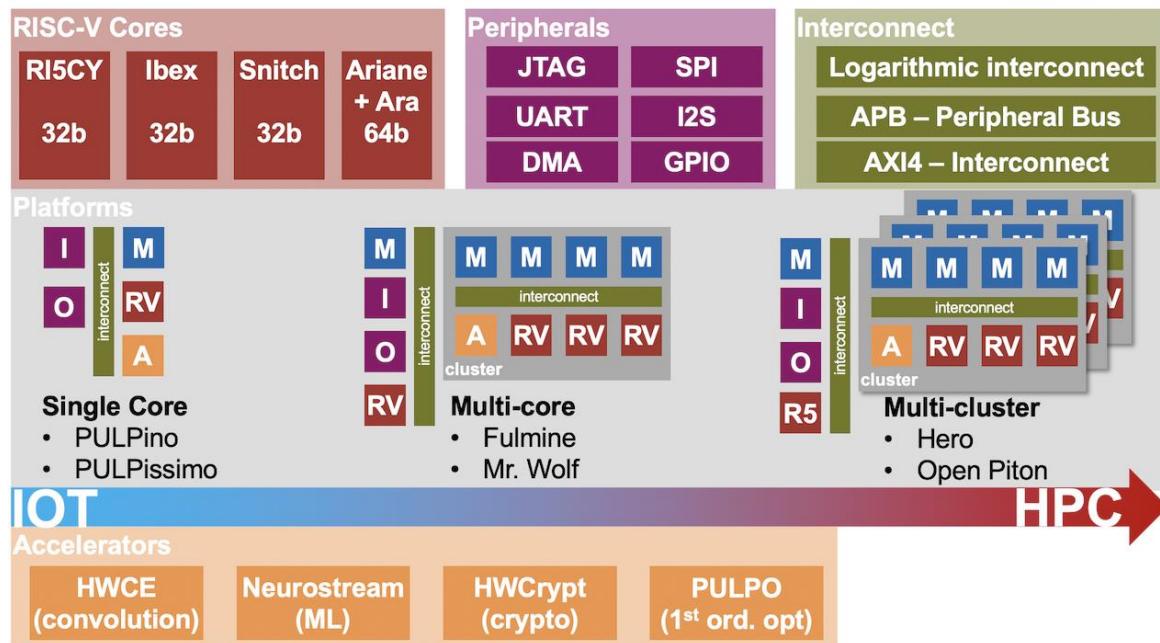


<https://creatorsim.github.io/>

- ▶ CREATOR: didaCtic geneRic assEmbly progrAmming simulaTOR
- ▶ CREATOR can simulate MIPS₃₂ and RISC-V architectures
- ▶ CREATOR can be executed from Firefox, Chrome, Edge or Safari

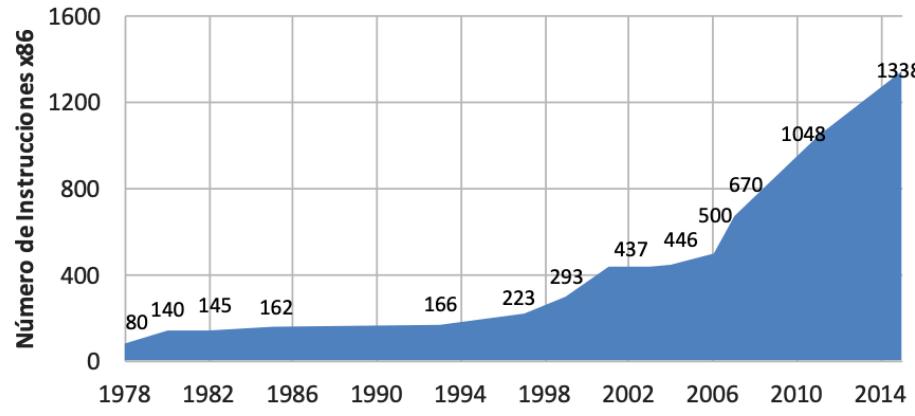
Motivations to use RISC-V

- RISC processor (*Reduced Instruction Set Computer*)
- Examples of RISC processors:
 - RISC-V, ARM, MIPS, etc.



Advantages of using RISC-V

- ▶ Open hardware architecture:
 - ▶ Allows anyone to design, manufacture and sell RISC-V chips and software
- ▶ Small and simple set of instructions
 - ▶ RV32I -> ~47 instructions, RV32IMAF -> ~76
 - ▶ Difference with x86 architecture instructions



Guía Práctica de RISC-V.
David Patterson y Andrew Waterman

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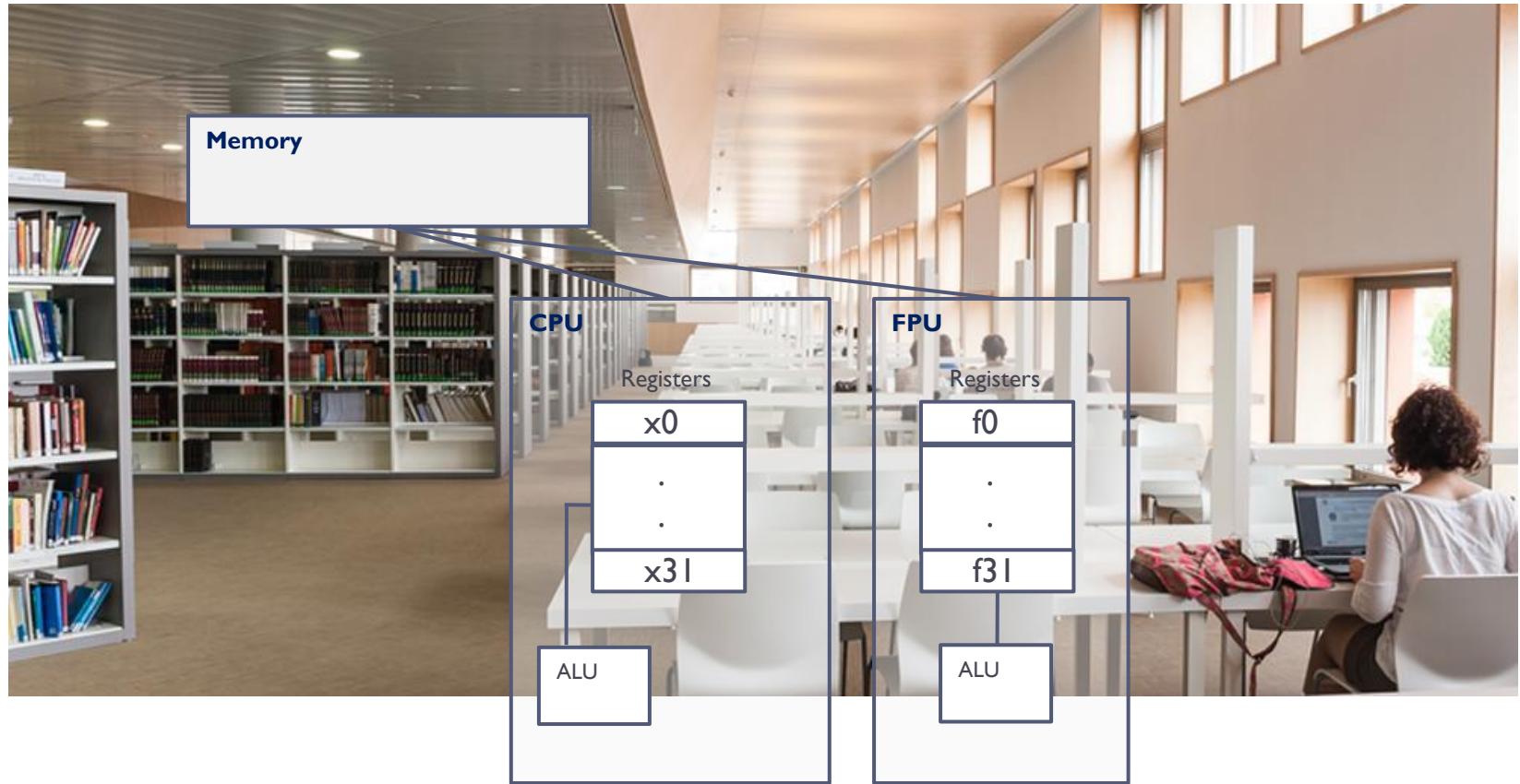
RISC-V instruction set

- ▶ **Instruction sets:**
 - ▶ RV32I: Set of instructions on integers. 32 bits
 - ▶ RV64I: Set of instructions on integers. 64 bits
 - ▶ RV128I: Set of instructions about integers. 128 bits
- ▶ **On each of them there are different extensions:**
 - ▶ M: instructions for integer multiplication and division
 - ▶ F: instructions for single-precision floating point
 - ▶ D: double precision floating-point instructions
 - ▶ G: Includes M, F and D
 - ▶ Q: quadruple-precision floating-point instructions
 - ▶ Etc.
- ▶ **Example: RV64IF: RISC-V 64-bits processor with simple-precision floating-point instructions**

RISC-V instruction sets to be described

- ▶ Instruction sets:
 - ▶ RV32I: Set of instructions on integers. 32 bits
 - ▶ RV64I: Set of instructions on integers. 64 bits
 - ▶ RV128I: Set of instructions on integers. 128 bits
- ▶ Each of them has different extensions:
 - ▶ M: instructions for integer multiplication and division
 - ▶ F: instructions for single-precision floating point
 - ▶ D: double precision floating-point instructions

RISC-V register file



CREATOR

didaCtic geneRic assEmbly progrAmming simulaTOR

Register file

Break	Address	Label	User Instructions	Loaded Instructions
0x4		main	addi \$t0 \$t0 100	addi \$t0 \$t0 100
0x8			li \$t1 100	addi \$t1 \$zero 100
0xc		④	beq \$t0 \$t1 7	beq \$t0 \$t1 7
0x10		⑤	addi \$a0 \$a0 10	addi \$a0 \$a0 10
0x14			mul \$a0 \$a0 \$4	mul \$a0 \$a0 \$4
0x18			addi \$v0 \$v0 1	addi \$v0 \$v0 1
0x1c			syscall	syscall
0x20			addi \$v0 \$v0 9	addi \$v0 \$v0 9
0x24			syscall	syscall
0x28			beq \$a0 \$t0 c	beq \$a0 \$t0 0x10
0x2c		⑥	addi \$a0 \$a1 15265	addi \$a0 \$a1 15265
0x30			addi \$a0 \$a1 105525452	lui \$at 0x064A
0x34				ori \$at \$at 0x30CC
0x38				add \$a0 \$a1 \$at
0x3c			move \$5 \$4	add \$5 \$zero \$4
0x40			addi \$t1 \$t1 100	addi \$t1 \$t1 100
0x44			j c	j 0x10

INT Registers		
Decimal		Hexadecimal
PC	400125452	v0
BADVADDR	1220432300	a0
LO	10	a1
FCSR	0	fcr
zero	0	at
v1	0	a0
a2	0	a1
t1	0	t2
t4	0	t3
t7	0	t1
s2	0	s3
s5	0	s6
t8	0	t9
k1	0	gp
fp	0	ra

<https://creatorsim.github.io/>

Register File (integers)

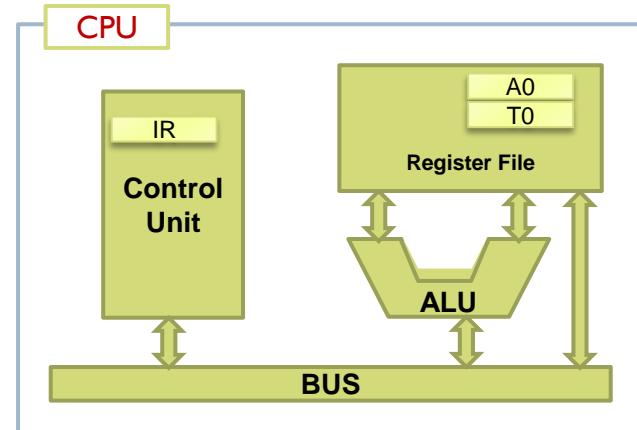
ABI Name	Number	Uso
zero	x0	Constant 0
ra	x1	Return address (routines)
sp	x2	Stack pointer
gp	x3	Global pointer
tp	x4	Thread pointer
t0...t2	x5...x7	Temporary (NON-kept between calls)
s0/fp	x8	Temporary (kept between calls) / Frame stack pointer
s1	x9	Temporary (kept between calls)
a0...a1	x10...x11	Input argument for routines/returned values
a2...a7	x12...x17	Input argument for routines
s2...s11	x18...x27	Temporary (kept between calls)
t3...t6	x28...x31	Temporary (<u>NON</u> -kept between calls)

- ▶ There are 32 registers
 - ▶ Size of 4 bytes (one word)
 - ▶ Dual name:
 - ▶ Logical: ABI name (*Application Binary Interface*)
 - ▶ Numeric: starting with **x** at the beginning
- ▶ Use agreement
 - ▶ Reserved
 - ▶ Arguments
 - ▶ Results
 - ▶ Temporary
 - ▶ Pointers

Data transfer (integer registers)

- ▶ Copy data:
 - ▶ Between registers
 - ▶ Between registers and memory (later)

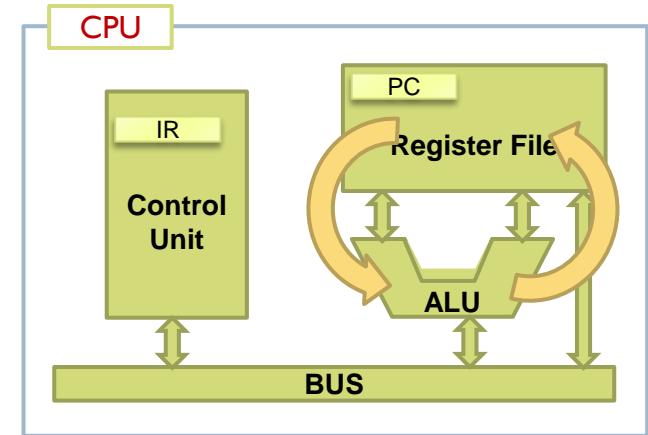
- ▶ Examples:
 - ▶ Copy from register to register
`mv a0 t0`
 - ▶ Immediate load
`li t0 5`



<code>mv</code>	<code>a0</code>	<code>t0</code>	#	<code>a0</code>	\leftarrow	<code>t0</code>
<code>li</code>	<code>t0</code>	<code>5</code>	#	<code>t0</code>	\leftarrow	<code>000...00101</code>

Arithmetic instructions (integer registers)

- ▶ Performs the arithmetic integer operations in two complement.
- ▶ Examples (ALU):
 - ▶ Addition
 - `add t0 t1 t2` # $t0 \leftarrow t1 + t2$
 - `addi t0 t1 5` # $t0 \leftarrow t1 + 5$
 - ▶ Subtraction
 - `sub t0 t1 t2` # $t0 \leftarrow t1 - t2$
 - ▶ Multiplication
 - `mul t0 t1 t2` # $t0 \leftarrow t1 * t2$
 - ▶ Integer division ($5 / 2 = 2$)
 - `div t0 t1 t2` # $t0 \leftarrow t1 / t2$
 - ▶ Division remainder ($5 \% 2 = 1$)
 - `rem t0 t1 t2` # $t0 \leftarrow t1 \% t2$



Example

```
int a = 5;  
int b = 7;  
int c = 8;  
int i;
```

```
i = a * (b + c)
```

Example

```
int a = 5;  
int b = 7;  
int c = 8;  
int i;
```

```
i = a * (b + c)
```

```
li t1 5  
li t2 7  
li t3 8
```

```
add t4 t2 t3  
mul t4 t4 t1
```

Exercise

```
int a = 5;  
int b = 7;  
int c = 8;  
int i;  
  
i = -(a * (b - 10) + c)
```

Exercise (solution)

```
int a = 5;  
int b = 7;  
int c = 8;  
int i;
```

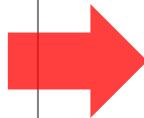
```
i = -(a * (b - 10) + c)
```

```
li t1 5  
li t2 7  
li t3 8
```

```
li t0 10  
sub t4 t2 t0  
mul t4 t4 t1  
add t4 t4 t3  
li t0 -1  
mul t4 t4 t0
```

Exercise

```
li t1 5  
li t2 7  
li t3 8  
  
li t0 10  
sub t4 t2 t0  
mul t4 t4 t1  
add t4 t4 t3  
li t0 -1  
mul t4 t4 t0
```



Can be performed by using
less instrucciones?

Exercise (solution)

```
li t1 5  
li t2 7  
li t3 8
```

```
li t0 10  
sub t4 t2 t0  
mul t4 t4 t1  
add t4 t4 t3  
li t0 -1  
mul t4 t4 t0
```

```
li t1 5  
li t2 7  
li t3 8
```

```
addi t4 t2 -10  
mul t4 t4 t1  
add t4 t4 t3  
add t4 x0 t4
```

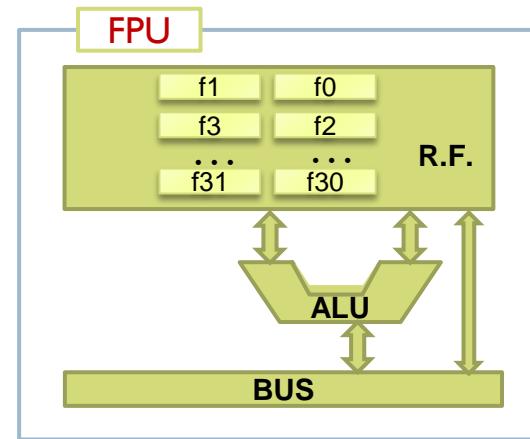
Register File (floating-point)

ABI Name	Name	Usage	
ft0...ft7	f0 ... f7	Temporals	(like t...)
fs0...fs1	f8 ... f9	There are saved	(like s...)
fa0...fa1	f10 ... f11	Arguments/return	(like a...)
fa2...fa7	f12 ... f17	Arguments	(like a...)
fs2...fs11	f18 ... f27	There are saved	(like s...)
ft8...ft11	f28 ... f31	Temporals	(like t...)

- ▶ There are 32 registers
- ▶ The ft0 register does not have its value set to 0.
- ▶ In the single precision extension, the registers are 32 bits (4 bytes).
- ▶ In the double precision extension, the registers are 64 bits (8 bytes) and can store:
 - ▶ Single precision values in the lower 32 bits of the register
 - ▶ Double precision values in the 64 bits of the register

Floating-point register file

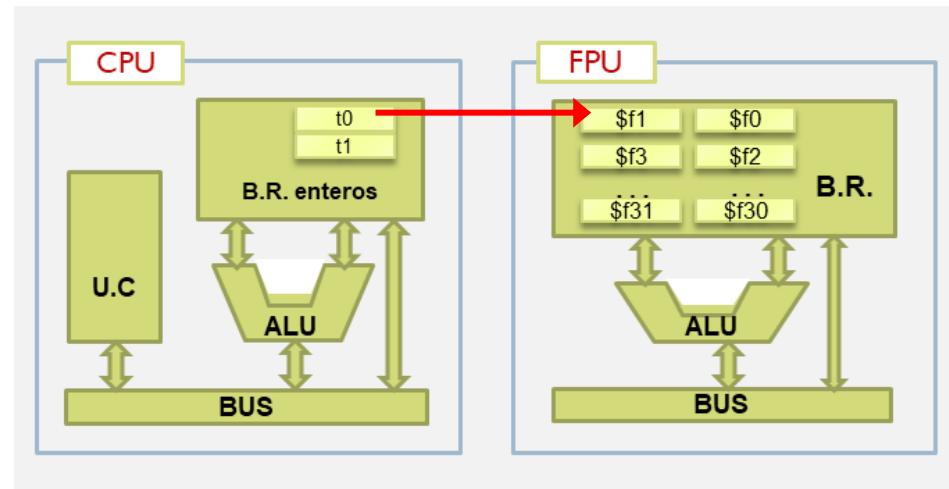
- ▶ There are 32 floating-point registers in addition to the integer registers:
 - ▶ From f0 to f31
- ▶ Copy registers (.s .d):
 - ▶ `fmv.s rd rs` # $rd = rs$
- ▶ Common arithmetic operations (.s .d):
 - ▶ `fadd.s rd rs1 rs2` # $rd = rs1 + rs2$
 - ▶ `fsub.s rd rs1 rs2` # $rd = rs1 - rs2$
 - ▶ `fmul.s rd rs1 rs2` # $rd = rs1 * rs2$
 - ▶ `fdiv.s rd rs1 rs2` # $rd = rs1 / rs2$
 - ▶ `fmin.s rd rs1 rs2` # $rd = \min(rs1, rs2)$
 - ▶ `fmax.s rd rs1 rs2` # $rd = \max(rs1, rs2)$
 - ▶ `fsqrt.s rd rs1` # $rd = \sqrt{rs1}$
 - ▶ `fmadd.s rd rs1 rs2 rs3` # $rd = rs1 \times rs2 + rs3$
 - ▶ `fmsub.s rd rs1 rs2 rs3` # $rd = rs1 \times rs2 - rs3$
 - ▶ `fabs.s rd rs` # $rd = |rs|$
 - ▶ `fneg.s rd rs` # $rd = -rs$



Copy instructions (integer registers<-> floating-point registers)

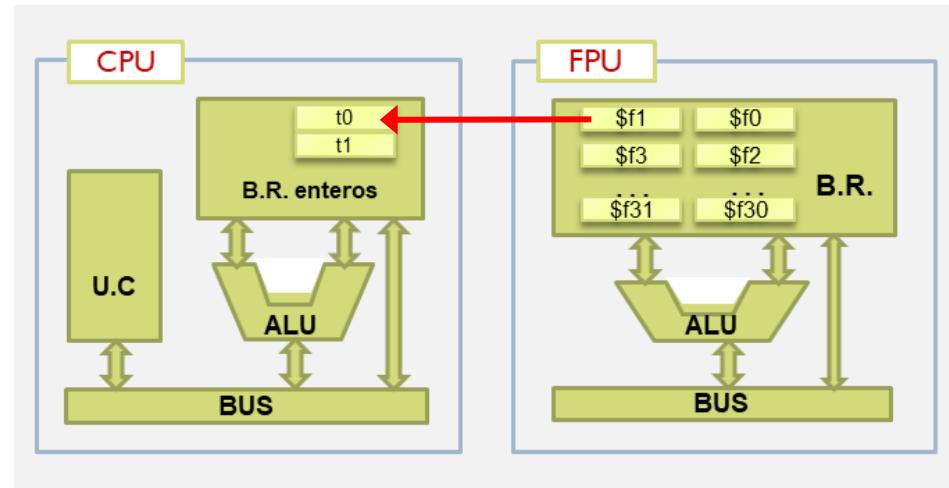
fmv.w.x rd rs

- ▶ Copy from integer register **rs** to a floating register **rd** (*single precisión*)



fmv.x.w rd rs

- ▶ Copy from floating register **rs** (*single precision*) to a integer register **rd**



Conversion operations (1 / 3)

integer <-> simple precision

- ▶ **fcvt.w.s rd, rs**
 - ▶ Convert from simple precision (value in floating register rs) to a 32-bit integer 32 **with** sign (integer register rd).
- ▶ **fcvt.wu.s rd, rs**
 - ▶ Convert from simple precision (value in floating register rs) to a 32-bit integer 32 **without** sign (integer register rd).
- ▶ **fcvt.s.w rd, rs**
 - ▶ Convert a 32-bit integer 32 **with** sign (value in integer register rs) to a simple precision (floating register rd).
- ▶ **fcvt.s.wu rd, rs**
 - ▶ Convert a 32-bit integer 32 **without** sign (value in integer register rs) to a simple precision (floating register rd).

Conversion operations (2 / 3)

integer <-> double precision

- ▶ **fcvt.w.d rd, rs**
 - ▶ Convert from double precision (value in floating register rs) to a 32-bit integer 32 **with** sign (integer register rd).
- ▶ **fcvt.wu.d rd, rs**
 - ▶ Convert from double precision (value in floating register rs) to a 32-bit integer 32 **without** sign (integer register rd).
- ▶ **fcvt.d.w rd, rs**
 - ▶ Convert a 32-bit integer 32 **with** sign (value in integer register rs) to a double precision (floating register rd).
- ▶ **fcvt.d.wu rd, rs1**
 - ▶ Convert a 32-bit integer 32 **without** sign (value in integer register rs) to a double precision (floating register rd).

Conversion operations (3/3)

double precision <-> simple precision

- ▶ **fcvt.s.d rd, rs1**

- ▶ Convert from double precision (value in floating register rs) to simple precision (floating register rd).

- ▶ **fcvt.d.s rd, rs**

- ▶ Convert from simple precision (value in floating register rs) to double precision (floating register rd).

Classification of floating-point numbers

- ▶ `fclass.s rd, rs1` (simple precision)
- ▶ `fclass.d rd, rs1` (doble precision)
- ▶ Save in `rd` the type of the floating-point number of the register `rs1`:

Value in rd	Meaning
0	-Inf
1	Negative normalized number
2	Negative non-normalized number
3	-0
4	+0
5	Positive non-normalized number
6	Positive normalized number
7	+Inf
8	NaN (non-quiet)
9	NaN (quiet)

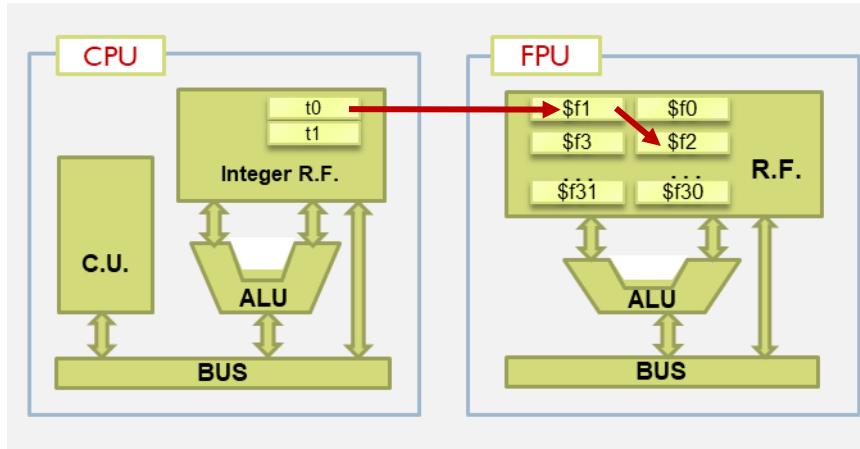
Example

```

float PI      = 3,1415;
int   radio = 4;
float length;

length = PI * radio;

```



```

.text
main:

    li t0, 0x40490E56
    # does not exist li.s
    # 0x40490E56 is the
    # representation IEEE754
    # in hexadecimal for 3.1415
    fmv.w.x  ft0, t0    # ft0 ← t0
    li        t1  4     # 4 in Ca2
    fcvt.s.w ft1, t1    # 4 in ieee754
    fmul.s   ft0, ft0, ft1

```

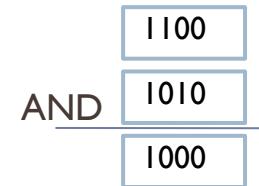
Logical instructions

- ▶ Boolean operations

- ▶ Examples:

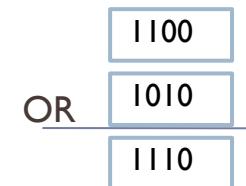
- ▶ AND

`and t0 tl t2` ($t0 = tl \& t2$)
`andi t0 tl t2` ($t0 = tl \& t2$)



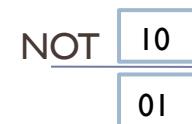
- ▶ OR

`or t0 tl t2` ($t0 = tl | t2$)
`ori t0 tl 80` ($t0 = tl | 80$)



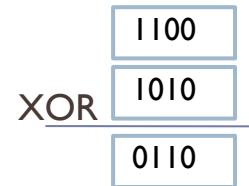
- ▶ NOT

`not t0 tl` ($t0 = ! tl$)
`xori t0 tl -1`



- ▶ XOR

`xor t0 tl t2` ($t0 = tl \wedge t2$)



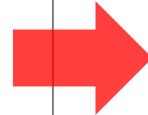
Exercise

```
li t0, 5
```

```
li t1, 8
```

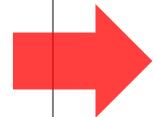
```
and t2, t1, t0
```

What will be the value of t2?



Exercise (solution)

```
.      li t0, 5  
      li t1, 8  
  
      and t2, t1, t0
```



00...0101	t0
00...1000	t1
<hr/>	
and 00...0000	t2

Exercise

```
li t0, 5  
li t1, 0x007FFFFF  
  
and t2, t1, t0
```

What does an "and" with
0x007FFFFF allow to do?

Exercise (solution)

```
li t0, 5  
li t1, 0x007FFFFF  
  
and t2, t1, t0
```

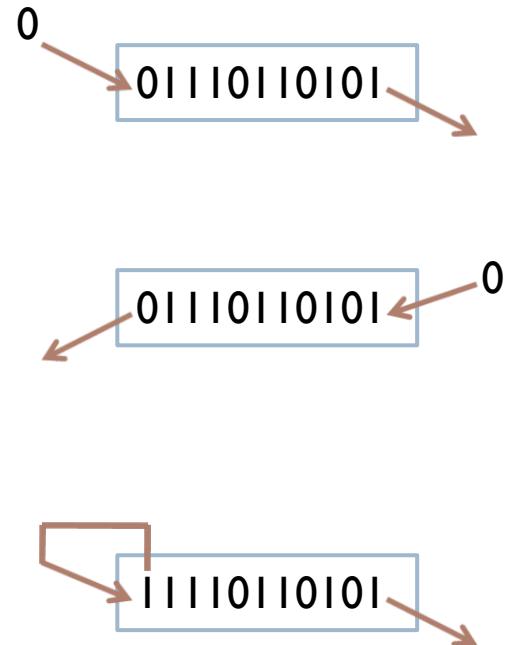
What does an "and" with 0x007FFFFF allow to do?

Obtain the 23 least significant bits

The constant used for bit selection is called a mask.

Shift instructions

- ▶ Bits movement
- ▶ Examples:
 - ▶ Shift right **logical**
`srl t0 t0 4` ($t0 = t0 \gg 4$ bits)
 - ▶ Shift left **logical**
`sll t0 t0 5` ($t0 = t0 \ll 5$ bits)
 - ▶ Shift right **arithmetic**
`sra t0 t0 2` ($t0 = t0 \gg 2$ bits)



Exercise (solution)

```
li t0, 5
```

```
li t1, 6
```

```
srai t0, t1, 1
```

```
slli t0, t1, 1
```



- What is the value of t0?

000 0110 t1

shift one bit to right (/2)

000 0011 t0

- What is the value of \$t0?

000 0110 t1

Shift one bit to left (x2)

000 1100 t0

Exercise

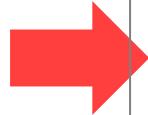
Make a program that
detects the sign of a
stored number t0 and
leaves in t1 a 1 if it
is negative and a 0 if
it is positive.



Exercise (solution)

CREATOR
WeSIM

Make a program that detects the sign of a stored number t0 and leaves in t1 a 1 if it is negative and a 0 if it is positive.



```
li    t0 -3  
srli t1 t0 31
```

Comparison instructions (integer registers)

- ▶ **slt** $rd, rs1, rs2$ if ($s(rs1) < s(rs2)$) $rd = 1$; else $rd = 0$
- ▶ **sltu** $rd, rs1, rs2$ if ($u(rs1) < u(rs2)$) $rd = 1$; else $rd = 0$
- ▶ **slti** $rd, rs1, 5$ if ($s(rs1) < s(5)$) $rd = 1$; else $rd = 0$
- ▶ **sltiu** $rd, rs1, 5$ if ($u(rs1) < u(5)$) $rd = 1$; else $rd = 0$
- ▶ **seqz** $rd, rs1$ if ($rs1 == 0$) $rd = 1$; else $rd = 0$
- ▶ **snez** $rd, rs1$ if ($rs1 != 0$) $rd = 1$; else $rd = 0$
- ▶ **sgtz** $rd, rs1$ if ($rs1 > 0$) $rd = 1$; else $rd = 0$
- ▶ **sltz** $rd, rs1$ if ($rs1 < 0$) $rd = 1$; else $rd = 0$

Comparison instructions (floating-point registers)

▶ Simple precision

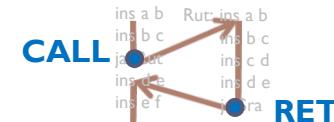
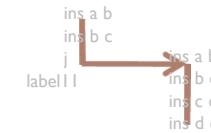
- ▶ **feq.s** rd, rs1, rs2 if ($rs1 == rs2$) rd= 1; else rd = 0
- ▶ **fle.s** rd, rs1, rs2 if ($rs1 <= rs2$) rd= 1; else rd = 0
- ▶ **flt.s** rd, rs1, rs2 if ($rs1 < rs2$) rd= 1; else rd = 0

▶ Doble precision:

- ▶ **feq.d** rd, rs1, rs2 if ($rs1 == rs2$) rd= 1; else rd = 0
- ▶ **fle.d** rd, rs1, rs2 if ($rs1 <= rs2$) rd= 1; else rd = 0
- ▶ **flt.d** rd, rs1, rs2 if ($rs1 < rs2$) rd= 1; else rd = 0

Control flow

- ▶ Change the sequence of instructions to be executed
- ▶ Several types:
 - ▶ Conditional branches:
 - ▶ Branch if value match condition
 - ▶ E.g.: `bne t0 t1 label1`
 - ▶ Unconditional branches:
 - ▶ Always branch
 - ▶ E.g.: `j etiqueta2`
 - ▶ Function calls:
 - ▶ Branch with return
 - ▶ E.g.: `jal ra subrutina1 jr ra`



Branch instructions

- ▶ Conditional (only with integer registers):

```
▶ beq    t0    t1    label1    # jump to label1 if t0 == t1
▶ bne    t0    t1    label1    # jump to label1 if t0 != t1
▶ blt    t0    t1    label1    # jump to label1 if t0 < t1
▶ bltu   t0    t1    label1    # jump to label1 if t0 < t1 (unsigned)
▶ bge    t0    t1    label1    # jump to label1 if t0 >= t1
▶ bgeu   t0    t1    label1    # jump to label1 if t0 >= t1 (unsigned)
(as pseudo-instructions)
▶ bgt    t0    t1    label1    # jump to label1 if t0 > t1
▶ ble    t0    t1    label1    # jump to label1 if t0 <= t1
```

Branch instructions

jump label

- ▶ Conditional (only with integer registers):

```
› beq    t0    t1    label1    # jump to label1 if t0 == t1
› bne    t0    t1    label1    # jump to label1 if t0 != t1
› blt    t0    t1    label1    # jump to label1 if t0 < t1
› bltu   t0    t1    label1    # jump to label1 if t0 < t1 (unsigned)
› bge    t0    t1    label1    # jump to label1 if t0 >= t1
› bgeu   t0    t1    label1    # jump to label1 if t0 >= t1 (unsigned)

› bgt    t0    t1    label1    # jump to label1 if t0 > t1
› ble    t0    t1    label1    # jump to label1 if t0 <= t1
```

- ▶ Unconditional:

› j **label1** # jump to **label1**. Equivalent to **beq x0 x0 label1**

label1 refers to an instruction (represents a memory address where the instruction is located) which is skipped:

```
add  t1, t2, t3
j    jump_addr
add  t2, t3, t4
li   t4, 1
jump_addr: li   t0, 4
```

Control flow

if

```
int a=1;  
int b=2;  
  
main ()  
{  
    if (a < b) {  
        a = b;  
    }  
    ...  
}
```

beq	t1 = t0
bne	t1 != t0
bge	t1 >= t0
ble	t0 <= t1
blt	t1 < t0
bgt	t0 > t1

Control flow

if

```
int a=1;  
int b=2;  
  
main ()  
{  
    if (a < b) {  
        a = b;  
    }  
    ...  
}
```

CREATOR

WeSIM

beq	t1 = t0
bne	t1 != t0
bge	t1 >= t0
ble	t0 <= t1
blt	t1 < t0
bgt	t0 > t1

```
li  t1 1  
li  t2 2  
  
if_1: blt t1 t2 then_1  
      j   fin_1  
  
then_1: mv t1 t2  
  
fin_1: ...
```

The diagram illustrates the control flow for the 'if' statement. It starts with the instruction 'if_1: blt t1 t2 then_1'. A red arrow points from this label to the 'then_1' label, which is highlighted in a green box. Another red arrow points from the 'then_1' label to the 'fin_1' label, also highlighted in a green box. The 'fin_1' label is followed by the instruction '...'. The labels 'if_1', 'then_1', and 'fin_1' are in blue, while the assembly instructions and other labels are in black.

Control flow

if

```
int a=1;  
int b=2;  
  
main ()  
{  
    if (a < b) {  
        a = b;  
    }  
    ...  
}
```

CREATOR

WeP SIM

beq	t1 = t0
bne	t1 != t0
bge	t1 >= t0
ble	t0 <= t1
blt	t1 < t0
bgt	t0 > t1

```
li t1 1  
li t2 2  
  
if_2: bge t1 t2 fin_2  
  
then_2: mv t1 t2  
  
fin_2: ...
```

Control flow if-else

```
int a=1;  
int b=2;  
  
main ()  
{  
    if (a < b){  
        // action 1  
    } else {  
        // action 2  
    }  
}
```

CREATOR

WepSIM

beq	t1 = t0
bne	t1 != t0
bge	t1 >= t0
ble	t0 <= t1
blt	t1 < t0
bgt	t0 > t1

```
li  t1 1  
li  t2 2  
  
if_3:  bge t1 t2 else_3  
  
then_3: # action 1  
        j  fi_3  
  
else_3: # action 2  
  
fi_3: ...
```

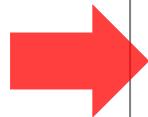
Exercise

```
int b1 = 4;  
int b2 = 2;  
  
if (b2 == 8) {  
    b1 = 1;  
}  
...
```



Exercise (solution)

```
int b1 = 4;  
int b2 = 2;  
  
if (b2 == 8) {  
    b1 = 1;  
}  
...
```



```
li    t0 4  
li    t1 2  
li    t2 8  
  
bne  t0 t2  fin1  
li    t1 1  
fin1: ...
```

Branches with floating-point numbers

Jump to `label` if
`ft1 < ft2`

```
flt t0, ft1, ft2
bne t0, x0, label
. . .
label:
```

Control flow

while

beq	t1 = t0
bne	t1 != t0
bge	t1 >= t0
ble	t0 <= t1
blt	t1 < t0
bgt	t0 > t1

```
int i;

main ()
{
    i=0;
    while (i < 10) {

        /* action */

        i = i + 1 ;
    }
}
```

Control flow

while

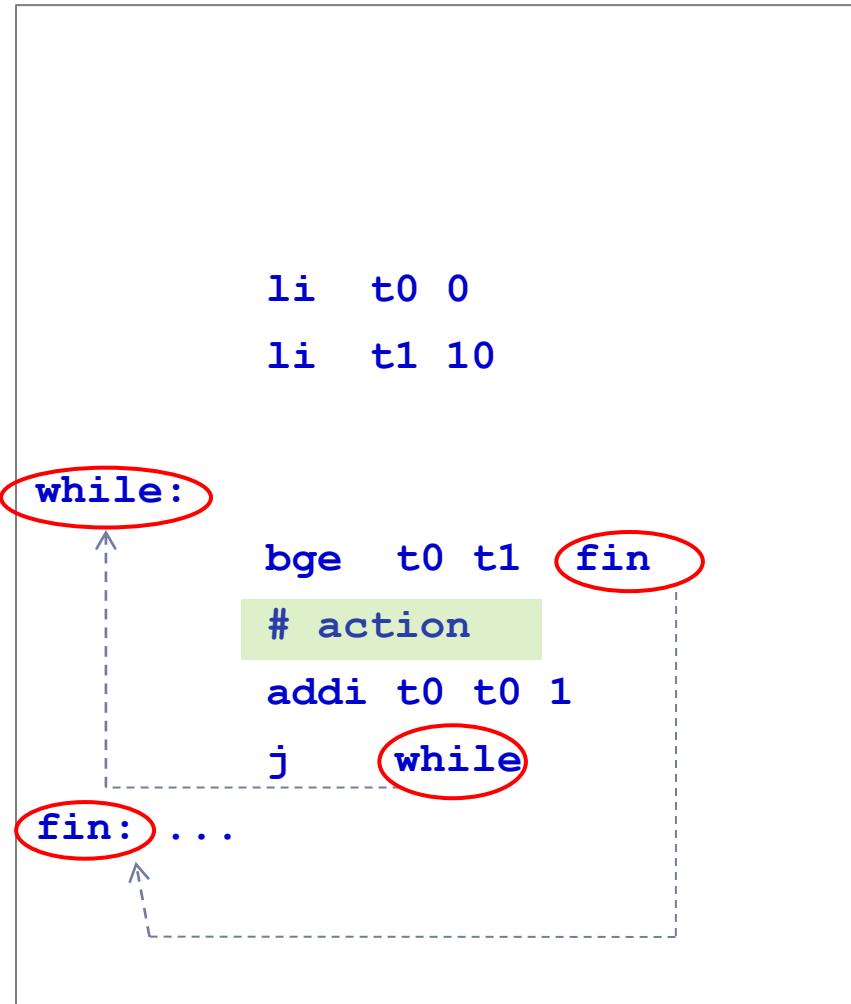
```
int i;

main ()
{
    i=0;
    while (i < 10) {
        /* action */
        i = i + 1 ;
    }
}
```

CREATOR

WepSIM

beq	t1 = t0
bne	t1 != t0
bge	t1 >= t0
ble	t0 <= t1
blt	t1 < t0
bgt	t0 > t1



Exercise

Make a program that
calculates the sum of
the first ten numbers
and leaves this value in
register a0



Exercise (solution)

Make a program that calculates the sum of the first ten numbers and leaves this value in register a0

$$1 + 2 + 3 + \dots + 10$$



No valid
;-)

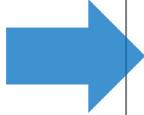
```
li  a0 0
add a0 a0 1
add a0 a0 2
add a0 a0 3
add a0 a0 4
add a0 a0 5
add a0 a0 6
add a0 a0 7
add a0 a0 8
add a0 a0 9
```

Exercise (solution)

Make a program that calculates the sum of the first ten numbers and leaves this value in register a0



```
int i, s;  
  
s=0;  
i=0;  
while (i <= 10)  
{  
    s = s + i ;  
    i = i + 1 ;  
}
```



Exercise (solution)

Make a program that calculates the sum of the first ten numbers and leaves this value in register a0



```
int i, s;  
  
s=0;  
i=0;  
while (i <= 10)  
{  
    s = s + i ;  
    i = i + 1 ;  
}
```



```
.  
  
        li t0 0  
        li a0 0  
        li t2 10  
while1:  
        bgt t0 t2 fin1  
        add a0 a0 t0  
        addi t0 t0 1  
        j while1  
  
fin1:
```

Exercise

- ▶ Calculate the number of 1's of a register (t0).
Result in t3.

Exercise (solution)

- ▶ Calculate the number of 1's of a register (t0).
Result in t3.

```
i = 0;
n = 45;  # number
s = 0;
while (i < 32)
{
    b = first bit of n
    s = s + b;
    shift the contents of
    of n one bit to the
    right
    i = i + 1 ;
}
```

Exercise (solution)

- ▶ Calculate the number of 1's of a register (t0).
Result in t3.

```
i = 0;  
n = 45; # number  
s = 0;  
while (i < 32)  
{  
    b = first bit of n  
    s = s + b;  
    shift the contents of  
    of n one bit to the  
    right  
    i = i + 1 ;  
}
```

```
i = 0;  
n = 45; # number  
s = 0;  
while (i < 32)  
{  
    b = n & 1;  
    s = s + b;  
    n = n >> 1;  
    i = i + 1 ;  
}
```

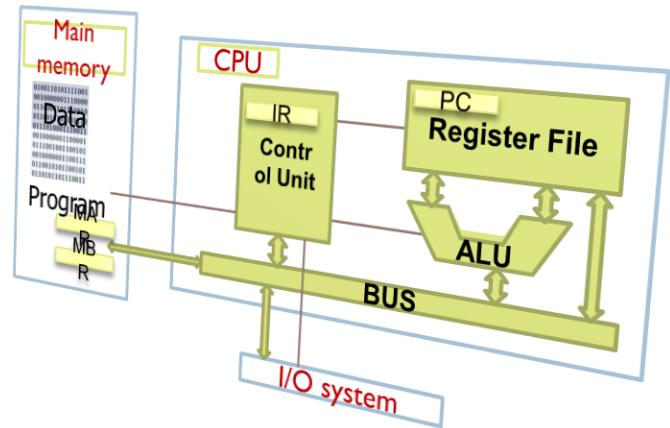
Exercise (solution)

- ▶ Calculate the number of 1's of a register (t0).
Result in t3.

```
i = 0;
n = 45;    # number
s = 0;
while (i < 32)
{
    b = n & 1;
    s = s + b;
    n = n >> 1;
    i = i + 1 ;
}
```

```
li    t0, 0      #i
li    t1, 45     #n
li    t2, 32
li    t3, 0      #s
while: bge  t0, t2, fin
        andi t4, t1, 1
        add  t3, t3, t4
        srlti t1, t1, 1
        addi t0, t0, 1
j      while
fin:   ...
```

Types of instructions summary



- ▶ Data transfer
- ▶ Arithmetic
- ▶ Logical
- ▶ Shifting and rotation
- ▶ Comparison
- ▶ Control flow (branches, ...)
- ▶ Conversion
- ▶ Input/output
- ▶ System calls

Typical faults

- 1) Poorly designed program
 - ▶ Does not do what is requested
 - ▶ Incorrectly does what is requested
- 2) Programming directly in assembler
 - ▶ Do not code in pseudo-code the algorithm to be implemented
- 3) Write unreadable code
 - ▶ Do not tabulate the code
 - ▶ Do not comment the assembly code or make reference to the algorithm initially proposed.

ARCOS Group

uc3m | Universidad **Carlos III** de Madrid

L3: Fundamentals of assembler programming Computer Structure

Bachelor in Computer Science and Engineering

Bachelor in Applied Mathematics and Computing

Dual Bachelor in Computer Science and Engineering and Business Administration

